# **High Power Electronic Load**

PEL-5000C Series

**USER MANUAL** 





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No. 7-1, Jhongsing Rd., Tucheng Dist., New Taipei City 236, Taiwan.



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# SAFETY INSTRUCTIONS

This chapter contains important safety instructions that you must follow during operation and storage. Read the following before any operation to insure your safety and to keep the instrument in the best possible condition.

## Safety Symbols

These safety symbols may appear in this manual or on the instrument.



WARNING Warning: Identifies conditions or practices that could result in injury or loss of life.



Caution: Identifies conditions or practices that could result in damage to the instrument or to other properties.



DANGER High Voltage



Attention Refer to the Manual



Earth (ground) Terminal



Frame or Chassis Terminal

Do not dispose electronic equipment as unsorted municipal waste. Please use a separate collection facility or contact the supplier from which this instrument was purchased.



## Safety Guidelines

## General Guideline



- Do not place any heavy object on the instrument. Note: Only 2 units can be stacked vertically.
- Avoid severe impact or rough handling that leads to damaging the instrument.
- Do not discharge static electricity to the instrument.
- Use only crimped wires, not bare wires, for the terminals.
- Do not block the cooling fan opening.
- Do not disassemble the instrument unless you are qualified.
- The equipment is not for measurements performed for CAT II, III and IV.

(Measurement categories) EN 61010-1:2010 specifies the measurement categories and their requirements as follows.

- Measurement category IV is for measurement performed at the source of low-voltage installation.
- Measurement category III is for measurement performed in the building installation.
- Measurement category II is for measurement performed on the circuits directly connected to the low voltage installation.
- 0 is for measurements performed on circuits not directly connected to Mains.
- Do NOT position the equipment so that it is difficult to disconnect the appliance inlet or the power plug.
- If the equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.



## Power Supply



- AC Input voltage range: 100-240VAC, Single phase
   90-250VAC
- Frequency: 47-63Hz
- To avoid electrical shock connect the protective grounding conductor of the AC power cord to an earth ground.
- To avoid electric shock, the power cord protective grounding conductor must be connected to ground. No operator serviceable components inside. Do not remove covers.
   Refer servicing to qualified personnel.

#### Cleaning

- Disconnect the power cord before cleaning.
- Use a soft cloth dampened in a solution of mild detergent and water. Do not spray any liquid.
- Do not use chemicals containing harsh material such as benzene, toluene, xylene, and acetone.

## Operation Environment

- Location: Indoor, no direct sunlight, dust free, almost non-conductive pollution (Note below)
- Temperature: 0°C to 40°C
- Humidity: 0 to 85% RH
- Altitude: <2000m
- · Overvoltage category II



(Pollution Degree) EN 61010-1:2010 specifies the pollution degrees and their requirements as follows. The instrument falls under degree 2.

Pollution refers to "addition of foreign matter, solid, liquid, or gaseous (ionized gases), that may produce a reduction of dielectric strength or surface resistivity".

- Pollution degree 1: No pollution or only dry, non-conductive pollution occurs. The pollution has no influence.
- Pollution degree 2: Normally only non-conductive pollution occurs. Occasionally, however, a temporary conductivity caused by condensation must be expected.
- Pollution degree 3: Conductive pollution occurs, or dry, nonconductive pollution occurs which becomes conductive due to condensation which is expected. In such conditions, equipment is normally protected against exposure to direct sunlight, precipitation, and full wind pressure, but neither temperature nor humidity is controlled.

## Storage environment

Location: Indoor

• Temperature: -20°C to 70°C

• Humidity: <90% RH

### Disposal



Do not dispose this instrument as unsorted municipal waste. Please use a separate collection facility or contact the supplier from which this instrument was purchased. Please make sure discarded electrical waste is properly recycled to reduce environmental impact.



# GETTING STARTED

The PEL-5000C series Electronic Load is designed to test, evaluation and burn-in of DC power supplies and batteries.

The PEL-5000C series high power electronic Load can be controlled locally at the front panel or remotely via computer over the GPIB/RS232/USB/LAN. Constant Current (CC) mode, Constant Resistance (CR) mode, and Constant Voltage (CV) mode. And Constant Power (CP) mode. The wide range dynamic load with independent rise and fall current slew rate and analog programming input with arbitrary wave-form input is available in Constant Current mode.



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## **GETTING STARTED**



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## PFI-5000C Series Introduction

#### Main Features

#### **Features**

- CC, CR, CV, CP, Dynamic, and Short Operating Mode.
- Remote control via a choice of computer interfaces.
- High accuracy & resolution with 16 bit voltage and current meter.
- Built in pulse generators for dynamic loading.
- Independently adjustable current rise and fall times.
- Short circuit test with current measurement
- Dedicated over current and overpower protection test functions
- Programmable voltage sense capability.
- Full protection from overpower, overtemperature, overvoltage, and reverse polarity.
- Analogue programming input for tracking an external signal
- Current Monitor with BNC (non-isolated) socket.
- Digital Calibration
- Advance Fan speed control
- Ability to save load setup via the mainframe memory (150 store/recall locations)
- Auto sequence function allowing test routines to be set from the mainframe



## Protection features

The protection features of the PEL-5000C series Electronic load modules are as follows:

Overvoltage protection	The Electronic Load will turn OFF Load OFF if the overvoltage circuit is tripped. The message OVP will be displayed on the LCD. When the OVP fault has been removed the load can be set to sink power again. While the unit will attempt to protect itself given an OVP state it is strongly advised to guard against any potential OVP fault state by using external protection and the correctly rated electronic load.
	The Overvoltage protection circuit is set at a predetermined voltage and cannot be adjusted. The OVP level is 105% of the PEL-5000C series nominal voltage rating.
Caution	Never apply an AC voltage to the input of the PEL-5000C series Load. Do not apply a DC voltage that is higher than PEL-5000C series Load rating. If this advice is ignored it is likely that damage will be caused to the electronic load module. This damage will not be covered by the warranty.
Over current protection (OCP)	The PEL-5000C series Electronic Load monitors the current level. The input to the load is automatically switched to LOAD OFF if the current is greater than 104% of the rated current input. If an over current condition occurs the display will show OCP.
Over power protection (OPP)	The PEL-5000C series Electronic Load monitors the power dissipation level. The input to the load is automatically switched to LOAD OFF if the power dissipation is greater than 105% of the rated power input. If an over power condition occurs the display will show OPP.



protection

Over temperature The load internal temperature at the heat sink is monitored. If the temperature reaches approximately 90°C the OTP message will be displayed and the unit will automatically switch to the LOAD OFF state. If an OTP error occurs please check the ambient temperature is between 0 to 40°C. Also ensure that the front and rear air vents of the mainframe are not obstructed. The air flow is taken from the front of the mainframe and exhausted from the rear. Therefore a suitable gap needs to be left at the rear of the mainframe. A minimum of 15cm is recommended. After a suitable cooling period the load can be switched.

#### Reverse Polarity

The PEL-5000C series load module will tolerate a reverse current up to the maximum current rating of the load module. The '-'symbol will be shown on the voltage and current displays.

#### Caution

If a reverse polarity situation occurs the load will sink power even if the LOAD button is OFF. No current will be displayed on the PEL-5000C series load module. Current up to the load's maximum current rating will be tolerated in reverse polarity. However there is no OVP OCP and OPP protection. It is strongly recommended that the load lines be fused if it is likely that the load could be subject to reverse polarity. These fuses should be fast acting and rated at the maximum current of the load module +5%.



## Accessories

Accessories		
Standard Accessories	Description	PCs
PEL-5000C series operation manual	It can be downloaded from GW Instek website.	
BANANA PLUGS		1
BNC – BNC CABLE		1
HD-DSUB 15PIN Parallel wire		1
Optional Accessories	Description	PCs
GPIB+RS232 interface	PEL-030	1
RS232 interface	PEL-023	1
GPIB interface	PEL-022	1
USB interface + USB driver (The driver can be downloaded from GW Instek website)	PEL-025	
LAN interface + LAN driver (The driver can be downloaded from GW Instek website)	PEL-024	
GPIB cable	GTL-250 GPIB Cable, 0.6m	1
GPIB cable	GTL-248 GPIB Cable, 2m	1
USB cable	GTL-246 USB Cable, 1.2m	1
PEL-5000C, AEL-5006, AEL-5008, AEL-5012 and AEL-5015 handle	PEL-028	1
PEL-5000C Hook Ring	PEL-026	
Rack Mount Kit For PEL-5006C	PEL-027-1	
Rack Mount Kit For PEL-5008C, PEL-5010C, PEL-5012C	PEL-027-2	
Rack Mount Kit For PEL-5015C, PEL-5018C	PEL-027-3	
Rack Mount Kit For PEL-5020C, PEL-5024C	PEL-027-4	

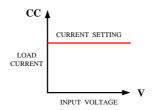


## Operating Mode Description

## CC Mode

### Background

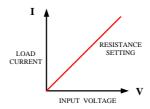
With the operating mode of Constant Current, the PEL-5000C Series electronic load will sink a current in accordance with the programmed value regardless of the input voltage



## CR mode

## Background

At Constant Resistance mode, the PEL-5000C series electronic load will sink a current linearly proportional to the load input voltage in accordance with the programmed resistance setting



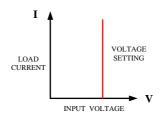
#### CV mode

## Background

At Constant Voltage mode, the PEL-5000C series electronic load will attempt to sink enough current



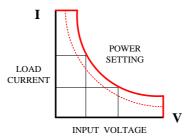
until the load input voltage reaches the programmed value



## CP mode

## Background

At Constant Power mode, the PEL-5000C series electronic load will attempt to sink load power (load voltage \* load current) in accordance with the programmed power.



#### Slew Rate

## Background

Slew rate is defined as the change in current or voltage over time. A programmable slew rate allows for a controlled transition from one load setting to another. It can be used to minimize induced voltage drops on inductive power wiring, or to control induced transients on a test device (such as would occur during power supply transient response testing).

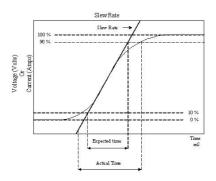
In cases where the transition from one setting to



another is large, the actual transition time can be calculated by dividing the voltage or current transition by the slew rate. The actual transition time is defined as the time required for the input to change from 10% to 90% or from 90% to 10% of the programmed excursion.

In cases where the transition from one setting to another is small, the small signal bandwidth (of the load) limits the minimum transition time for all programmable slew rates. Because of this limitation, the actual transition time is longer than the expected time based on the slew rate.

## Rise Time Transition Limitation



Therefore, both minimum transition time and slew rate must be considered when determining the actual transition time. Following detail description is excluding in specification sheet.

The minimum transition time for a given slew rate as about a 30% or greater load change, the slew rate increases from the minimum transition time to the Maximum transition time at a 100% load change. The actual transition time will be either the minimum transition time, or the total slew time (transition divided by slew rate), whichever is longer.

## Example

PEL-5012C-600-840 600V/840A/12000W (CCH - CCL >840Ax 30%)



Use the following formula to calculate the minimum transition time for a given slew rate min transition time=252A/slew rate (in amps/second).

 $10.5 \text{uS} (252 \text{A}/24) \times 0.8 (10\% \sim 90\%) = 8.4 \text{uS}$ 

Use the following formula to calculate the maximum transition time for a given slew rate max transition time=840/slew rate (in amps/second).

 $35uS (840A/24) \times 0.8(10\sim90\%) = 28uS$ 

EX. CCH=168A, CCL=0A Slew Rate =24A, the expected time is 5.6uS but the actual Transition

Time Will be limited to 4.8Us.

 $7uS (168/24 \times 0.8(10\% \sim 90\%) = 5.6uS$ 

Note

When CC mode rang1 slew rate, CCL setting at least 0.1% larger than the specification.

## Dynamic Waveform Definition

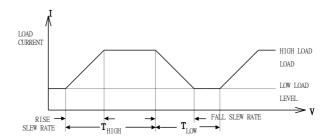
## Background

Along with static operation the PEL-5000C series electronic load are built with a dynamic mode for operation in Constant Current (CC), Constant Resistance (CR) or Constant Power (CP). This allows the test engineer to simulate real world pulsing loads or implement a load profile that varies with time.

A dynamic waveform can be programmed from the front panel of the PEL-5000C electronic load. The user would first set a High and low value of load current using the Level button. The Dynamic Setting then allows for the rise and fall time between these 2 current values to be adjusted. The time period that the waveform is high (Thigh) along with the time period that the waveform is low (Tlow) can also be set.



Dynamic Wave form



The dynamic waveform can also be set up via the optional computer interface. Dynamic waveform settings made from the front panel of the load module can also be saved in the memory of the PEL-5000C series Electronic Load. For the store/recall procedure and the computer command set please refer to the relevant operating manual for the PEL-5000C series Electronic Load.

Further dynamic waveform definitions are:

- The period of dynamic waveform is Thigh + Tlow
- The dynamic frequency = 1 / (Thigh + Tlow)
- The duty cycle = Thigh / (Thigh + Tlow)

Example 1

PEL-5000C series, Dynamic up to 50 KHz frequency

Dynamic highest frequency 50 KHz = 0.02ms=20us

Setting THIGH=10 uS, TLOW=10uS, THIGH+TLOW=20uS

CCH-CCL/SR≤10uS

Setting CCH=30A, CCL=10A

 $(30-10)/2.5A/uS \le 10 uS$ 

8 uS≤10 uS ,Compliance with frequency 50KHz

Example 2

Setting THIGH=10 uS, TLOW=10uS, THIGH+TLOW=20uS

CCH-CCL/SR≤10uS



Setting CCH=50A, CCL=0A

(50-0)/2.5A/uS=20uS, 20uS>10uS, It's not compliance the frequency 50 KHz

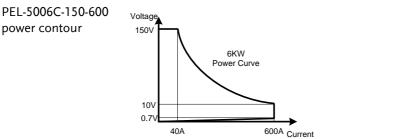
The analogue programming input also provides a convenient method of implementing a dynamic waveform.

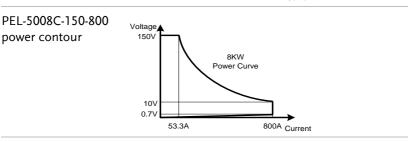


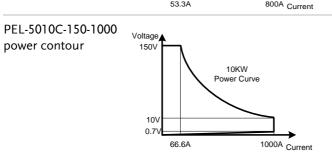
## Operating Area

The PEL-5000C series electronic load can be operated for manual and GPIB operation.

The PEL-5000C series high power electronic Load can be controlled locally at the front panel or remotely via computer over the GPIB/RS232/USB/LAN. Constant current (CC) mode, constant resistance (CR) mode, and constant voltage (CV) mode and constant power (CP) mode. The wide range dynamic load with independent rise and fall current slew rate and analog programming input with arbitrary wave-form input is available in Constant Current mode.

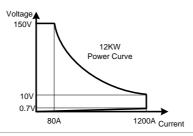




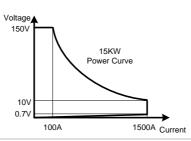




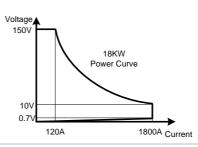
PEL-5012C-150-1200 power contour



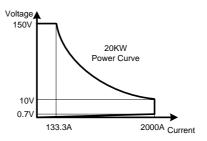
PEL-5015C-150-1500 power contour



PEL-5018C-150-1800 power contour

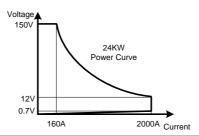


PEL-5020C-150-2000 power contour

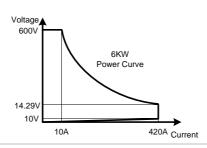




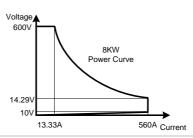
PEL-5024C-150-2000 power contour



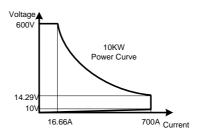
PEL-5006C-600-420 power contour



PEL-5008C-600-560 power contour

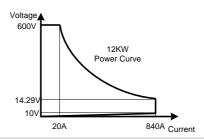


PEL-5010C-600-700 power contour

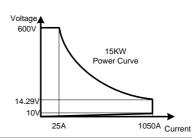




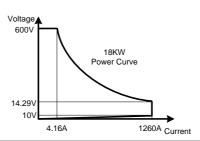
PEL-5012C-600-840 power contour



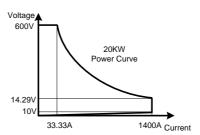
PEL-5015C-600-1050 power contour



PEL-5018C-600-1260 power contour

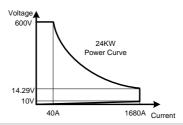


PEL-5020C-600-1400 power contour

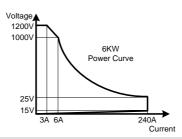




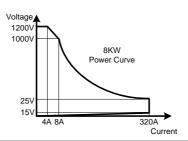
PEL-5024C-600-1680 power contour



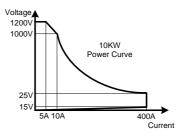
PEL-5006C-1200-240 power contour



PEL-5008C-1200-320 power contour

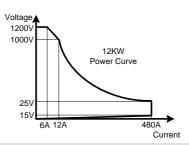


PEL-5010C-1200-400 power contour

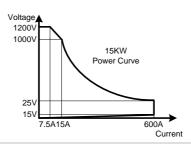




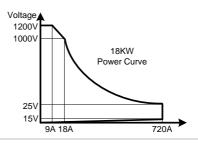
PEL-5012C-1200-480 power contour



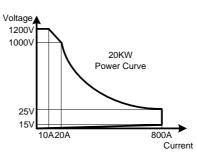
PEL-5015C-1200-600 power contour



PEL-5018C-1200-720 power contour

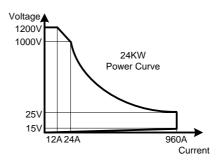


PEL-5020C-1200-800 power contour





PEL-5024C-1200-960 power contour



## **Appearance**

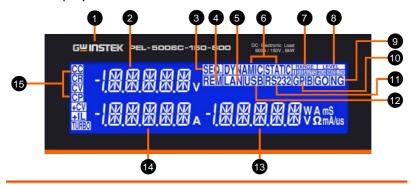
## Front Panel



- 1 Power switch
- 2 LCD Multi-function display
- 3 System keys
- 4 Function keys
- 5 Test function keys
- 6 Number keypad
- 7 Knob setting



## LCD Display



 Model number and sink ranges The model number along with maximum voltage, current and power values are detailed in this position at the top of the load front panel.

2 Left 5 digit LCD display

The 5 digit LCD display is a multi-function display. The function of the display changes depending whether the user is in NORMAL mode or in a SHORT, OPP or OCP modes:

Status display:

When enter System Setting or AUTO SEQUENCE, the display setting item.

Normal mode

The left 5 digit display displays the voltage present at the load's input terminals. The value displayed will include the automatic voltage compensation if the sense terminals are also connected to the device under test (DUT).

Note

If V-sense is set to "AUTO" and the sense leads are connected to the DUT the losses need to be approx. 700mV (PEL-5006C-150-600) before the display compensates for the voltage loss.

If V-sense is set to "ON" and the sense terminals are connected to the DUT the load will check and compensate for all voltage drops.



#### Test mode

If the SHORT, OPP or OCP buttons are pressed the left display will show a text Message that correlates with the selected test function.

- SHORT test selected: left display will show "Short".
- OPP test selected: left display will show "OPP"
- OCP test selected: left display will show "OCP".

During the test the left display will show the load Input voltage.

3 SEQ. indicator

When entering AUTO SEQUENCE mode, LCD indicator will light up.

4 REM LCD Indicator

If the REMOTE LCD Indicator is illuminated this means that the unit is operating remotely via one of the optional interfaces. While REMOTE is lit it is not possible to make settings manually at the front panel. The LOCAL button on the mainframe can be used to revert back to front panel control. When the unit is operating from the front panel the REMOTE LCD will not be illuminated.

5 LAN mode Lit

It is LAN interface inside.

6 DYN/STA LED Indicator The DYN button allows the user to switch between DYNAMIC operation and STATIC operation. Dynamic operation is only possible in constant current (CC) or Constant power (CP) mode only. The LED next to the DYN button will become lit When DYNAMIC operation is selected. If you are in constant resistance (CR) or Constant voltage (CV) mode pressing the DYN button will have no effect.

7 Rang LED Indicator The PEL-5000C series Load Module features 2 setting ranges for CC, CR, CV & CP operation. This allows improved resolution for setting



		low values. When left in the default AUTO mode the changeover between ranges is automatic depending on the setting value entered.  If desired the RANGE button can be pressed to force the unit to operate only in ANGE II. This is signaled by the accompanying LED becoming lit.
	Note	That it is only possible to force RANGE II in CC mode.
8	Level LED Indicator	The LEVEL button is used to program a High or Low load value. The setting value changes between current, resistance, voltage or power depending whether CC, CR, CV or CP mode has been selected. If the LED is lit then the High level value setting has been enabled. If the LED is not lit then the low load level can be set using the rotary switch in combination with the arrow keys.
		In STATIC mode the user can switch between High and low load levels during operation.
		In DYNAMIC operation (CC & CP modes only) the preset high and low levels are used to define the dynamic waveform.
	Note	The low level setting cannot exceed the high level. The converse is also true in that the High level cannot be set below the low level.
9	NG LCD Indicator	The user can adjust upper and lower limits for voltage, current and power within the CONFIG menu and turn the NG Indicator ON. If a voltmeter, ammeter or wattmeter measurement is outside these set limits then the NG indicator will illuminate.
10	GPIB mode Lit	It is GPIB inside. The LCD will be lit GPIB when Power ON. If PEL-5000C series is controlled by GPIB through PC, the GPIB will



		be lit.
11	RS232 mode Lit	It is RS232 inside. The LCD will be lit RS232 when Power ON. If PEL-5000C series is controlled by RS232 through PC, the RS232 will be lit.
12	USB mode Lit	It is USB interface inside.
13	The right 5 digit displays	The right 5 digit displays also changes function depending if the unit is in normal mode or one of the setting menus has been activated.
		Setting display: Display System Setting state or AUTO SEQUENCE setting value.
	Normal mode	In normal mode the right 5 digit displays shows the power consumption in Watts (W).
	Setting mode	The right display together with the rotary adjustment knob is used to set values.
		The value changes according to the setting function that is active. The middle LCD provides a text message to tell the user which part of the setting menu is active.
14	Middle 5 digit LCD display	The middle 5 digit displays also changes function depending if the user is in normal mode or has entered a setting menu Status display:  When enter System Setting or AUTO SEQUENCE, the display setting item.
	Normal mode	In normal mode the middle LCD display functions as a 5 digit ammeter. The 5 digit DAM shows the load current flowing into the DC load when the Load is ON.
	Setting mode	If CONFIG, LIMIT, DYN, SHORT, OPP or OCP buttons are pressed the middle LCD show a text message according to the setting function it is in. Each subsequent press of the



button moves the display to the next available function.

The sequence of each setting menu is detailed below

#### CONFIG:

Sequence is "SENSE" → "LDon" → "LDoff" →"POLAR" → "MPPT" → "CPRSP" → "AVG"

• LIMIT:

Sequence is "Add.CV"  $\rightarrow$  "V\_Hi"  $\rightarrow$ "V\_Lo"  $\rightarrow$  "I\_Hi"  $\rightarrow$  "I\_Lo"  $\rightarrow$  "W\_Hi"  $\rightarrow$ "W Lo"  $\rightarrow$  "NG"

 DYN setting: Sequence is "T-Hi" → "T-Lo" → "RISE" → "FALL"

SHORT:
 Sequence is "PRESS" → "TIME" → "V\_Hi"
 → "V Lo"

OPP:
 Sequence is "PSTAR" → "PSTEP" →
 "PSTOP" → "Vth"

 OCP: Sequence is "ISTAR" → "ISTEP" → "ISTOP" "Vth"

## PRESET mode

The value of the setting entered on the right display changes depending on the operating MODE that has been selected

- If CC mode is selected the right display provides setting in amps "A".
- If CR mode is selected the right display provides setting in ohms " $\Omega$ "
- If CP mode is selected the right display provides setting in watts "W".
- If CV mode is selected the right display provides setting in volts "V".

LIMIT

Each press of the LIMIT button changes the

middle LCD text. The sequence and the corresponding setting value shown on the bottom display is as follows:

Set CC + CV or CP + CV upper limit voltage, the middle of the display show "Add.CV", right display set value, the unit is V.

- V\_Hi (left limit voltage) displays the set value in volts "V"
- V\_Lo (right limit voltage) displays the set value in volts "V"
- I\_Hi (left limit current) displays the set value in amps "A"
- I\_Lo (right limit current) displays the set value in amps "A"
- W\_Hi (left limit power) displays the set value in watts "W"
- W\_Lo (right limit power) displays the set value in watts "W"
- NG displays whether the NG flag is set to "ON" or "OFF".

#### DYN Setting

Each press of the DYN setting button changes the text on the middle LCD. The sequence and the corresponding setting value shown on the bottom display are as follows:

- T-Hi (time high) displays the set value in milliseconds "ms"
- T-Lo (time low) displays the set value in milliseconds "ms"
- Rise (current rise time/slew rate) displays the set value in "A/us" or "A/ms"

Fall (current fall time/slew rate) displays the set value in "A/us" or "A/ms"

#### CONFIG

Each press of the CONFIG button changes the right upper LCD Text.

The sequence and the corresponding setting



value shown on the bottom displays are as follows:

- SENSE can be set to "AUTO" or "ON"
- LDon (load ON voltage) displays the set value in volts "V"
- LDoff (load OFF voltage) displays the set value in volts "V"
- POLAR (load polarity) can be set to "+LOAD" or "-LOAD"
- MPPT (Maximum power point tracking)
- BATT1 (Battery Discharge)
- BATT2 (Battery Discharge)
- BATT3 (Battery Discharge)
- CPRSP (CP RESPONSE)
- AVG

#### SHORT test

This allows the parameters of the short test to be set up.

Each press of the SHORT button moves the setting function. The sequence of the short test along with the setting value is as follows:

- Short Press Start (pressing the START/STOP button starts the test).
- TIME shows the duration of the SHORT test. "CONTI", on the bottom display indicates continuous. Time can be adjusted in "ms".
- V-Hi (voltage high threshold) displays the set value in volts "V"
- V-Lo (voltage low threshold) displays the set value in volts "V"

When the test is started the right display will show RUN. When the test has finished the right display will show END.

**OPP** test

This allows the parameters of the over power protection test to be set up. Each press of the

OPP button moves the setting function. The sequence of the OPP test along with the setting value is as follows:

- OPP Press Start (pressing the red START/STOP button starts the test)
- PSTAR (power start point) right display provides setting in watts "W"
- PSTEP (power steps) right display provides setting in watts "W"
- PSTOP (power stop point) right display provides setting in watts "W"
- VTH (voltage threshold) right display provides setting in volts "V"

When the test is started the right display will show the power value being taken by the load. If the Device Under Test is able to supply the load according to the values set then the right display will show PASS and the right display will show the maximum power taken during the OPP test. If during the test, OTP is displayed the over temperature protection has been engaged. Similarly if OPP is shown on the display the over power protection has been activated.

#### OCP test

This allows the parameters of the over current protection test to be set up. Each press of the OCP button moves the setting function.

The sequence of the OCP test along with the setting value is as follows:

- OCP Press Start (pressing the red START/STOP button starts the test)
- ISTAR (current start point) right display provides setting in amps "A"
- ISTEP (current steps) right display provides setting in amps "A"
- ISTOP (current stop point) right display



provides setting in amps "A"

• VTH (voltage threshold) right display provides setting in volts "V"

When the test is started the right display will show the current value being taken by the load. If the Device under Test is able to supply the load according to the values set then the middle display will show PASS and the right display will show the maximum current taken during the OCP test. If during the test, OTP is displayed the over temperature protection has been engaged. Similarly if OPP is shown on the display the over power protection has been activated.

## 10 Mode and Indicators

There are four operating modes that can be selected by pressing the "MODE" key on the PEL-5000C series Electronic Load module. The sequence is Constant Current (CC), Constant Resistance (CR), Constant Voltage (CV), and Constant Power (CP). Each time the "MODE" key is pressed the operating mode is changed. The actual operating mode selected is indicated on the left hand side of the LCD.

#### **OPP** test

This allows the parameters of the over power protection test to be set up. Each press of the OPP button moves the setting function. The sequence of the OPP test along with the setting value is as follows:

- OPP Press Start (pressing the red START/STOP button starts the test)
- PSTAR (power start point) right display provides setting in watts "W"
- PSTEP (power steps) right display provides setting in watts "W"
- PSTOP (power stop point) right display provides setting in watts "W"
- VTH (voltage threshold) right display



provides setting in volts "V"

When the test is started the right display will show the power value being taken by the load. If the Device Under Test is able to supply the load according to the values set then the right display will show PASS and the right display will show the maximum power taken during the OPP test. If during the test, OTP is displayed the over temperature protection has been engaged. Similarly if OPP is shown on the display the over power protection has been activated.



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## Function keys description



Mode and CC, CR, CP, CV Indicator



There are four operating modes. These can be selected in turn by pressing the "MODE" key on the PEL-5000C series Electronic Load module. The sequence is:

- (CC) Constant Current
- (CR) Constant Resistance
- (CP) Constant Power
- (CV) Constant Voltage

The appropriate LCD will illuminate according to the operating mode is selected.

Load key and LED indicators



The input to the PEL-5000C Series electronic load can be switched ON/OFF by using the "LOAD" button. Indication of the ON/OFF state is provided by illumination of the button.

LOAD button lit = LOAD ON (load sinks according to the preset values)

LOAD button unlit = LOAD OFF (the load does not sink current)

Turning the LOAD OFF does not affect the preset values. When the LOAD ON state is enabled the unit will revert to sinking according to the preset values.

When the Load ON/OFF key is operated



the current taken by load will follow the RISE or FALL with time according to the preset rate. The current RISE and FALL times can be adjusted in the DYN Setting button of the front panel.

In addition to the LOAD ON/OFF function the user can also adjust the voltage level at which the unit will automatically start or stop sinking energy. The adjustable LDon and LDoff voltage levels are found within the CONFIG menu.

Please note that the LDoff level cannot be set higher than the LDon level.

Preset key and LED indicators



If the PRESET key is pressed the button will become lit indicating that the PRESET mode has been accessed. The lowest 5 digit display will change from showing the power consumption in watts to displaying the value to be preset. The value that can be programmed changes according to the operating mode that has been selected.

- Constant Current (CC) mode:
   The A and B levels of load current can be preset at right lower 5 digit LCD.
   The "A" LED will be lit indicating the setting value is amps.
- Constant Resistance (CR) mode: The A and B levels of load resistance can be preset on the right lower 5 digit LCD. The " $\Omega$ " LED will be lit indicating the setting value is ohms.
- Constant Voltage (CV) mode:
   The A and B levels of load voltage can be preset on the right lower 5 digit LCD. The "V" LED will be lit indicating the setting value is volts.
- Constant Power (CP) mode:

The A and B levels of load power can be preset on the right lower 5 digit LCD. The "W" LED will be lit indicating the setting value is watts.

• Dynamic mode (CC, CR or CP modes only):

#### Preset key



Each press of the DYN button cycles through the dynamic load settings. The DYN settings are used in conjunction with the High and Low levels of load current to define the dynamic waveform. Each press of the DYN button switches from T\_Hi (time high), to T\_Lo (time low), to Rise time and then to fall time. The middle LCD shows the section of the dynamic waveform which is programmed with the rotary knob and read from the right display. The "ms" LED shows that the settings are programmed in milliseconds.

#### Range key



The PEL-5000C series Load Module features 2 setting ranges for CC, CR, CV & CP operation. This allows improved resolution for setting low values. When left in the default AUTO mode the changeover between ranges is automatic depending on the setting value entered.

If desired the RANGE button can be pressed to force the unit to operate only in RANGE II. This is signaled by the accompanying LED becoming lit.

#### Note

It is only possible to force RANGE II in CC mode.



Level key

Level

The LEVEL button is used to program a High or Low load value. The setting value changes between current, resistance, voltage or power depending whether CC, CR, CV or CP mode has been selected. If the LED is lit then the High level value setting has been enabled. If the LED is not lit then the low load level can be set using the rotary switch in combination with the arrow keys.

In STATIC mode the user can switch between High and low load levels during operation.

In DYNAMIC operation (CC & CP modes only) the preset high and low levels are used to define the dynamic waveform.

Note

The low level setting cannot exceed the high level. The converse is also true in that the High level cannot be set below the low level.

Limit key

Limit

The LIMIT button allows the user to set left and right thresholds for voltage, current or power. These threshold settings are used in conjunction with the NG function to flag when the load is operating outside the desired limit.

Each press of the LIMIT key enables a different value to be entered. On first press of the LIMIT key the button will illuminate Add.CV will be displayed on the middle LCD. The setting is made with the rotary knob and can be read from the right LCD during setting.

The setting sequence is shown below:

- Add.CV (CC+CV or CP+CV upper limit)
- V\_Hi (DVM upper limit)



- V\_Lo (DVM lower limit)
- I\_Hi (DAM upper limit)
- I\_Lo (DAM lower limit)
- W\_Hi (DWM upper limit)
- W\_Lo (DWM lower limit)
- NG OFF/ON (No Good Flag)
- LIMIT setting function OFF

The engineering unit is "V", "A" or "W" depending on the threshold LIMIT being set.

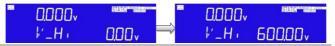


Setting CC+CV or CP+CV upper limit voltage, Middle 5 digit LCD display "Add.CV", right 5 digit LCD display the unit is "V", The Add.CV set range from 0.00 V to 600.00V step 0.01V by rotating the Setting knob.





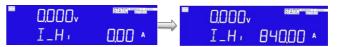
Setting upper limit voltage VH, Middle 5 digit LCD display "V-Hi", right 5 digit LCD display the unit is "V", The V-Hi set range from 0.00 V to 600.00V step 0.01V by rotating the Setting knob.



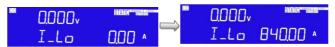
Setting lower limit voltage VL, the right upper 5 digit monitor display "V-Lo" and right lower monitor display lower limit of the voltmeter with the unit as "V", The V-Lo set range from 0.00 V to 600.00V step 0.01V by rotating the Setting knob.



Setting upper limit current IH, the right upper 5 digit monitor display "I-Hi" and right lower monitor display upper limit of the voltmeter with the unit as "A", the I-Hi set range from 0.000 A to 840.00A step 0.0001A by rotating the Setting knob.



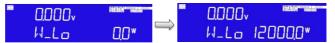
Setting lower limit current IL , the right upper 5 digit monitor display "I-Lo" and right lower monitor display lower limit of the voltmeter with the unit as "A", the I-Lo set range from 0.000 A to 840.00A step 0.01A by rotating the Setting knob.



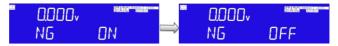
Setting upper limit power WH, the right upper 5 digit monitor display "W-Hi" and right lower monitor display upper limit of the voltmeter with the unit as "W", the W-Hi set range from 0 W to 12000W step 1W by rotating the Setting knob.



Setting lower limit power WL, the right upper 5 digit monitor display "W-Lo" and right lower monitor display lower limit of the voltmeter with the unit as "W", the W-Lo set range from 0 W to 12000W step 1W by rotating the Setting knob.

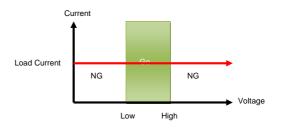


Setting NG ON/OFF, When exceed VH, VL, IH, IL, WH, WL One of these whether NG on LCD display.



Limit

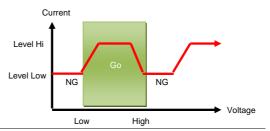
CC mode, press limits key to set the V-Hi and V-Lo voltage upper and lower limits of the GO / NG.



Limit

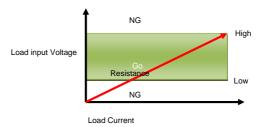
CC Dynamic Mode, press key to set the Level Hi and Level Low voltage upper and lower limits of the GO / NG.





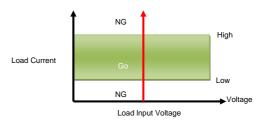
Limit

CR mode, press limits key to set the V-Hi and V-Lo voltage upper and lower limits of the GO / NG.



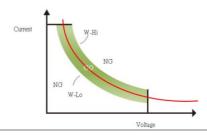
Limit

CV mode, press limits key to set the I-Hi and I-Lo Current upper and lower limits of the GO / NG.



Limit

CP mode, press limits key to set the W-Hi and W-Lo power upper and lower limits of the GO / NG.



DYN setting key



The DYN button allows the user to define the timings of the dynamic load Waveform. Firstly the high and low levels of load current will need to be set via the LEVEL switch. The RISE and FALL times between the low load current and the high load current along with the TIME the waveform is HIGH and the TIME LOW can is set via the DYN menu.

Each press of the DYN key enables a section of the DYNAMIC waveform to be set.

On first press of the DYN key the button will illuminate and T-Hi will be displayed on the middle LCD. The value is adjusted with the rotary knob and can be read from the right LCD during setting.

The setting sequence is shown below:

- T\_Hi (time the waveform is high)
- T\_Lo (time the waveform is low)
- RISE (rise time)
- FALL (fall time)
- DYN setting function OFF

The time that the waveform is high includes the rise time and is set in "ms".

The time that the waveform is low includes the fall time and is set in "ms".

The RISE and FALL time is set in "A/ $\mu$ s".



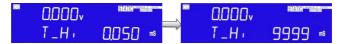
The actual engineering unit is shown on the right of the Right 5 digit display



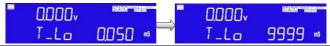
Press DYN setting key, LED will ON setting level High Period, Middle 5 digit LCD display will show "T-Hi" Right 5 digit LCD display will show setting value, the unit is "ms", The T-Hi set range from 0.010 ms to 9999 ms step 0.001ms by rotating the setting knob.

There are four ranges from 0.010 ms to 9999 ms, the ranges are below:

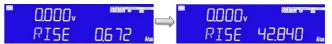
- Range 1:0.010ms~9.999ms
- Range 2:10.00ms~99.99ms
- Range 3:100.0ms~999.9ms
- Range 4:10000ms~9999ms



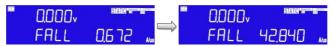
Setting level Low period, Middle 5 digit LCD display will show "T-Lo", right 5 digit LCD display will show setting value, the unit is "ms", the T-Lo set range from 0.010 ms to 9999 ms step 0.001ms by rotating the Setting knob.



Setting rise time, Middle 5 digit LCD display will show "RISE", right 5 digit LCD display will show setting value, the unit is " $A/\mu$ s", the RISE time set range from 0.672A/us to 42.840 A/us step 0.168A/us by rotating the Setting knob.



Setting fall time, Middle 5 digit LCD display will show "FALL", right 5 digit LCD display will show setting value, the unit is " $A/\mu$ s", the FALL time set range from 0.672A/us to 42.840A/us step 0.168A/us by rotating the Setting knob.



Config key



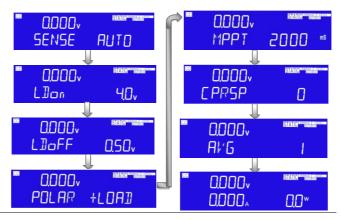
The CONFIG key allows the sense function to engage automatically or switched ON. The CONFIG key also enables the LOAD to automatically turn ON/OFF when a voltage level is reached. The polarity symbol can also be switched via the CONFIG menu.

Each press of the CONFIG key moves the menu on one step. On first press of the CONFIG key the button will illuminate and EXTIN will be displayed on the Right



upper LCD. The value is adjusted with the rotary knob and can be read from the right LCD during setting. The setting sequence is shown below:

- SENSE (AUTO or ON)
- LDon (Voltage at which LOAD turns ON)
- LDoff (Voltage at which LOAD turns OFF)
- POLAR (change polarity symbol)
- MPPT
- CPRSP
- Exit CONFIG options



Note

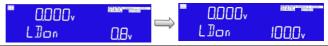
- The adjustable LDon (LOAD ON) voltage is valid for CC, CR & CP operating modes. The adjusted LDon voltage will not operate in CV mode.
- The LDon (LOAD ON) voltage setting cannot be lower than the LDoff (LOAD OFF) voltage. If 0V is required for both LOAD ON and LOAD OFF make the LOAD OFF adjustment first.

Set vsense and load input switching methods, the middle of the 5 digit LCD display will show "SENSE", Right 5 digit LCD display will show "AUTO" or "ON".





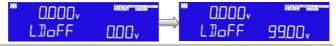
Set Load ON voltage, the middle of the 5 digit LCD display will show "LDon", Right 5 digit LCD display will show setting value, the units is V, The Load ON Voltage set range from 0.8V to 100.0V step 0.4V by rotating the setting knob. If the load is greater than the input voltage Load ON voltage setting, the Electronic load current begin to load on.



Note

CC/CR/CP MODE is controlled by Load ON voltage, CV MODE is not controlled by Load ON voltage.

Set Load OFF voltage, the middle of the 5 digit LCD display will show "LDoFF", Right the 5 digit LCD display will show settings value, the units is V, The Load OFF Voltage set range from 0.0V to 99.00V step 0.01V by rotating The Setting knob. If the load input voltage is less than Load OFF setting voltage, the electronic load to load off.



Set Load polarity, the middle of the 5 digit LCD display will show "POLAR", Right the 5 digit LCD display will show "+ LOAD" or "-LOAD", use the knobs and key settings "+ LOAD" or "-LOAD".

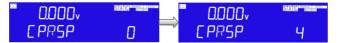




Set MPPT (Maximum power point tracking) testing, the middle of the 5 digit LCD display will show "MPPT", Right the 5 digit LCD display "1000", the MPPT setting range from 1000mS to 60000mS.



Set CPRSP, the middle of the 5 digit LCD display will show "CPRSP", Right the 5 digit LCD display "0", the CPRSP set range from 0 to 4 steps 1 by rotating the setting knob. Setting CP Mode reaction speed, 0: Fast, 4: Slow.



Set AVG, the middle of the 5 digit LCD display will show "AVG", Right the 5 digit LCD display "1", the AVG setting range from 1 to 64 steps 1 by rotating the setting knob.



## Test keys description



Item, Setting and Exit keys

Item

Setting

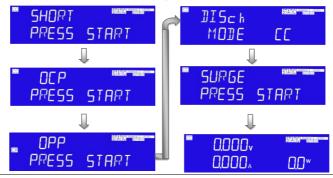
"key. Press ITEM key enter setting mode, ITEM LED light ON, the setting sequence is shown below:

Item, Setting and Exit key for Test. There

are eight operating modes. These can be selected in turn by pressing the "Item

Exit

- OCP
- OPP
- DISch
- SURGE
- Exit ITEM options





Setting Short mode

The Setting key allows the parameters of a SHORT circuit test to be entered. The SHORT test will attempt to sink high current up to the PEL-5000C series load maximum current in order to check the power source's protection and behavior. The test time can be adjusted and threshold values for the High and low voltage limits set.

Setting

Pressing the Setting key once will cause the button to illuminate. The Message "SHORT PRESS START" will be shown across the 3 displays.

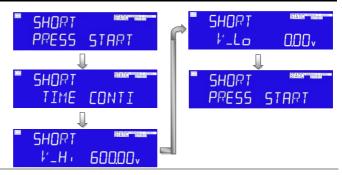
Setting

Each press of the SHORT key moves the menu on one step. The left and Middle LCDs show the currently selected test parameter as text. The value is adjusted by the rotary knob and can be read from the right display during Setting.

The setting sequence is shown below:

- SHORT PRESS START (pressing the start/stop key starts test)
- SHORT Time (CONTI = Continuous or 100ms to 10,000ms possible)
- SHORT V\_Hi (High voltage threshold setting)
- SHORT V\_Lo (Low voltage threshold setting
- Exit SHORT test set-up

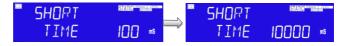




Set the short test time, the LCD display show "SHORT" on left 5 Digits LCD display, shows "TIME" on middle 5 digits LCD display, right 5 digit LCD display "CONTI", the unit is "ms".

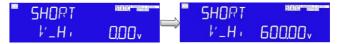


TIME: Set the short test time, The LCD display show "SHORT" on left 5 digits LCD display, shows "TIME" on middle 5 digits LCD display the unit is "ms", and shows "CONTI" on right 5 digits LCD display, the setting range is "CONTI" means continue, 100mS to 10000mS step 100mS by clockwise rotate the setting knob. The short test will be no time limitation when setting to CONTI until press "START/STOP" key to stop the short test.

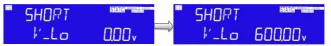




V-Hi: Short test voltage check upper limitation setting, the LCD display shows "SHORT" on left 5 digit LCD display, Middle 5 digit LCD display "V-Hi", right 5 digit LCD display setting value, the unit is "V", The V-Hi setting range from 0.00V to 600.00V step 0.01V by rotating the setting knob.



V-Lo: Short test voltage check lower limitation setting, the Left 5 digit monitor display the "SHORT", the middle 5 digit monitor display the "V-Lo" and right lower monitor display setting value, the unit is "V". The range is 0.01V to 600.00V.



Start Stop Once the test parameters have been entered the test is started by pressing the START/STOP button while the SHORT PRESS START text is displayed. During the test the bottom LCD will show run and the actual short current will be displayed on the right upper LCD.

Note

- The message PASS END will be displayed if the measured voltage levels stay within the V\_Hi and V\_Lo threshold levels during the test.
- The message FAIL END will be displayed if the measured voltage levels fall outside the V\_Hi and V\_Lo threshold levels during the test. The NG flag will also illuminate.
- If continuous short time is selected the test is ended by pressing the red START/STOP button.



OCP parameters setting The OCP key allows the parameters of an Over Current Protection test to be entered. The OCP test will ramp up the load current in steps to validate the Device Under test's (DUT) protection and behavior. A voltage threshold level can be set. If the voltage measured during the test is lower than the set Threshold voltage then the test will fail and the display will signal OCP ERROR. Similarly a current Threshold (I STOP) can be set. If the measured Current reaches the I STOP Threshold the test will be discontinued and the OCP ERROR message will be displayed.

### Setting

Press the Setting key once will cause the button to illuminate. The message "OCP PRESS START" will be shown across the 3 displays.

Each press of the OCP button moves the menu on one step. The Left and Middle LCDs show the currently selected test parameter as text. The value is adjusted by the rotary knob and can be read from the Right display during setting.

The setting sequence is shown below:

- OCP VTH OCP PRESS START (pressing the red start/stop key starts test)
- OCP I STAR (current starting point of the OCP test)
- OCP I STEP (value of incremental current steps from I START)
- OCP I STOP (the OCP test's upper current threshold
- OCP Vth (the voltage threshold setting)
- Exit OCP test set-up

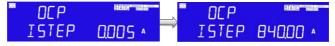




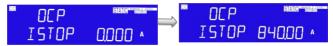
ISTAR: setting the start current point, the Left 5 digit monitor display the "OCP", the right upper 5 digit monitor display the "ISTAR", and right lower monitor display setting value, the unit is "A". The range is 0.001A to the full scale of the CC mode specification. The setting is by rotating the setting knob.



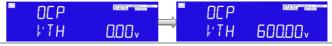
ISTEP: setting the increment step current point, The LCD display shows "OCP" on Left 5 digit LCD display, Middle 5 digit LCD display "ISTEP", right 5 digit LCD display setting value, the unit is "A". The setting range is 0.01A to the full scale of the CC mode specification. The setting is by rotating the setting knob.



ISTOP: setting the stop current point, The LCD display shows "OCP" on Left 5 digit LCD display, Middle 5 digit LCD display "ISTOP", right 5 digit LCD display setting value, the unit is "A", the setting range is 0.000A to the full scale of the CC mode specification. The setting is by rotating the setting knob.



Vth: Setting threshold voltage; The LCD display shows "OCP" on left 5 Digit LCD display, middle 5 digit LCD display "Vth", right 5 digit LCD Display setting value, the unit is "V", the setting range is 0.00V to the full scale of the voltage specification. The setting is by rotating the setting knob.





Once the test parameters have been entered the test is started by pressing the red START/STOP button while the OCP PRESS START text is displayed. During the Test the middle LCD will show run and the actual current being Taken will be displayed on the Right LCD

Note

The message OCP ERROR will be displayed if the DUT fails the test. The reasons for failure are due to one of the following conditions:

- (a) the voltage level of the DUT falls below the set voltage threshold (OCP Vth) during the test
- (b) The current taken from the DUT reaches the OCP I STOP setting.

The message PASS will be displayed if the DUTs voltage stays above the set threshold. Also to PASS the OCP test the current taken from the DUT cannot equal the I STOP



setting.

If the DUT passes the OCP test the maximum current taken during the test is displayed on the right LCD.

Upon PASS or OCP ERROR the test will automatically stop. The red START/STOP button can be used during the test to immediately cease operation.

OPP parameters setting

The OPP allows the parameters of an Over Power Protection test to be entered. The OPP test will ramp up the load power in steps to validate the Device under test's (DUT) protection and behavior. A voltage threshold level can be set. If the voltage measured during the test is lower than the set Threshold voltage then the test will fail and the display will signal OPP ERROR. Similarly a power threshold (P STOP) can be set. If the measured power reaches the P STOP threshold the test will be discontinued and the OPP ERROR message will be displayed.

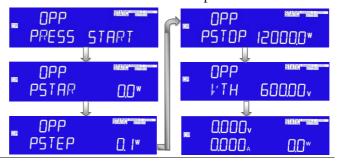
Setting

Press the Setting key once will cause the button to illuminate. The message "OPP PRESS START" will be shown across the displays.

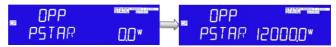
Each press of the OPP button moves the menu on one step. The Left and Middle LCDs show the currently selected test parameter as text. The value is adjusted by the rotary knob and can be read from the Right display during Setting.

The setting sequence is shown below:

- OPP PRESS START (pressing the red start/stop key starts test)
- OPP P STAR (power starting point of the OPP test)
- OPP P STEP (value of incremental current steps from P START)
- OPP P STOP (the OPP test's upper threshold power limit)
- OPP Vth (the voltage threshold setting)
- Exit OPP test set-up

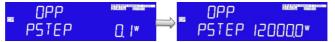


PSTAR: setting the start power, the LCD display shows "OPP" on left 5 digit LCD display, middle 5 digit LCD display "PSTAR", right 5 digit LCD display setting value, the unit is "W", the setting range is 0.00W to the full scale of the CP mode specification. The setting is by rotating the setting knob.

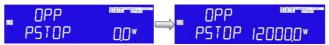




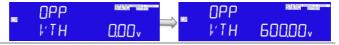
PSTEP: setting the increment step power, the LCD display shows "OPP" on left 5 digit LCD display, middle 5 digit LCD display "PSTEP", right 5 digit LCD display setting value, the unit is "W", the setting range is 0.00W to the full scale of the CP mode specification. The setting is by rotating the setting knob.



PSTOP: setting the stop power, the Left 5 digit monitor display the "OPP", the right upper 5 digit monitor display the "PSTOP", and right lower monitor display setting value, the unit is "W". The range is 0.1W to the full scale of the CP mode specification.



Vth: Setting threshold voltage; the Left 5 digit monitor display the "OPP", the right upper 5 digit monitor display the "Vth", and right lower monitor display setting value, the unit is "V". The range is 0.00V to the full scale of the voltage specification. The setting is by rotating the setting knob.





Once the test parameters have been entered the test is started by pressing the red START/STOP button while the OPP RESS START text is displayed. During the Test the middle LCD will show run and the actual current being Taken will be displayed on the Right LCD



Note

The message OPP ERROR will be displayed if the DUT fails the test. The reasons for failure are due to one of the following conditions:

- (c) the voltage level of the DUT falls below the set voltage threshold (OPP Vth)during the test
- (d) The current taken from the DUT reaches the OPP P STOP setting.

The message PASS will be displayed if the DUTs voltage stays above the set threshold. Also to PASS the OPP test the current taken from the DUT cannot equal the I STOP setting.

If the DUT passes the OPP test the maximum current taken during the test is displayed on the right LCD.

Upon PASS or OCP ERROR the test will automatically stop. The red START/STOP button can be used during the test to immediately cease operation.

Battery discharge setting

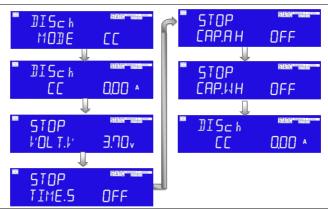


DIsch the test function has 5 parameters, "CC", "VOLT.V", "TIME.S", "CAP.AH" and CAP.WH parameters.

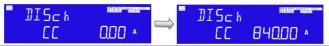
Press the Setting key to set stop discharge voltage "VOLT.V", Press again Setting key to set stop discharge time "TIMES.S".

Press Setting key again to stop discharge capacity "CAP.AH" / "CAP.WH".

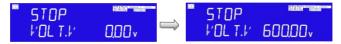




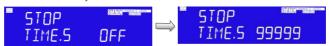
Setting battery discharge CC mode, DISCH CC, LCD show "DISch", middle 5 digit LCD display "CC", setting range 0.00A to full scale.



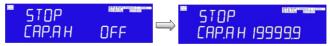
Setting stop discharge voltage STOP "VOLT.V", middle 5 digit LCD display "VOLT.V", right 5 digit LCD display setting value, unit is V, STOP "VOLT.V" setting range 0.00V to full scale.



Setting stop discharge time, setting STOP "TIME.S", middle 5 digit LCD display "TIME.S", right 5 digit LCD display setting value, STOP "TIME.S" setting OFF to 99999, each setting knob and button adjustment interval is 1.



Setting stop discharge capacity, setting STOP "CAP.AH", middle 5 digit LCD display "CAP.AH", right 5 digit LCD display setting value, STOP "CAP.AH" setting range OFF to 19999.9, each setting knob and button adjustment interval is 0.1.



Setting stop discharge capacity, setting STOP "CAP.WH", middle 5 digit LCD "CAP.WH", right 5 digit LCD display setting value, STOP "CAP.WH" setting range OFF to 19999.9, each setting knob and button adjustment interval is 0.1.



Surge current testing setting

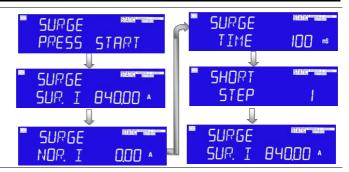


SURGE sequence is shown below:

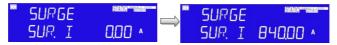
SURGE the test function has 4 parameters, "SUR.I", "NOR.I', "TIME" and "STEP" parameters.

- Press the Setting key to set surge current testing loading current value "SUR.I".
- Press again Setting key to set normal current testing loading current value "NOR.I".
- Press Setting key again to set surge current testing time "TIME".
- Press the Setting key again to set surge current testing diminishing step current setting value "STEP".





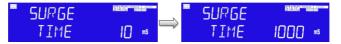
Set SURGE testing surge current, unit is A, setting range 0.00A to full scale.



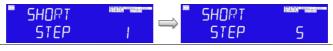
Set SURGE testing normal current, unit is A, setting range 0.00A to full scale.



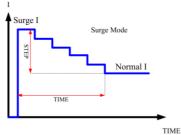
Set SURGE time, unit is mS, setting range 10mS to 1000mS.



Set SURGE step, setting range 1 to 5.



## Setting fig explanation.





Exit Key	Exit	Setting OCP / OPP / DISch / SURGE during the setting process press Exit key to exit setting item.
Start/Stop key	Start Stop	The START/STOP key is used in conjunction with the SHORT, OCP or OPP test functions. It is used to START a test according to the set parameters or to STOP a test before PASS or FAIL is signaled. Please refer to the preceding sections for more information on the SHORT, OCP & OPP tests.



## System keys description



Shift key



Shift key is used to switch the key to the second function key.

System key



Press SYSTEM to set the argument, GPIB address, RS232 BAUD- RATE, WAKE UP and buzzer Alarm power ON/OFF and Master/Slave control.



Local key



Press Local key to exit REMOTE mode



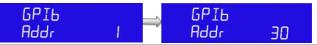
Setting system parameters

Set GPIB address



Set GPIB address, RS232 BAUD RATE, WAKE UP, Buzzer ON/OFF

First press SYSTEM key, the LCD display shows GPIB on left 5 digit LCD display, Middle 5 digit LCD display Addr, right 5 digit LCD display setting GPIB address of the representative, Press UP, DOWN buttons to adjust the GPIB address 1~30, Key and then press ENTER, PEL-5000C series GPIB Address value is saved, Press system key four times to leave the GPIB address configuration State.



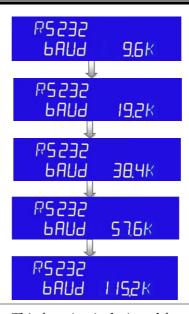
Set RS232 BAUD RATE



X2

SYSTEM key first by the second, the LCD display shows RS232 on left 5 digit LCD display, Middle 5 digit LCD display baud, right 5 digit LCD display setting BAUD-RATE, Press UP, DOWN buttons to adjust the value of BAUD RATE, Key and then press ENTER, PEL-5000C series is saved setting BAUD RATE, press system key three times to leave the BAUD-RATE setting state.





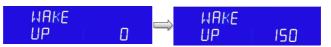
WAKE-UP function

System

X3

This function is designed for auto setting the load status and load level in turning on the PEL-5000C series every time. SYSTEM key first by the three, The LCD display shows WAKE on left 5 digit LCD display, Middle 5 digit LCD display UP, right 5 digit LCD display setting, Press UP, DOWN buttons to adjust the 0~150.

Press ENTER key to be stored, press system key two times to leave the WAKE-UP setting state, If set to "0" means do not call.





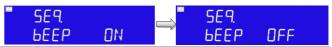
Buzzer ON/ OFF This is the test set automatically (AUTO SEQUENCE) at the end, if it increases buzzer function, if set to ON, Then when the test result is PASS automatically when the buzzer will call out, if the test result is FAIL when the buzzer will call the second tone.



X4

Setting method:

first by 4 Times SYSTEM key and the LCD display shows SEQ on left 5 digit LCD display, Middle 5 digit LCD display bEEP, right 5 digit LCD display setting ON or OFF, press UP DOWN key to adjust.



Note

Setting system parameters, if the input is required to use the KEYPAD ENTER button to confirm, otherwise PEL-5000C Series will not save the changes the settings.

Pass: Automatic test mode, no NG state, is the PASS. Fail: Automatic test mode, any test if the NG then is the FAIL.

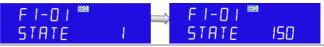
Recall/ Store key Store Recall Recall/ Store load state settings

The function keys on the front panel of PEL-5000C series mainframe are designed for high testing throughput purpose. There are 150 operation states or testing steps can be store in the EEPROM memory of PEL-5000C series electronic load respectively, each state can store or recall the load status and level for electronic load simultaneously.



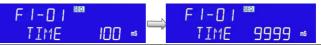
STORE process	Store Recall	Set the load status and load level. Press SHIFT key then press the STORE key to enter the storage state.		
		Press UP, DOWN key or KEYPAD to adjust, press the ENTER OK to save the STATE.		
RECALL	Store	Press RECALL to enter the call state.		
operation	Recall	Press UP, DOWN key or KEYPAD to adjust.		
		Finally, Press the ENTER key to confirm, In the electronic load front panel, set the value that would call out the information in accordance with re-setting.		
AUTO SEQUENCE instructions		PEL-5000C series has AUTO SEQUENCE function, PEL-5000C series to select the state F1~F9 Automatic testing can be edited, 16 steps each group can be set to select 150 group of the STATE, within each step can be set TEST TIME Units of 100 ms range (0.1s ~ 9.9s).		
Edit mode	Shift	Press SHIFT key, press the SEQ. key to enter the AUTO SEQUENCE mode, Press UP, DOWN key to select EDIT, the LCD display shows EDIT on left 5 digit LCD		
	SEQ			
	Mode	display, Middle 5 digit LCD display FX, "FX" means to Select the state F1-F9,Press keypad key $1 \sim 9$ choose F1 $\sim$ F9.		
	EdIT Fl	san EdIT san OO.O F9 O.O		

 Press ENTER key, the LCD display shows FX-XX on left 5 digit LCD display, Middle 5 digit LCD display STATE, right 5 digit LCD display setting 1~150, "FX" means to select the state F1-F9. "XX" means the test STEP01-16, setting state value, press UP and down key or keypad to adjust setting.

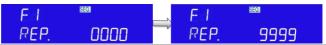


Test time setting

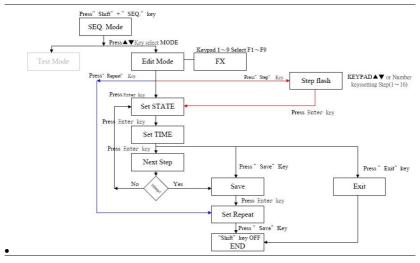
 Press ENTER to set TIME value, press UP, DOWN keys or KEYPAD to adjust settings, range from 100 ms~9999ms.
 Press ENTER key or SAVE key to finish editing the action is set to repeat, if you do not save the settings, press the EXIT key to leave edit mode.



 Setting repeat (REPEAT TEST), Press UP and DOWN key or Keypad to adjust setting 0~9999, Press ENTER SAVE REPEAT Value, or press eXIT key Exit EDIT MODE.





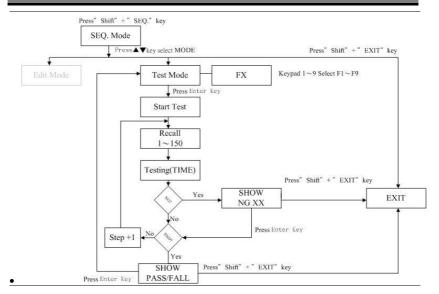


Store (Edit) mode operation flow chart



Test mode	<ul> <li>Press SHIFT key, press the SEQ. key to enter the AUTO SEQUENCE mode, Press UP, DOWN key to select TEST, the LCD display shows tEST on left 5 digit LCD display FX, "FX" means to Select the state F1-F9, Press keypad key 1 ~ 9 choose F1 ~ F9. When the press ENTER to enter. The next automatic test Mode.</li> <li>Test LCD will display "SXX", "XX" on behalf of the test of STEP, if the test result is NG, the LCD will show "NG" (flashing) and suspension of the test, this time users can test or ENTER key to continue Press EXIT key to leave the test mode, test mode by the (STEP01 - TIME) then (SETP02 - TIME) until all the steps done or press EXIT to leave the test mode.</li> </ul>
	• If all the test steps are OK, the test result is PASS, LCD displays "PASS"; test procedure if any of the NG, the test result is FAIL,, LCD displays "FAIL", if the buzzer is set to ON, when the test result is pass automatically when the buzzer will call out, if the test result is fail Buzzer will sound when the second call.
	When the test is completed, the user can press the ENTER key again to test or EXIT key to leave the test mode.
Example	• Edit the 16 step test is completed, press the TEST key, according to the order of S01 ~ S16 test is complete LCD display PASS.





Test mode operation flow chart



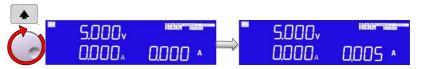
## Test keys description



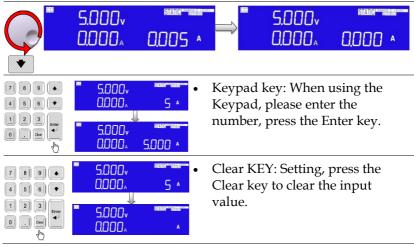
Rotary Knob The ROTARY knob and ARROW keys are used to and ARROW increase or decrease the set values.

Keys

• Clockwise the rotary switch and up arrow key to increase the setting values.



 Anti-clockwise and down arrow key operation of the ROTARY Knob decreases the setting value.





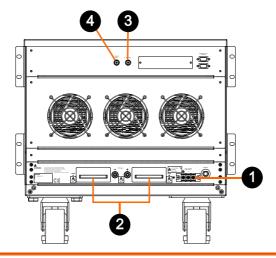
Note	In CR mode, the up arrow key and clockwise operation of the rotary Knob reduces the resistance.		
	In CR mode, the down arrow key & anti-clockwise operation of the rotary Knob increases the resistance.		

# CONNECTION

Rear Panel	80
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#### Rear Panel



#### 1 DC INPUT Terminal

The positive (LOAD +) and negative (LOAD -) power input terminals are clearly marked. DO NOT confuse them with the smaller SENSE terminals.

Please ensure that the voltage and current rating of the DUT do not exceed the maximum rating of the PEL-5000C Series load module being used. Please also check the output polarity of the DUT prior to connection and testing.

The negative load terminal should be connected to ground if testing a positive output power supply. This is normally achieved when the negative output of the power supply is grounded.

Similarly if a power supply with a negative output is to be tested then the positive load terminal should be grounded. This is normally achieved when the positive output of the power supply under test is grounded.

# 2 V-sense input terminal

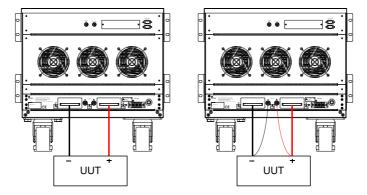
The V-sense terminals can be used to compensate for a voltage drop in the load lines between the power supply and the PEL-5000C series Electronic Load. This is a useful feature useful when the load current is relatively high.

If remote sense is required the V-sense terminals are connected to the appropriate positive and negative terminals of the power supply as shown in fig below. In the CONFIG menu the V-sense function can be set to AUTO or ON.

Please note that if V-sense is set to AUTO and the sense leads are connected to the DUT the losses need to be approx. before the display compensates for the voltage loss.

If V-sense is set to 'ON' and the sense terminals are connected to the DUT the load will check and compensate for all voltage drops.

The maximum voltage sense compensation is the same as the rating of the PEL-5000C series electronic load. For example the PEL-5006C-1200-240 is capable of sinking current at up to 1200Vdc. Therefore the maximum V-sense is also 1200Vdc.



Typical connection of PEL-5000C series load module

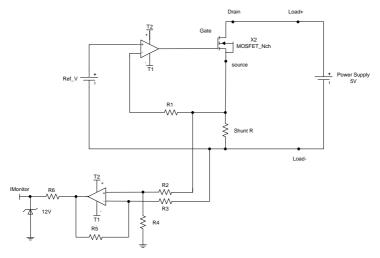
3 I-monitor The I-monitor is provided as a BNC socket. It is



designed to enable the user to monitor the Electronic Load's input current or short current. The I-monitor's signal is 0V to 10V. This signal is proportional to the full scale current that the particular electronic Load is capable of.

Example

PEL-5012C-600-840: Imax = 840A therefore I-monitor 10V = 840A so 1V = 84A



An equivalent circuit in terms of the current monitor

4 Analog programming input

The Electronic Load has an analog programming input on the rear panel of the mainframe. The analogue programming input enables the load module to track and load according to an external 0-10V (ac or ac + dc) signal.

The analog programming input is configured as a BNC socket on the mainframe's rear panel.

The analogue programming input operates in CC or CP modes only. The PEL-5000C series Load will attempt to load proportionally according to the signal and the load module's maximum current or power range. For example: PEL-5012C-600-840: Imax = 840A and Pmax = 12000W

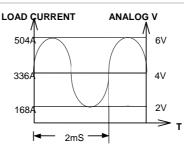
So in CC mode if analogue programming input is 5V = 420A load setting (Range II) or in CP mode if analogue programming input is 1V = 1200W load setting (Range II)

The analog programming signal can act alone or it can be summed with the programmed value set via the front panel or the optional computer interface (GPIB, RS-232, USB, or LAN) or the front panel.

#### Example

Fig. below shows the result of an analog programming signal at 4 Vac, 500Hz when it is summed with a 128A programmed setting in CC mode of PEL-5012C-600-840 Load.

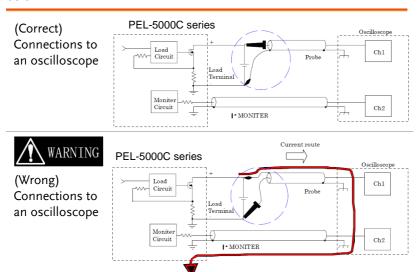
Analog programming example





# Connecting the I-monitor to an oscilloscope

When you connect this product to an oscilloscope, please ensure the correct polarities of the connecting probes as shown in fig below



If the probes connection is reversed as shown above, a large current would flow through the probe and the internal circuitry of the oscilloscope is likely to be damaged.

## Master/Slave Instructions

PEL-5000C Series "MASTER / SLAVE" Parallel function, 1 Master, 7 SLAVE, setting method press the System key to set the CONTROL MODE to select ALONE, MASTER or SLAVE1 ~ 7, Press the ENTER key to set, when Power off Data will not be lost, this parameter is saved. Master will automatically detect whether there is slave machine, if there is no Slave Machine will run "ALONE Mode", if the Slave machine will run "MASTER Mode". Master machine measuring current and power meter is to show the total current and total power (Master + Slave), the voltage meter is displayed by the Master Machine, the Slave machine voltage meter position will display "SL1" ~ "SL7".



The following procedure should be followed before applying power on Master/Slave mains: Step1. Turn on (O) the Slave POWER switch. Step2. Turn on (O) the Master POWER switch.

The following procedure should be followed before applying power off Master/Slave mains:

Step1. Turn off (I) the Master POWER switch. Step2. Turn off (I) the Slave POWER switch.



Parallel method Use HD-DSUB 15pin 1: 1 Cable to connect the MASTER and SLAVE rear panel, HD-DSUB 15pin connector (connect the upper and lower Connectors) Caution Do not use VGA Cable, because of internal pin4 ~ 8, 11 and chassis short circuit. 0 0 Master/Slave, It requires wiring as follows: Wiring requirements Vsense is not connected Vsense connection 0+ 0+ 0+ 0+ Manual operation (PEL-5012C-600-840 MASTER/SLAVE model the following is example)PRESET setting: CC/CR/CV/CP Mode as Figure, CC setting 64A=Master 32A + Slave 32A, CR:12500 $\Omega$ =Master//Slave=6250 $\Omega$ //6250 $\Omega$ , CV: 100V=Master 100V=Slave=100V,

CP:1000W=Master 500W + Slave 500W.

5.000v

0.000 4 64.000 4

Master Display

CC Set 100A



	Slave Display		SL 1 SAIO CARA
CR Set $12500\Omega$	Master Display	e:	0.000v SIAIG SAGE 0.000a 12500 a
	Slave Display	<b>B</b> (8	SL 1 8446 200 2
CP Set 1000W	Master Display	Ma	5,000v SIAIO***********************************
	Slave Display	es.	SL I SOOO*
CV Set 100V	Master Display	GV	500.0v SIAIO -
	Slave Display		SL 1 0,000 A 100,000 v

Note

Master Mode operation except CC / CR / CV / CP Mode, The following functions will be disabled.

- Config function BATT type 1~N Disable
- Config functions MPPT disable.
- CC+CV, CP+CV Disable.
- Recall/Store Disable.
- Auto Seq. Disable.
- Short, OCP, OPP Disable.



# NSTALLATION

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## Check line voltage

#### Background

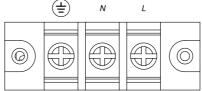
The PEL-5000C Series high power load can operation with 100 Vac ~240Vac input as indicated on the label on the rear panel. Make sure that the factory check mark corresponds to your nominal line voltage. Skip this procedure if the label is corrected marked.

#### Installation

- 1. With the PEL-5000C Series load power OFF, disconnect the power cord.
- 2. Refer the drawing on the rear panel of PEL-5000C Series high power load below.

PEL-5000C series AC Input Connection

# LINE INPUT



## Grounding requirements

#### Installation

- 1. It is requested to use the 3Pin plug connector only for PEL-5000C Series mainframe to out of danger when electric leakage. And the complete and proper grounded is necessary.
- 2. The PEL-5000C Series high power load is equipped with three conductor cable which plugs in an appropriate receptacle to ground the instrument's cover.



### Power up

D	-	~	٠,	١.	ıre
м	( )	( 6	٦(	11.	ır⊬

- 1. Turn off (O) the POWER switch.
- 2. Check that the power cord is corrected.
- 3. Check that nothing is connected to the DC INPUT on the rear panels.
- 4. Turn on POWER switch.

## Connection to the load Input Terminal

Connection procedure of the load input terminal on the rear panel

#### Procedure

- 1. Turn off POWER switch.
- Check that the output of the equipment under test is off.
- 3. Connect the load wire to the load input terminal on the rear panel.
- 4. Check the polarity of the connection and connect the load wire to the output terminal of the equipment under test.

#### Note

Avoid equipment damaged, don't input the DC voltage standard output to the DC Load input terminal, if calibration voltage meter required, please input the DC voltage standard to the Vsense input.

## GPIB & RS232 interface option

Connection procedure of the load input terminal on the rear panel

#### Procedure

- 1. GPIB + RS232 interface is on the rear panel of PEL-5000C Series Mainframe for application GPIB or RS232.
- 2. GPIB and RS232 interface can only be used at the same time, to change the interface must reboot unit.
- GPIB connection with three important limitations as described below:

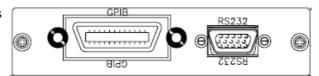
The maximum number of devices including the controller is no more than 15.

The maximum length of all cable is no more than 2 meters times the number of devices connected together, up to 20 meters Maximum.

RS232 female block connections on the back panel, the connecting device and the computer RS232 port to one-way connection.

The figure below shows the RS232 connector (Female) on the rear panel connects PEL-5000C Series Mainframe to RS232 port of computer in one by one configuration .The RS232 BAUD-RATE can be set in the front panel, it will be lit the GPIB address when press the "SYSTEM" button. Press it again, it will be lit the BAUD-RATE.

PEL-5000C Series GPIB & RS232 interface





#### RS232 interface option

Connection procedure of the load input terminal on the rear panel

The figure below shows the RS232 connector (Female) on the rear panel connects PEL-5000C Series mainframe to RS232 port of computer in one by one configuration. The RS232 BAUD-RATE can be set in the front panel, it will be lit the GPIB address when press the "SYSTEM" button. Press it again, it will be lit the BAUD-RATE.

PEL-5000C Series RS232 interface



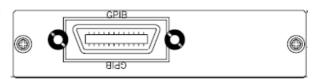
## GPIB interface option

Connection procedure of the load input terminal on the rear panel

The maximum number of devices including the controller is no more than 15.

The maximum length of all cable is no more than 2 meters times the Number of devices connected together, up to 20 meters maximum.

PEL-5000C Series GPIB interface



## **USB** interface option

Connection procedure of the load input terminal on the rear panel

The figure below shows the USB connector in the rear panel of PEL-5000C Series mainframe.



PEL-5000C USB interface



## LAN interface option

Connection procedure of the load input terminal on the rear panel

The figure below shows the LAN connector in the rear panel of PEL-5000C Series mainframe.

PEL-5000C LAN interface



### I/O connection

Connection procedure of the load input terminal on the rear panel

PEL-5000C series I/O Interface with Vsense, Analog Programming Input, Imonitor

PEL-5000C series I/O interface













## Load current slew rate setting

Connection procedure of the load input terminal on the rear panel

What is the load current slew rate during load current level change, power supply turn ON/OFF switch between ON, and OFF? The PEL-5000C series Electronic load provides all of the above load current slew rate in controllable condition, the rise and fall current slew rate can be set independently from front panel operation or remote programming.

The slew rate determines a rate at which the current changes to a new programmed value. The slew rate can be set at the front panel or via GPIB on the rear panel of PEL-5000C series high power load.

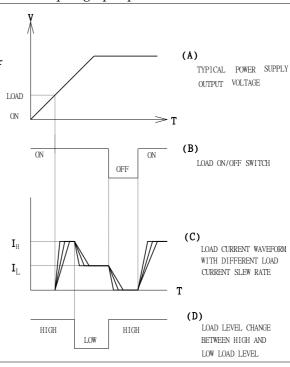
The rise and fall slew rate can be independently programmed from 384mA/usec to 24A/usec (PEL-5012C-600-840 Load) in the 840A current range and from 38.4mA/usec to 2.4A/usec in the 84A current range. This allows a independent controlled transition from Low load current level to High load current level (Rise current slew rate) or from High load current level to Low load current level (Fall current slew rate) to minimize induced voltage drops on the inductive wiring, or to control induced transients on the est. device (power supply transient response testing).

This controllable load current slew rate feature also can eliminate the overload current Phenomenon and emulate the actual load current slew rate at turn ON the power supply Under test. The load current slew rate is according to the power supply's Output Voltage, Load level setting and Load ON/OFF switch. So, you could do all items of Power

Supply testing task by using constant current mode only, it can significantly improve The Testing quality and Process as well as efficiency.

There are two load current range in PEL-5000C series Load, Range I and Range II, the slew rate of range I, range II, RISE/FALL slew rate are listed in paragraph specifications.

The relationship of load current load ON/OFF, load level and output voltage of DC power supply at turn ON

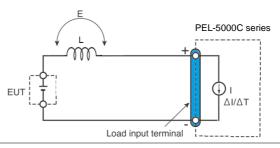




#### Load wire inductance

Connection procedure of the load input terminal on the rear panel

The load wiring has an inductance (L). When the current (I) varies in short time period, It generates a large voltage at both ends of the wiring cable. This voltage applies to all of the load input terminals of the PEL-5000C Series when the impedance of the EUT is relatively small. The voltage generated by the load wire inductance (L) and the current variation (I) is expressed using the following equation.



 $E = L \times (\Delta I / \Delta T)$ 

E: Voltage generated by the wire inductance

L: Load wire inductance

ΔI: Amount of Current variation

 $\Delta T$ : Variation period of current

In general, the wire inductance can be measured approximately 1  $\mu$ H per 1 meter. If the 10 meters of Load wires is connected between the EUT and the electronic load (PEL-5000C Series) with the current Variation of 2 A/ $\mu$ s, the voltage generated by the wire inductance Will be 20 V.

The negative polarity of the load input terminal is the reference potential of the external Control signal, Therefore, the device connected to the external control terminal may get malfunctioned.

When operating under the constant voltage (CV) mode or constant resistance (CR) mode or constant power (CP), the load current is varied by the voltage at the load input terminal, so the operation can be affected easily by the generated voltage.

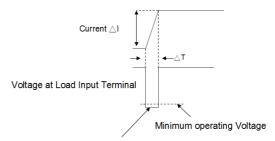
The wiring to the EUT should be twisted and the shortest as possible.

If the load wire is long or has a large loop, the wire inductance is increased. Consequently, the Current variation that results when switching occurs will cause a large voltage drop.

When the value of instantaneous voltage drops under the minimum operating voltage depends on the generated voltage at the load input terminal, the response of recovery will be extensively delayed.

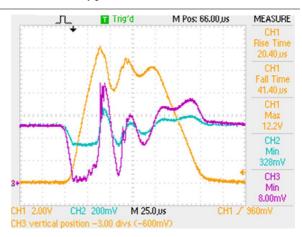
In such event, the electronic load may generate unstable oscillation. In such condition, the input voltage may exceed the maximum input voltage and Cause damage to the PEL-5000C Series.





When the Voltage drops under minimum operating voltage, the electronic load may generate unstable oscillation

Waveform example: Generate unstable oscillation



CH1= Imonitor

CH2=Power Supply output Voltage (x10)

CH3= LOAD Input Voltage (x10)

You must be careful especially when the slew rate setting is high or switching is performed using large currents through parallel operation.

To prevent problems, connect the PEL-5000C Series and the equipment under test using the shortest Twisted Wire possible to keep the voltage caused by inductance between the minimum operating Voltage and the maximum input voltage range or set a low slew rate.

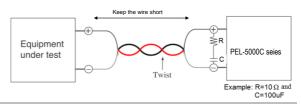
If the high-speed response operation is not required, decrease the slew rate setting.

In such settings, the value of DI /DT will be decreased, accordingly the generated voltage Will be reduced even the inductance of load wiring can't be reduced.

In the case of DC operation also, the phase delay of the current may cause instability in the PEL-5000C Series Control inducing oscillation. In this case also, connect the PEL-5000C Series and the equipment under test using the shortest twisted wire possible.

If only DC operation is required, a capacitor may be connected to the load Input Terminal as shown in Fig below to alleviate oscillation. In this case, use the capacitor within its allowable ripple current.

#### Length of wiring





# REMOTE CONTROL

The rear panel remote control interface of PEL-5000C Series mainframe is designed to connect PC or NOTEBOOK PC with remote control interface, the NOTEBOOK PC acts as a remote controller of PEL-5000C Series Electronic Load.

This feature can be used as an automatic load/cross load regulation and centering voltage testing for a switching power supply or an rechargeable battery charge/discharge characteristic testing. The function capability of rear panel remote control interface not only can set the load level and load status, but also can read back the load voltage and load current.

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## Interface Configuration

The rear panel Communication Interface programming of PEL-5000C series mainframe is designed to connect PC or NOTEBOOK PC with remote control interface, the NOTEBOOK PC acts as a Communication Interface programming of PEL-5000C series Electronic Load.

This feature can be used as an automatic load/cross load regulation and centering voltage testing for a switching power supply or a rechargeable battery charge/discharge characteristic testing. The function capability of rear panel communication Interface programming not only can set the load level and load status, but also can read back the load voltage and load current.

Note

When use USB/LAN interface controls the PEL-5000C series, the PEL-5000C series will convert the USB/LAN interface to RS232 interface.

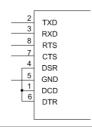
#### Configure RS232C

The following RS232 commands are same as GPIB commands. The RS232 protocol in PEL-5000C Series mainframe is listing below:

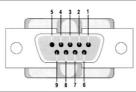
RS232C Configuration	Baud Rate			9600~115200bps 1 bit					
	Stop Bit Data Bit		_	8 bits					
	Parity		N	one					
	Hands	haking	Н	ardv	ware (l	RTS/C	CTS)		
The RS232 Interface	RS232 PC	port on		RS	232 port 5000C	on			
connector of PEL-		TxD -		<b></b>	RxD				
5000C Series rear panel		RxD RTS			TxD CTS				
parier		CTS	ı		RTS				



Inside of PEL-5000C series Mainframe



#### Pin Assignment



PIN	Abbreviation	Description
Pin1	CD	Carrier Detect
Pin2	RXD	Receive
Pin3	TXD	Transmit
Pin4	DTR	Data Terminal Ready
Pin5	GND	Ground
Pin6	DSR	Data Set Ready
Pin7	RTS	Request To Send
Pin8	CTS	Clear To Send
Pin9	RI	Ring Indicator

# Communication Interface programming command list

#### SIMPLE TYPE FORMAT

Table: Communication interface programming setting command summary

Sullimary	
SETTING PRESET NUMERIC COMMAND	REMARK
RISE{SP}{NR2}{; NL}	A/us
FALL{SP}{; NL}	A/us
PERD:{HIGH LOW}{SP}{NR2}{; NL}	
LDONV{SP}{NR2}{; NL}	
LDOFFV{SP}{NR2}{; NL}	
CC   CURR:{HIGH   LOW} {SP} {NR2}{;   NL}	
CP:{HIGH LOW} {SP} {NR2}{; NL}	
CR   RES:{HIGH   LOW} {SP} {NR2}{;   NL}	
CV VOLT:{HIGH LOW} {SP} {NR2}{; NL}	
TCONFIG{SP}{NORMAL   OCP   OPP   SHORT } {;   NL}	
OCP:START {SP} {NR2}{;   NL}	
OCP:STEP {SP} {NR2}{;   NL}	
OCP:STOP {SP} {NR2}{;   NL}	
VTH {SP} {NR2}{;   NL}	
OPP:START {SP} {NR2}{;   NL}	
OPP:STEP {SP} {NR2}{;   NL}	
OPP:STOP {SP} {NR2}{;   NL}	
STIME {SP} {NR2}{;   NL}	
MPPT {SP}{ON   OFF}{;   NL}	
MPPTIME {SP} n{; NL}	SET MPPT RECORD TIME, n=1000~60000 ms
BATT:TYPE {SP}{n}{;  NL}	n=1~5
BATT:UVP{SP}{NR2}{; NL}	unit:V
BATT:CURR{SP}{NR2}{NL}	CC   CURR:HIGH{SP} {NR2}{NL}



BATT:POWER{SP}{NR2}{NL}	CP:HIGH{SP}{NR2} {NL}
BATT:TIME{SP}{n}{; NL}	0~99999,0=OFF
BATT:AH{SP}{NR2}{NL}	0,0.1~19999.9 ,0=OFF
BATT:WH{SP}{NR2}{NL}	0,0.1~19999.9 ,0=OFF
BATT:TEST{SP}{ON   OFF}	TEST ON/OFF
BATT:STEP{SP}{n}{; NL}	Cycle Life TEST: n=1~3,TYPE5:n=1~9
BATT:CCH{n}{SP}{NR2}{; NL}	Cycle Life TEST CC:HIGH level, n=1~3
BATT:CCL{n}{SP}{NR2}{; NL}	Cycle Life TEST CC:LOW level, n=1~3
BATT:TH{n}{SP}{NR2}{; NL}	Cycle Life TEST Thigh (unit:ms), n=1~3
BATT:TL{n}{SP}{NR2}{;  NL}	Cycle Life TEST Tlow (unit:ms), n=1~3
BATT:CYCLE{n}{SP}{NR1}{; NL}	Cycle Life TEST:1~2000, n=1~3
BATT:DYN{SP}{ON   OFF}	Cycle Life TEST ON/OFF
BATT:CC{n}{SP}{NR2}{; NL}	RAMP Current, n=0~9
BATT:CV{n}{SP}{NR2}{NL}	RAMP Voltage, n=0~9
BATT:DTIME{n}{SP}{NR1}{; NL}	TYPE5 Delta time (T1 $\sim$ T9:0 $\sim$ 6000sec), n=0 $\sim$ 9
BATT:REPEAT {SP} {n}{; NL}	Disch CC/CP Repeat times:0~9999
BATT:RAMP:CC{SP}{ON   OFF}	RAMP CC TEST ON/OFF
BATT:RAMP:CV{SP}{ON   OFF}	RAMP CV TEST ON/OFF
SURGE: SURI {NR2}{;  NL} SURGE: NORI {NR2}{;  NL}	
SURGE: TIME {NR2}{;   NL}	SURGE TIME:10~1000ms
SURGE: STEP {SP}{n} {;   NL}	n=1~5
SURGE {ON   OFF}{;   NL}	:ON:RUN



	SURGE,OFF:STOP
$CPRSP{SP}{n}{; NL}$	
$AVG{SP}{n}{; NL}$	

Table: Communication Interface programming query command summary

· <i>y</i>	
QUERY PRESET NUMERIC COMMAND	RETURN
RISE{?} {;  NL}	###.###
FALL{?} {;   NL}	###.####
PERD:{HIGH LOW}{?} {; NL}	###.####
LDONV{?}{; NL}	###.###
LDOFFV{?}{; NL}	###.####
CC CURR:{HIGH LOW} {?} {; NL}	###.###
CP:{HIGH   LOW} {?} {;   NL}	###.####
CR   RES:{HIGH   LOW} {?} {;   NL}	###.####
CV VOLT:{HIGH LOW} {?} {; NL}	###.####
TCONFIG {?}{;   NL}	1:NORMAL 3:OPP 2:OCP 4:SHORT
OCP: START {?} {;   NL}	###.###
OCP: STEP {?}{;   NL}	###.####
OCP: STOP {?}{; NL}	###.###
VTH {?}{; NL}	###.####
OPP: START {?} {;   NL}	###.####
OPP: STEP {?}{;   NL}	###.####
OPP: STOP {?}{;   NL}	###.####
STIME {?}{;   NL}	###.###
OCP {?}	###.###
OPP {?}	###.####
MPP {?}{;   NL}	READ MPP DATA "V/I/P" OR "END"
MPPTIME ?{;   NL}	#####
BATT:RAH?{NL}	READ BATT TEST RESULT AH
BATT:RWH?{NL}	READ BATT TEST RESULT WH
BATT:RTIME?{NL}	READ BATT TEST RESULT TIME
BATT:RVOLT?{NL}	READ BATT TEST RESULT VOLTAGE
AVG {?} {;   NL}	



Table: Communication Interface programming limit command summary

LIMIT COMMAND	REMARK
IH   IL{SP}{NR2}{;   NL}	
IH IL{?}{; NL}	
WH WL{SP}{NR2}{; NL}	
WH WL{?}{; NL}	###.###
VH   VL{SP}{NR2}{;   NL}	
VH VL{?}{; NL}	###.###
SVH SVL{SP}{NR2}{; NL}	
SVH SVL{?}{; NL}	###.###
[LIMit:]ADDCV:VOLTage{SP}{NR2}{;   NL}	
[LIMit : ]ADDCV:VOLTage{?}{;   NL}	###.###
[LIMit:]ADDCV{SP}{ON OFF}{; NL}	

#### Table: STAGE COMMAND SUMMARY

STAGE COMMAND	REMARK
LOAD {SP}{ON   OFF   1   0} {;   NL}	
LOAD {?} {;   NL}	0:OFF 1:ON
MODE {SP} {CC   CR   CV   CP} {;   NL}	
MODE (2) (-INII.)	0:CC 1:CR
MODE {?} {;   NL}	2:CV 3:CP
SHOR {SP} {ON   OFF   1   0} {;   NL}	
SHOR {?} {;   NL}	0:OFF 1:ON
PRES {SP} {ON   OFF   1   0} {;   NL}	
PRES {?} {;   NL}	0:OFF 1:ON
SENSe {SP} {ON   OFF   AUTO   1   0} {;   NL}	
SENSe {?} {;   NL}	0:OFF/AUTO 1:ON
LEV {SP} { LOW   HIGH   0   1} {;   NL}	
LEV {?} {;   NL}	0:LOW 1:HIGH
DYN {SP} {ON   OFF   1   0} {;   NL}	
DYN {?} {;   NL}	0:OFF 1:ON
CLR{;   NL}	
ERR {?}{;   NL}	
NG {?}{;   NL}	0:GO 1:NG
PROT {?}{;   NL}	
CC{SP}{AUTO   R2}{;   NL}	



NGENABLE{SP}{ON   OFF}{;   NL}	
POLAR{SP}{POS   NEG}{;   NL}	
START{; NL}	
STOP{;   NL}	
TESTING {?}{;   NL}	0:TEST END,1:TESTING
	ON:START
	TEST,OFF:STOP TEST
	TYPE1&2 TEST
	END,AUTO ECHO
BATT:TEST {SP} {ON   OFF}{;   NL}	"OK,XXXXX" XXXXX:AH
	TYPE3~5 TEST
	END,AUTO ECHO
	"OK,XXXXX"
	XXXXX:DVM

# System command

### Table: SYSTEM COMMAND SUMMARY

COMMAND	NOTE	RETURN
RECALL {SP} {m }{;   NL}	m=1~150, m:STATE	
STORE {SP} {m }{;   NL}	m=1~150 m:STATE	
REMOTE {;   NL}	RS232/USB/LAN command	
LOCAL{; NL}	RS232/USB/LAN command	
NAME {?} {;   NL}		"XXXXX"



#### Measure command

### Table: MEASURE COMMAND SUMMARY

COMMAND	RETURN
MEAS: CURR {?}{;   NL}	###.###
MEAS: VOLT {?}{;   NL}	###.####
MEAS: POW {?}{;   NL}	###.###
MEAS: VC {?}{;   NL}	###.####,###.###

Remark

1. Current engineering unit: A

2. Voltage engineering unit: V

3. Resistance engineering unit:  $\Omega$ 

4. Period engineering unit: mS

5. Slew-rate engineering unit: A/uS

6. Power engineering unit: W

### **AUTO SEQUENCE**

## Table: Auto sequence command list

1		
AUTO SEQUENCE SET COMMAND	NOTE	RETURN
FILE {SP} {n}{;   NL}	n=1~9	1~9
STEP {SP} {n} {;   NL}	n=1~16	1~16
TOTSTEP {SP} {n}{;   NL}	Total step n=1~16	1~16
SB {SP} {n} {;   NL}	m=1~150 m:STATE	
TIME {SP} {NR2} {;   NL}	100~9999(ms)	100~9999(ms)
SAVE {;   NL}	Save "File n" data	
REPEAT {SP} {n} {;   NL}	n=0~9999	0~9999
RUN {SP} {F} {n} {;   NL}	n=1~9	AUTO REPLY "PASS" or "FAIL:XX" (XX=NG STEP)



## **COMPLEX TYPE FORMAT**

Table: Communication Interface programming setting command summary

SETTING COMMAND SUMMARY  [PRESet:] RISE{SP}{NR2}{; NL}  A/us  [PRESet:] FALL{SP}{; NL}  [PRESet:] FALL{SP}{; NL}  [PRESet:] PERD:HIGH LOW{SP}{NR2; NL}  [PRESet:] LDONv{SP}{NR2}{; NL}  [PRESet:] LDOFfv{SP}{NR2}{; NL}  [PRESet:] LDOFfv{SP}{NR2}{; NL}  [PRESet:] C CURR:{HIGH LOW}{SP}{NR2; NL}  [PRESet:] CP:{HIGH LOW}{SP}{NR2}{; NL}  [PRESet:] CR   RES:{HIGH LOW}{SP}{NR2}{; NL}  [PRESet:] CV   VOLT:{HIGH LOW}{SP}{NR2}{; NL}  [PRESet:] COP:START {SP} {NR2}{; NL}  [PRESet:] OCP:START {SP} {NR2}{; NL}  [PRESet:] OCP:START {SP} {NR2}{; NL}  [PRESet:] OCP:STOP {SP} {NR2}{; NL}  [PRESet:] OPP:START {SP} {NR2}{; NL}  [PRESet:] OPP:START {SP} {NR2}{; NL}  [PRESet:] OPP:START {SP} {NR2}{; NL}  [PRESet:] OPP:STOP {SP} {NR2}{; NL}  [PRESet:] OPP:STOP {SP} {NR2}{; NL}  [PRESet:] STIME {SP} {NR2}{; NL}  [PRESet:] STIME {SP} {NR2}{; NL}  [PRESet:] BATT:TYPE {SP}{n}{; NL}  [PRESet:]BATT:TYPE {SP}{NR2}{; NL}  [PRESet:]BATT:CURR{SP}{NR2}{; NL}  [PRESet:]BATT:CURR{SP}{NR2}{; NL}  [PRESet:]BATT:POWER{SP}{NR2}{; NL}  [PRESet:]BATT:THME{SP}{NR2}{; NL}  [PRESet:]BATT:TIME{SP}{NR2}{; NL}  [PRESET:]BATT:TIME{SP}{NR2}{NL2}  [PRESET:]BATT:TIME{SP}{NR2}{; NL2}  [PRESET:]BATT:TIME{SP}	Summary	
[PRESet:] FALL{SP}{; NL} [PRESet:]PERI   PERD:HIGH   LOW{SP}{NR2; NL} [PRESet:] LDONv{SP}{NR2}{; NL} [PRESet:] LDOFfv{SP}{NR2}{; NL} [PRESet:] LDOFfv{SP}{NR2}{; NL} [PRESet:] CC   CURR:{HIGH   LOW}{SP}{NR2; NL} [PRESet:] CP:{HIGH   LOW}{SP}{NR2}{; NL} [PRESet:] CR   RES:{HIGH   LOW}{SP}{NR2}{; NL} [PRESet:] CV   VOLT:{HIGH   LOW}{SP}{NR2} {; NL} [PRESet:] TCONFIG{SP}{NORMAL   OCP   OPP   SH ORT}{; NL} [PRESet:] OCP:START {SP} {NR2}{; NL} [PRESet:] OCP:STOP {SP} {NR2}{; NL} [PRESet:] OCP:STOP {SP} {NR2}{; NL} [PRESet:] OPP:START {SP} {NR2}{; NL} [PRESet:] OPP:START {SP} {NR2}{; NL} [PRESet:] OPP:START {SP} {NR2}{; NL} [PRESet:] OPP:STOP {SP} {NR2}{; NL} [PRESet:] OPP:STOP {SP} {NR2}{; NL} [PRESet:] STIME {SP} {NR2}{; NL} [PRESet:] STIME {SP} {NR2}{; NL} [PRESet:] MPPTIME {SP}n{; NL} [PRESet:] BATT:TYPE {SP}{NR2}{; NL} [PRESet:]BATT:CURR{SP}{NR2}{; NL} [PRESet:]BATT:CURR{SP}{NR2}{NL2}{NL} [PRESet:]BATT:POWER{SP}{NR2}{NL2}{NL} [PRESet:]BATT:POWER{SP}{NR2}{NL2}{NL}	SETTING COMMAND SUMMARY	REMARK
[PRESet:]PERI   PERD:HIGH   LOW \ SP \ NR2;   NL \ [PRESet:] LDONv \ SP \ NR2 \ \ \ \ \ \ NR2 \ \ \ \ \ \ \ \ NR2 \ \ \ \ \ \ \ \ \ \ PRESet:] LDOFfv \ SP \ \ NR2 \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	[PRESet:] RISE{SP}{NR2}{; NL}	A/us
[PRESet:] LDONv{SP}{NR2}{;   NL} [PRESet:] LDOFfv{SP}{NR2}{;   NL} [PRESet:] CC   CURR:{HIGH   LOW}{SP}{NR2;   NL} [PRESet:] CP:{HIGH   LOW}{SP}{NR2}{;   NL} [PRESet:] CR   RES:{HIGH   LOW}{SP}{NR2}{;   NL} [PRESet:] CV   VOLT:{HIGH   LOW}{SP}{NR2}{;   NL} [PRESet:] CV   VOLT:{HIGH   LOW}{SP}{NR2}{;   NL} [PRESet:] TCONFIG{SP}{NORMAL   OCP   OPP   SH ORT}{;   NL} [PRESet:] OCP:START {SP} {NR2}{;   NL} [PRESet:] OCP:STOP {SP} {NR2}{;   NL} [PRESet:] OCP:STOP {SP} {NR2}{;   NL} [PRESet:] OPP:START {SP} {NR2}{;   NL} [PRESet:] OPP:START {SP} {NR2}{;   NL} [PRESet:] OPP:STOP {SP} {NR2}{;   NL} [PRESet:] OPP:STOP {SP} {NR2}{;   NL} [PRESet:] STIME {SP} {NR2}{;   NL} [PRESet:] MPPTIME {SP}{NR2}{;   NL} [PRESet:] BATT:TYPE {SP}{n}{;   NL} [PRESet:]BATT:UVP{SP}{NR2}{;   NL} [PRESet:]BATT:CURR{SP}{NR2}{NL} [PRESet:]BATT:POWER{SP}{NR2}{NL} [PRESet:]BATT:POWER{SP}{NR2}{NL} [PRESet:]BATT:POWER{SP}{NR2}{NL}	[PRESet:] FALL{SP}{;   NL}	A/us
[PRESet:] LDOFfv{SP}{NR2}{; NL}  [PRESet:] CC   CURR:{HIGH   LOW}{SP}{NR2; NL}  [PRESet:] CP:{HIGH   LOW}{SP}{NR2}{; NL}  [PRESet:] CR   RES:{HIGH   LOW}{SP}{NR2}{; NL}  [PRESet:] CV   VOLT:{HIGH   LOW}{SP}{NR2}{; NL}  [PRESet:] CV   VOLT:{HIGH   LOW}{SP}{NR2}{; NL}  [PRESet:] TCONFIG{SP}{NORMAL   OCP   OPP   SH  ORT}{; NL}  [PRESet:] OCP:START {SP} {NR2}{; NL}  [PRESet:] OCP:STEP {SP} {NR2}{; NL}  [PRESet:] OCP:STOP {SP} {NR2}{; NL}  [PRESet:] OPP:STOP {SP} {NR2}{; NL}  [PRESet:] OPP:START {SP} {NR2}{; NL}  [PRESet:] OPP:STEP {SP} {NR2}{; NL}  [PRESet:] OPP:STOP {SP} {NR2}{; NL}  [PRESet:] STIME {SP} {NR2}{; NL}  [PRESet:] MPPTIME {SP}n{; NL}  [PRESet:] MPPTIME {SP}n{; NL}  [PRESet:] BATT:TYPE {SP}{NR2}{; NL}  [PRESet:] BATT:CURR{SP}{NR2}{; NL}  [PRESet:] BATT:CURR{SP}{NR2}{NR2}{NL}  [PRESet:] BATT:POWER{SP}{NR2}{NL}  [PRESet:] BATT:POWER{SP}{NR2}{NL}  [PRESet:] BATT:POWER{SP}{NR2}{NL}	[PRESet:]PERI   PERD:HIGH   LOW{SP}{NR2;   NL}	
[PRESet:]CC CURR:{HIGH LOW}{SP}{NR2; NL} [PRESet:] CP:{HIGH LOW}{SP}{NR2}{; NL} [PRESet:] CR RES:{HIGH LOW}{SP}{NR2}{; NL} [PRESet:] CV VOLT:{HIGH LOW}{SP}{NR2} {; NL} [PRESet:] CV VOLT:{HIGH LOW}{SP}{NR2} {; NL} [PRESet:]TCONFIG{SP}{NORMAL OCP OPP SH ORT}{; NL} [PRESet:] OCP:START {SP} {NR2}{; NL} [PRESet:] OCP:STEP {SP} {NR2}{; NL} [PRESet:] OCP:STOP {SP} {NR2}{; NL} [PRESet:] OPP:STOP {SP} {NR2}{; NL} [PRESet:] OPP:START {SP} {NR2}{; NL} [PRESet:] OPP:STEP {SP} {NR2}{; NL} [PRESet:] OPP:STOP {SP} {NR2}{; NL} [PRESet:] OPP:STOP {SP} {NR2}{; NL} [PRESet:] MPPTIME {SP} {NR2}{; NL} [PRESet:] BATT:TYPE {SP}{N}{; NL} [PRESet:] BATT:TYPE {SP}{NR2}{; NL} [PRESet:] BATT:CURR{SP}{NR2}{; NL} [PRESet:] BATT:CURR{SP}{NR2}{NR2}{NL} [PRESet:]BATT:POWER{SP}{NR2}{NL} [PRESet:]BATT:POWER{SP}{NR2}{NL} [PRESet:]BATT:POWER{SP}{NR2}{NL}	[PRESet:] LDONv{SP}{NR2}{;   NL}	
[PRESet:] CP:{HIGH   LOW}{SP}{NR2}{;   NL}  [PRESet:] CR   RES:{HIGH   LOW}{SP}{NR2}{;   NL}  [PRESet:] CV   VOLT:{HIGH   LOW}{SP}{NR2} {;   NL}  [PRESet:] CV   VOLT:{HIGH   LOW}{SP}{NR2} {;   NL}  [PRESet:] TCONFIG{SP}{NORMAL   OCP   OPP   SH  ORT}{;   NL}  [PRESet:] OCP:START {SP} {NR2}{;   NL}  [PRESet:] OCP:STEP {SP} {NR2}{;   NL}  [PRESet:] OCP:STOP {SP} {NR2}{;   NL}  [PRESet:] OPP:START {SP} {NR2}{;   NL}  [PRESet:] OPP:START {SP} {NR2}{;   NL}  [PRESet:] OPP:STEP {SP} {NR2}{;   NL}  [PRESet:] OPP:STOP {SP} {NR2}{;   NL}  [PRESet:] STIME {SP} {NR2}{;   NL}  [PRESet:] MPPTIME {SP}n{;   NL}  [PRESet:] MPPTIME {SP}n{;   NL}  [PRESet:]BATT:TYPE {SP}{n}{;   NL}  [PRESet:]BATT:UVP{SP}{NR2}{;   NL}  [PRESet:]BATT:CURR{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}	[PRESet:] LDOFfv{SP}{NR2}{; NL}	
[PRESet:] CR   RES:{HIGH   LOW} {SP}{NR2} {;   NL}  [PRESet:] CV   VOLT:{HIGH   LOW} {SP}{NR2} {;   NL}  [PRESet:] TCONFIG{SP}{NORMAL   OCP   OPP   SH ORT} {;   NL}  [PRESet:] OCP:START {SP} {NR2} {;   NL}  [PRESet:] OCP:STEP {SP} {NR2} {;   NL}  [PRESet:] OCP:STOP {SP} {NR2} {;   NL}  [PRESet:] OPP:START {SP} {NR2} {;   NL}  [PRESet:] OPP:START {SP} {NR2} {;   NL}  [PRESet:] OPP:STEP {SP} {NR2} {;   NL}  [PRESet:] OPP:STOP {SP} {NR2} {;   NL}  [PRESet:] OPP:STOP {SP} {NR2} {;   NL}  [PRESet:] STIME {SP} {NR2} {;   NL}  [PRESet:] MPPTIME {SP} {NR2} {;   NL}  [PRESet:] MPPTIME {SP} {NR2} {;   NL}  [PRESet:]BATT:TYPE {SP} {NR2} {;   NL}  [PRESet:]BATT:UVP{SP} {NR2} {;   NL}  [PRESet:]BATT:CURR{SP}{NR2} {;   NL}  [PRESet:]BATT:POWER{SP}{NR2} {NL}  [PRESet:]BATT:POWER{SP}{NR2} {NL}  [PRESet:]BATT:POWER{SP}{NR2} {NL}	[PRESet:]CC   CURR:{HIGH   LOW}{SP}{NR2;   NL}	
[PRESet:] CV   VOLT:{HIGH   LOW}{SP}{NR2} {;   NL} [PRESet:]TCONFIG{SP}{NORMAL   OCP   OPP   SH ORT}{;   NL} [PRESet:] OCP:START {SP} {NR2}{;   NL} [PRESet:] OCP:STEP {SP} {NR2}{;   NL} [PRESet:] OCP:STOP {SP} {NR2}{;   NL} [PRESet:] OCP:STOP {SP} {NR2}{;   NL} [PRESet:] OCP:START {SP} {NR2}{;   NL} [PRESet:] OCP:START {SP} {NR2}{;   NL} [PRESet:] OCP:START {SP} {NR2}{;   NL} [PRESet:] OCP:STOP {SP} {NR2}{;   NL} [PRESet:] OCP:STOP {SP} {NR2}{;   NL} [PRESet:] STIME {SP} {NR2}{;   NL}  [PRESet:] MPPTIME {SP} {NR2}{;   NL}  [PRESet:] BATT:TYPE {SP}{n}{;   NL}  [PRESet:] BATT:UVP{SP}{NR2}{;   NL}  [PRESet:] BATT:CURR{SP}{NR2}{NL}  [PRESet:] BATT:POWER{SP}{NR2}{NL}  [PRESet:] BATT:POWER{SP}{NR2}{NL}  [PRESet:] BATT:POWER{SP}{NR2}{NL}  [NL]	[PRESet:] CP:{HIGH LOW}{SP}{NR2}{; NL}	
{; NL} [PRESet:]TCONFIG{SP}{NORMAL OCP OPP SH ORT}{; NL} [PRESet:] OCP:START {SP} {NR2}{; NL} [PRESet:] OCP:STEP {SP} {NR2}{; NL} [PRESet:] OCP:STOP {SP} {NR2}{; NL} [PRESet:] VTH {SP} {NR2}{; NL} [PRESet:] OPP:START {SP} {NR2}{; NL} [PRESet:] OPP:START {SP} {NR2}{; NL} [PRESet:] OPP:STEP {SP} {NR2}{; NL} [PRESet:] OPP:STOP {SP} {NR2}{; NL} [PRESet:] STIME {SP} {NR2}{; NL} [PRESet:] STIME {SP} {NR2}{; NL}  [PRESet:] MPPTIME {SP}n{; NL}  SET MPPT RECORD TIME n=1000~60000 mS [PRESet:]BATT:TYPE {SP}{n}{; NL}  [PRESet:]BATT:UVP{SP}{NR2}{; NL}  Unit:V  [PRESet:]BATT:CURR{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}	$[PRESet:] \ CR \   \ RES: \{HIGH \   \ LOW\} \{SP\} \{NR2\} \{; \   \ NL\}$	
ORT}{;   NL}  [PRESet:] OCP:START {SP} {NR2}{;   NL}  [PRESet:] OCP:STEP {SP} {NR2}{;   NL}  [PRESet:] OCP:STOP {SP} {NR2}{;   NL}  [PRESet:] VTH {SP} {NR2}{;   NL}  [PRESet:] OPP:START {SP} {NR2}{;   NL}  [PRESet:] OPP:STEP {SP} {NR2}{;   NL}  [PRESet:] OPP:STOP {SP} {NR2}{;   NL}  [PRESet:] OPP:STOP {SP} {NR2}{;   NL}  [PRESet:] STIME {SP} {NR2}{;   NL}  [PRESet:] MPPTIME {SP}n{;   NL}  [PRESet:] MPPTIME {SP}n{;   NL}  [PRESet:]BATT:TYPE {SP}{n}{;   NL}  [PRESet:]BATT:UVP{SP}{NR2}{;   NL}  [PRESet:]BATT:CURR{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}		
[PRESet:] OCP:STEP {SP} {NR2}{;   NL}  [PRESet:] OCP:STOP {SP} {NR2}{;   NL}  [PRESet:] VTH {SP} {NR2}{;   NL}  [PRESet:] OPP:START {SP} {NR2}{;   NL}  [PRESet:] OPP:STEP {SP} {NR2}{;   NL}  [PRESet:] OPP:STOP {SP} {NR2}{;   NL}  [PRESet:] STIME {SP} {NR2}{;   NL}  [PRESet:] STIME {SP} {NR2}{;   NL}  [PRESet:] MPPTIME {SP}n{;   NL}  [PRESet:] MPPTIME {SP}n{;   NL}  [PRESet:]BATT:TYPE {SP}{n}{;   NL}  [PRESet:]BATT:UVP{SP}{NR2}{;   NL}  [PRESet:]BATT:CURR{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}		
[PRESet:] OCP:STOP {SP} {NR2}{;   NL}  [PRESet:] VTH {SP} {NR2}{;   NL}  [PRESet:] OPP:START {SP} {NR2}{;   NL}  [PRESet:] OPP:STEP {SP} {NR2}{;   NL}  [PRESet:] OPP:STOP {SP} {NR2}{;   NL}  [PRESet:] STIME {SP} {NR2}{;   NL}  [PRESet:] STIME {SP} {NR2}{;   NL}  SET MPPT RECORD  TIME  n=1000~60000 mS  [PRESet:]BATT:TYPE {SP}{n}{;   NL}  [PRESet:]BATT:UVP{SP}{NR2}{;   NL}  unit:V  [PRESet:]BATT:CURR{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}	[PRESet:] OCP:START {SP} {NR2}{;   NL}	
[PRESet:] VTH {SP} {NR2}{;   NL}  [PRESet:] OPP:START {SP} {NR2}{;   NL}  [PRESet:] OPP:STEP {SP} {NR2}{;   NL}  [PRESet:] OPP:STOP {SP} {NR2}{;   NL}  [PRESet:] STIME {SP} {NR2}{;   NL}  [PRESet:] STIME {SP} {NR2}{;   NL}  [PRESet:] MPPTIME {SP}n{;   NL}  [PRESet:] MPPTIME {SP}n{;   NL}  [PRESet:]BATT:TYPE {SP}{n}{;   NL}  [PRESet:]BATT:UVP{SP}{NR2}{;   NL}  [PRESet:]BATT:CURR{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}	[PRESet:] OCP:STEP {SP} {NR2}{;   NL}	
[PRESet:] OPP:START {SP} {NR2}{;  NL}  [PRESet:] OPP:STEP {SP} {NR2}{;  NL}  [PRESet:] OPP:STOP {SP} {NR2}{;  NL}  [PRESet:] STIME {SP} {NR2}{;  NL}  [PRESet:] STIME {SP} {NR2}{;  NL}  [PRESet:] MPPTIME {SP}n{;  NL}  [PRESet:]BATT:TYPE {SP}{n}{;  NL}  [PRESet:]BATT:UVP{SP}{NR2}{;  NL}  [PRESet:]BATT:CURR{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}	[PRESet:] OCP:STOP {SP} {NR2}{;   NL}	
[PRESet:] OPP:STEP {SP} {NR2}{;   NL}  [PRESet:] OPP:STOP {SP} {NR2}{;   NL}  [PRESet:] STIME {SP} {NR2}{;   NL}  [PRESet:] STIME {SP} {NR2}{;   NL}  [PRESet:] MPPTIME {SP}n{;   NL}  [PRESet:]BATT:TYPE {SP}{n}{;   NL}  [PRESet:]BATT:UVP{SP}{NR2}{;   NL}  [PRESet:]BATT:CURR{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}	[PRESet:] VTH {SP} {NR2}{;   NL}	
[PRESet:] OPP:STOP {SP} {NR2}{;   NL}  [PRESet:] STIME {SP} {NR2}{;   NL}  SET MPPT RECORD TIME [PRESet:] MPPTIME {SP}n{;   NL}  [PRESet:]BATT:TYPE {SP}{n}{;   NL}  [PRESet:]BATT:UVP{SP}{NR2}{;   NL}  [PRESet:]BATT:CURR{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}  [PRESet:]BATT:POWER{SP}{NR2}{NL}	[PRESet:] OPP:START {SP} {NR2}{;  NL}	
$[PRESet:] STIME \{SP\} \{NR2\}\{;   NL\} \\ SET MPPT RECORD \\ TIME \\ n=1000\sim60000 \text{ mS} \\ [PRESet:] BATT:TYPE \{SP\}\{n\}\{;   NL\} \\ [PRESet:] BATT:UVP\{SP\}\{NR2\}\{;   NL\} \\ [PRESet:] BATT:CURR\{SP\}\{NR2\}\{NL\} \\ [PRESet:] BATT:POWER\{SP\}\{NR2\}\{NL\} \\ [PRESet:] BATT:POWER\{SP\}\{NR2\}\{NL\} \\ [PRESet:] BATT:POWER\{SP\}\{NR2\}\{NL\} \\ [NL] \\ [NL] \\ [NL] \\ SET MPPT RECORD \\ n=1000\sim60000 \text{ mS} \\ n=1\sim5 \\ unit:V \\ -CC   CURR:HIGH\{SP\}\{NR2\}\{NL\} \\ [PRESet:] BATT:POWER\{SP\}\{NR2\}\{NL\} \\ [NL] \\ $	[PRESet:] OPP:STEP {SP} {NR2}{;   NL}	
$[PRESet:] MPPTIME \{SP\}n\{;   NL\} \\ TIME \\ n=1000\sim60000 \text{ mS} \\ [PRESet:] BATT:TYPE \{SP\}\{n\}\{;   NL\} \\ [PRESet:] BATT:UVP\{SP\}\{NR2\}\{;   NL\} \\ [PRESet:] BATT:CURR\{SP\}\{NR2\}\{NL\} \\ [PRESet:] BATT:POWER\{SP\}\{NR2\}\{NL\} \\ [PRESet:] BATT:POWER\{SP\}\{NR2\}\{NL\} \\ [PRESet:] BATT:POWER\{SP\}\{NR2\}\{NL\} \\ [NL]$	[PRESet:] OPP:STOP {SP} {NR2}{;   NL}	
$[PRESet:] MPPTIME \{SP\}n\{;   NL\} \\ n=1000\sim60000 \ mS \\ [PRESet:] BATT:TYPE \{SP\}\{n\}\{;   NL\} \\ [PRESet:] BATT:UVP\{SP\}\{NR2\}\{;   NL\} \\ [PRESet:] BATT:CURR\{SP\}\{NR2\}\{NL\} \\ [PRESet:] BATT:POWER\{SP\}\{NR2\}\{NL\} \\ [PRESet:] BATT:POWER\{SP\}\{NR2\}\{NL\} \\ [NL] $	[PRESet:] STIME {SP} {NR2}{;   NL}	
	[PRESet:] MPPTIME {SP}n{;   NL}	TIME
	[PRESet:]BATT:TYPE {SP}{n}{: NL}	
$[PRESet:]BATT:CURR\{SP\}\{NR2\}\{NL\} \\ = CC \mid CURR:HIGH\{SP\}\{NR2\}\{NL\} \\ [PRESet:]BATT:POWER\{SP\}\{NR2\}\{NL\} \\ = CP:HIGH\{SP\}\{NR2\}\{NL\} \\ \{NL\} \\ = CP:HIGH\{SP\}\{NR2\}\{NL\} \\ = CP:HIGH\{SP\}\{NR2\}\{NR2\}\{NL\} \\ = CP:HIGH\{SP\}\{NR2\}\{NR2\}\{NL\} \\ = CP:HIGH\{SP\}\{NR2\}\{NR2\}\{NR2\}\{NR2\} \\ = CP:HIGH\{SP\}\{NR2\}\{NR2\}\{NR2\} \\ = CP:HIGH\{SP\}\{NR2\}\{NR2\}\{NR2\} \\ = CP:HIGH\{SP\}\{NR2\}\{NR2\}\{NR2\} \\ = CP:HIGH\{SP\}\{NR2\}\{NR2\} \\ = CP:HIGH\{SP\}\{NR2\}\{NR2\}\{NR2\} \\ = CP:HIGH\{SP\}\{NR2\}\{NR2\} \\ = CP:HIGH\{SP\}\{NR2\} \\ = CP:HIGH\{SP\}\{NR2\} \\ = CP:HIGH\{SP\}\{NR2\} \\ = CP:HIGH\{SP\}\{N$	1 1 1 1 1 1	-
[PRESET:]DATT:POWER(SP){INR2}{INL} {NL}		=CC   CURR:HIGH{S
[PRESet:]BATT:TIME{SP}{n}{;   NL } 0~99999,0=OFF	[PRESet:]BATT:POWER{SP}{NR2}{NL}	
	[PRESet:]BATT:TIME{SP}{n}{; NL}	0~99999,0=OFF
[PRESet:]BATT:AH{SP}{NR2}{NL} 0,0.1~19999.9,0=OFF	[PRESet:]BATT:AH{SP}{NR2}{NL}	0,0.1~19999.9 ,0=OFF
[PRESet:]BATT:WH{SP}{NR2}{NL} 0,0.1~19999.9,0=OFF	[PRESet:]BATT:WH{SP}{NR2}{NL}	0,0.1~19999.9 ,0=OFF



[PRESet:]BATT:TEST{SP}{ON   OFF}	TEST ON/OFF
[PRESet:]BATT:STEP{SP}{n}{; NL}	Cycle Life TEST: n=1~3,TYPE5:n=1~9
[PRESet:]BATT:CCH{n}{SP}{NR2}{; NL}	Cycle Life TEST CC:HIGH level, n=1~3
[PRESet:]BATT:CCL{n}{SP}{NR2}{;  NL}	Cycle Life TEST CC:LOW level, n=1~3
[PRESet:]BATT:TH{n}{SP}{NR2}{; NL}	Cycle Life TEST Thigh(unit:ms), n=1~3
$[PRESet:]BATT:TL\{n\}\{SP\}\{NR2\}\{; NL\}$	Cycle Life TEST Tlow (unit:ms), n=1~3
[PRESet:]BATT:CYCLE{n}{SP}{NR1}{; NL}	Cycle Life TEST:1~2000, n=1~3
[PRESet:]BATT:DYN{SP}{ON   OFF}	Cycle Life TEST ON/OFF
$[PRESet:]BATT:CC\{n\}\{SP\}\{NR2\}\{; NL\}$	Ramp Current, n=0~9
[PRESet:]BATT:CV{n}{SP}{NR2}{NL}	Ramp Voltage, n=0~9
[PRESet:]BATT:DTIME{n}{SP}{NR1}{; NL}	Ramp Delta time (T1~T9:0~6000sec), n=0~9
[PRESet:]BATT:REPEAT {SP} {n}{; NL}	Cycle Life TEST / Ramp Repeat times:0~9999
[PRESet:]BATT:RAMP:CC{SP}{ON   OFF}	RAMP CC TEST ON/OFF
[PRESet:]BATT:RAMP:CV{SP}{ON   OFF}	RAMP CV TEST ON/OFF
[PRESet : ]SURGE: SURI {NR2}{;   NL}	
[PRESet : ]SURGE: NORI {NR2}{;   NL}	
[PRESet : ]SURGE: TIME {NR2}{;   NL}	SURGE TIME:10~1000ms
[PRESet : ]SURGE: STEP {SP}{n} {;   NL}	n=1~5
[PRESet : ]SURGE {ON   OFF}{;   NL}	ON:RUN SURGE,OFF:STOP
[PRESet:]CPRSP{SP}{n}{; NL}	
$[PRESet:]AVG\{SP\}\{n\}\{; NL\}$	



Table: Communication Interface programming query command summary



Table: Communication Interface programming limit command summary

LIMIT	RETURN
LIMit:CURRent:{HIGH   LOW}{SP}{NR2}{;   NL}	
LIMit:CURRent:{ HIGH   LOW }{?}{;   NL}	###.####
IH   IL{SP}{NR2}{;   NL}	
IH IL{?}{; NL}	
LIMit:POWer:{HIGH   LOW}{SP}{NR2}{;   NL}	
LIMit:POWer:{HIGH LOW}{?}{; NL}	###.####
WH WL{SP}{NR2}{; NL}	
WH WL{?}{; NL}	###.###
LIMit:VOLTage:{HIGH   LOW}{SP}{NR2}{;   NL}	
LIMit: VOLTage:{HIGH LOW}{?}{; NL}	###.####
VH VL{SP}{NR2}{; NL}	
VH VL {?}{; NL}	###.###
SVH SVL{SP}{NR2}{; NL}	
SVH SVL{?}{; NL}	###.####
[LIMit:]ADDCV:VOLTage{SP}{NR2}{;   NL}	
[LIMit:]ADDCV: VOLTage{?}{; NL}	###.###
[LIMit:]ADDCV{SP}{ON   OFF}{;   NL}	

Table: STAGE COMMAND SUMMARY

STAGE COMMAND	REMARK
[STATe:] LOAD{SP}{ON   OFF}{;   NL}	
[STATe:] LOAD{?}{; NL}	0:OFF 1:ON
[STATe:] MODE{SP} {CC   CR   CV   CP} {;NL}	
[STATe:] MODE{?} {;   NL}	0   1   2   3:CC   CR   CV   CP
[STATe:] SHORt{SP} {ON   OFF} {;   NL}	
[STATe:] SHORt{?} {;   NL}	0:OFF 1:ON
[STATe:] PRESet{SP} {ON   OFF} {;   NL}	
[STATe:] PRESet{?} {;   NL}	0:OFF 1:ON
[STATe:] SENSe{SP} {ON   OFF   AUTO } {;   NL}	
[STATe:] SENSe{?} {;   NL}	0:OFF/AUTO 1:ON
[STATe:] LEVEI{SP} { LOW   HIGH} {;   NL}	
[STATe:] LEVEI{?} {;   NL}	0:LOW 1:HIGH
[STATe:] LEV{SP} {LOW   HIGH} {;   NL}	
[STATe:] LEV{?} {;   NL}	0:LOW 1:HIGH



[STATe:] DYNamic {SP} {ON   OFF} {;   NL}	
[STATe:] DYNamic {?} {;   NL}	0:OFF 1:ON
[STATe:] CLR{;   NL}	
[STATe:] ERRor {?}{; NL}	
[STATe:] NO{SP}GOOD {?}{;   NL}	0:GO 1:NG
[STATe:] NG {?}{; NL}	0:GO 1:NG
[STATe:] PROTect {?}{; NL}	
[STATe:] CC{SP}{AUTO   R2}{;   NL}	
[STATe:] NGENABLE{SP}{ON OFF}{; NL}	
[STATe:]POLAR{SP}{POS NEG}{; NL}	
[STATe:]START{;   NL}	
[STATe:]STOP{;   NL}	
[STATe:]TESTING {?}{; NL}	0:TEST END,1:TESTING

### Table: SYSTEM COMMAND SUMMARY

COMMAND	NOTE	RETURN
[SYStem:]RECall {SP} {m }{;   NL}	m=1~150	
[SYStem:]STORe {SP} {m }{;   NL}	m=1~150	
[SYStem:]REMOTE {;   NL}	RS232/USB/LAN command	
[SYStem:]LOCAL{;   NL}	RS232/USB/LAN command	
[SYStem:]NAME {?} {;   NL}		"XXXXX"

### Table: MEASURE COMMAND SUMMARY

COMMAND	RETURN
MEASure:CURRent {?}{;   NL}	###.###
MEASure: VOLTage {?}{;   NL}	###.###
MEASure:POWer {?}{;   NL}	###.###
MEASure:VC{?}{;   NL}	###.###,###.####



Remark	1.	Current engineering unit: A
	2.	Voltage engineering unit: V
	3.	Resistance engineering unit: $\Omega$
	4.	Period engineering unit: mS
	5.	Slew-rate engineering unit: A/uS
	6.	Power engineering unit: W

## Table: AUTO SEQUENCE COMMAND

AUTO SEQUENCE COMMAND	NOTE	RETURN
FILE {SP} {n}{;   NL}	n=1~9	1~9
STEP {SP} {n} {;   NL}	n=1~16	1~16
TOTSTEP {SP} {n}{;   NL}	Total step n=1~16	1~16
SB {SP} {m} {;   NL}	m=1~150 m:STATE	
TIME {SP} {NR2} {;   NL}	100~9999 (ms)	100~9999 (ms)
SAVE {;   NL}	Save "File n" data	
REPEAT {SP} {n} {;   NL}	n=0~9999	0~9999
RUN {SP} {F} {n} {;   NL}	n=1~9	AUTO REPLY "PASS" or "FAIL:XX" (XX=NG STEP)



# Command Syntax

# The description of abbreviation

Command Tree	SP: Space, the ASCII code is 20 Hexadecimal.
	;:Semicolon, Program line terminator, the ASCII code is OA Hexadecimal.
	NL:New line, Program line terminator, the ASCII code is OA Hexadecimal.
	NR2:Digits with decimal point. It can be accepted in the range and format of ###.####.
	For Example:
	30.12345, 5.0
	The description of GPIB programming command syntax.

# Communication Interface programming command syntax description

{}	The contents of the {} symbol must be used as a part or data of the GPIB command, it cannot be omitted.
[]	The contents of the [] symbol indicts the command can be used or not. It depends on the testing application.



This symbol means option. For example "LOW | HIGH" means it can only use LOW or HIGH as the command, it can choose only one as the setting command.

Terminator: You have to send the program line terminator character after send the GPIB command, the available command terminator characters which can be accepted in PEL-5000C series mainframe is listed in table below

LF		
LF WITH EOI		
CR , LF		
CR , LF WITH EOI		

Semicolon ";":The semicolon ";"is a back-up command, the semicolon allows you to combine command statement on one line to create command message.



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## **PRESET Commands**

### Set RISE **→** Query Description Set and read the RISE SLEW-RATE. The definition of RISE SLEW-RATE is load level change or dynamic load can be programmed of RISE and FALL are completely independent. The value of RISE has to be included the number of the decimal point, otherwise the command will not be available. The least significant number is the 3th behind the decimal point. PEL-5000C series will set to the maximum value of the model automatically when the set RISE is over the specification of Load. The unit is A/uS. [PRESet:]RISE{SP}{NR2}{;NL} Syntax **Query Syntax** [PRESet:]RISE{?}{;NL} Set ) FALL Query Set and read the linear current. Set and read the Description FALL SLEW-RATE The definition of FALL SLEW-RATE is load level change or dynamic load can be programmed of RISE and FALL are completely independent. PEL-5000C series will set to the maximum value of the model automatically when the

FALL which has been set is over the

specification of Load. The unit is A/uS.



Syntax Query Syntax	[PRESet:]FALL{SP}{;NL} [PRESet:]FALL{?}{;NL}
PERI or PERD	Set → Query
Description	<ul> <li>Set and read the TLOW and Thigh of DYNAMIC when loading.</li> <li>A period of loading waveform of DYNAMIC is combined by TLOW and THIGH.</li> <li>The value of TLOW and THIGH have to be included the number of the decimal point, otherwise the command will not be available.</li> <li>The least significant number is the 5th behind the decimal point.</li> <li>PEL-5000C Series will set the value of TLOW or THIGH automatically when the value which has been set is over the maximum of the Load.</li> <li>The unit is mS.</li> </ul>
Syntax	[PRESet:]PERI PERD:HIGH LOW{SP}{NR2}{; NL}
Query Syntax	[PRESet:]PERI PERD:HIGH LOW{?}{; NL}
LDONv	Set → Query
Description	Set and Read the voltage of LOAD ON This command is for setting the Load voltage value of LOAD ON.
Syntax	[PRESet:]LDONv{SP}{NR2}{; NL}
Query Syntax	[PRESet:]LDONv{?}{; NL}
LDOFfv	Set → —Query
Description	Set and read the voltage of LOAD OFF. This command is for setting the Load voltage value of LOAD OFF.



Syntax	[PRESet:]LDOFfv{SP}{NR2}{;NL}		
Query Syntax	[PRESet:]LDOFfv{?}{; NL}		
	(Set )→		
CURR: HIGH	LOW —Query		
Description	Set and read the current of HIGH   LOW. This command is for setting the required Load current. And this command must be followed the next notices:		
	• The required value of current must be included the number of the decimal point, otherwise the command will not be available.		
	• The least significant number is the 5th behind the decimal point.		
	<ul> <li>PEL-5000C Series will set the maximum value of current of the load automatically when the value which has been set is over the maximum of the load.</li> </ul>		
	<ul> <li>The value of LOW has to be smaller than HIGH.</li> </ul>		
	• The unit is A		
Syntax	[PRESet:]CC CURR:HIGH LOW{SP}{NR2}{; NL}		
Query Syntax	[PRESet:]CClCURR:HIGH LOW{?}{; NL}		
	(Set )→		
CP:{HIGH LO	W} —Query		
Description	Set and read the value of watt. This command is for setting the required value of watt, and the unit is W		
Syntax	[PRESet:]CP:{HIGH LOW}{SP}{NR2}{; NL}		
Query Syntax	[PRESet:]CP:{HIGH LOW}{?}{; NL}		



## CR|RES:{HIGH|LOW}



### Description

Set and read the value of resistance. This command is used for setting the required value of Load Resistance. And this command must be followed the next notices:

- The required value of resistance must be included the number of the decimal point, otherwise the command will not be available.
- The least significant number is the 3rd behind the decimal point.
- PEL-5000C Series will set to the maximum value of the model automatically when the value of Resistance which has been set is over the specification of load.
- The Resistance value which has been set of LOW has to be smaller than HIGH.
- The unit is  $\Omega$ .

Syntax Query Syntax [PRESet:]CR|RES:{HIGH|LOW}{SP}{NR2}{;|NL}
[PRESet:]CR|RES:{HIGH|LOW}{?}{;|NL}

# CV:{HIGH|LOW}



### Description

Set and Read the value of load voltage. This command is used for setting the required Load Voltage. And this command must be followed the next notices:

- The required value of resistance must be included the number of the decimal point, otherwise the command will not be available.
- The least significant number is the 5th behind the decimal point.
- PEL-5000C Series will set to the maximum value of the model automatically when the value of Voltage which has been set is over the



	<ul> <li>specification of load.</li> <li>The Voltage value which has been set of LOW has to be smaller than HIGH.</li> <li>The unit is voltage (V)</li> </ul>		
Syntax	[PRESet:]CV:{HIGH LOW}{SP}{NR2}{; NL}		
Query Syntax	[PRESet:]CV:{HIGH LOW}{?}{; NL}		
	(Set )→		
OCP:START	→ Query		
Description	Set and read the initial value of OCP test. This command is used for setting the required initial value (I-START) of OCP		
Syntax	[PRESet:]OCP:START{SP}{NR2}{; NL}		
Query Syntax	[PRESet:]OCP:START{?}{; NL}		
OCP:STEP	Set → Query		
Description	Set and read the increasing value of OCP test. This command is used for setting the increasing value (I-STEP) of OCP test.		
Syntax	[PRESet:]OCP:STEP{SP}{NR2}{; NL}		
Query Syntax	[PRESet:]OCP:STEP{?}{; NL}		
OCP:STOP	Set → —(Query)		
Description	Set and read the maximum value of OCP test. This command is used for setting the maximum value (I-STOP) of OCP		
Syntax	[PRESet:]OCP:STOP{SP}{NR2}{; NL}		
Query Syntax	[PRESet:]OCP:STOEP{?}{; NL}		



ОСР	→ Query
Description	Read OCP testing current. This command is used for reading OCP current.
Query Syntax	OCP{?}
VTH	Set → Query
Description	Set and read the maximum value of OCP test. This command is used for setting the maximum value (I-STOP) of OCP Set and read the value of the threshold voltage. This command is used for setting the Threshold Voltage. That is the OCP/OPP of this Load model when the output voltage of appliance is lower or equaled to the VTH.
Syntax	[PRESet:]VTH{SP}{NR2}{; NL}
Query Syntax	[PRESet:]VTH{?}{; NL}
OPP:START	Set → Query
Description	Set and read the initial value of OPP test. This command is used for setting the required initial value (P-START) of OPP
Syntax	[PRESet:]VTH{SP}{NR2}{; NL}
Query Syntax	$[PRESet:]VTH\{?\}\{; NL\}$
OPP:STEP	Set → Query
Description	Set and read the increasing value of OPP test. This command is used for setting the increasing value (P-STEP) of OPP Test.



Syntax	[PRESet:]OPP:STEP{SP}{NR2}{; NL}		
Query Syntax	[PRESet:]OPP:STEP{?}{; NL}		
			Set →
OPP:STOP			Query
Description		ed for setting the	e of OPP test. This maximum value
Syntax	[PRESet:]OPP:ST	OP{SP}{NR2}{; N	IL}
Query Syntax	[PRESet:]OPP:ST	OEP{?}{; NL}	
	-		
OPP			→ Query
Description	Read OPP testing watt. This command is used for reading OPP watt.		
Query Syntax	OPP{?}		
			Set →
TCONFIG			Query
Description	Set and read the function of Dynamic test. There are four options of this command. Those are NORMAL mode, OCP test, OPP test and SHORT test.		
Syntax	[PRESet:] TONFIG {NORMAL OCP OVP OPP SHORT} {; NL}		
Query Syntax	[PRESet:] TONFIG {?} {; NL}		
Return Parameter			
	1	NORMAL	
	2	ОСР	
	3	OPP	
	4	SHORT	



STIME	Set → Query
Description	Set and read time of the short-circuit test. This command is used for setting time of the short-circuit test. If time set to 0, it means that have no the time limit and continue to be short -circuited. The unit is milli-second (ms)
Syntax	[PRESet:]STIME{SP}{NR2}{; NL}
Query Syntax	[PRESet:]STIME{?}{; NL}
MPPT	Set →
Description	MPPT(Maximum power point tracking) testing ON/OFF. This command is MPPT ON/OFF
Syntax	[PRESet:]MPPT{SP}ON OFF{; NL}
МРР	→ Query
Description	Read MPP max power data, readback" Voltmeter / Ammeter / PowerMeter."
Query Syntax	[PRESet:]MPP{?}{; NL}
MPPTIME	Set → Query
Description	Set and read MPPTIME (Maximum power point tracking time). This command is MPPTIME maximum power point tracking time n=1000ms~60000ms
Syntax	[PRESet:] MPPTIME{SP}{n}{; NL} [PRESet:] MPPTIME{?}{; NL}



Example	1. Set MPPTIME 5000ms (maximum power point, read once every 5 seconds).
	2. Set MPPT ON command.
	3. Set MPP? command, readback "Voltmeter / Ammeter / PowerMeter."
	4. Set MPP OFF command.
BATT: UVP	
Description	Set under voltage protect. This command is to set battery discharge test mode Disch CC or Disch CP under Voltage Protect voltage, unit is voltage (V).
Syntax	[PRESet:] BATT:UVP {SP}{NR2}{; NL}
BATT:TIME	<u>Set</u> →
Description	Set battery discharge test mode time. This command is to set battery discharge test mode Disch CC or Disch CP discharge test time, n=1~99999, unit is second (S).
Syntax	[PRESet:]BATT:TIME{SP}{n}{; NL}
BATT:STEP	Set →
Description	Set battery discharge test mode step. This command is to set battery discharge test mode Cycle Life test mode or RAMP Mode test mode, Cycle Life test mode setting step n=1~3, RAMP Mode test mode setting step n=1~9.
Syntax	[PRESet:]BATT:STEP{SP}{n}{; NL}



BATT:CCH	<u>Set</u> →
Description	Set battery discharge test mode cycle life test mode level high current. This command is to set battery discharge test mode Cycle Life test mode level high current value, n = 1~3, current value unit (A).
Syntax	[PRESet:]BATT:CCH{n}{SP}{NR2}{; NL}
BATT:CCL	Set →
Description	Set battery discharge test mode cycle life test mode level low current. This command is to set battery discharge test mode cycle life test mode level low current value, $n = 1 \sim 3$ , current is unit (A).
Syntax	[PRESet:]BATT:CCL{n}{SP}{NR2}{; NL}
BATT:TH	Set →
Description	Set battery discharge test mode Cycle Life test mode level high testing time. This command is to set battery discharge test mode Cycle Life test mode level high time value, n=1~3, time is unit millisecond(ms).
Syntax	[PRESet:]BATT:TH{n}{SP}{NR2}{; NL}
BATT:TL	Set →
Description	Set battery discharge test mode cycle life test mode level low testing time. This command is to set battery discharge test mode cycle life test mode level low time value, n=1~3, time is unit millisecond(ms).
Syntax	$[PRESet:]BATT:TL\{n\}\ \{SP\}\{NR2\}\{; NL\}$



BATT:CYCLE	Set →
Description	Set battery discharge test mode Cycle Life test mode testing cycle. This command is to set battery discharge test mode Cycle Life test mode testing cycle, n=1~3, cycle range is 1~2000.
Syntax	$[PRESet:]BATT:CYCLE\{n\}\{SP\}\{NR1\}\{; NL\}$
BATT:CC	
Description	Set battery discharge test mode Ramp mode loading current. This command is to set battery discharge test mode Ramp mode loading current, n=1~9, current is unit (A).
Syntax	[PRESet:] BATT:CC{n} {SP}{NR2}{; NL}
BATT:DTIME	Set →
Description	Set battery discharge test mode Ramp mode time. This command is to set battery discharge test mode Ramp mode time, n=1~9, time range is 1 ~ 6000 second.
	Set battery discharge test mode Ramp mode time. This command is to set battery discharge test mode Ramp mode time, $n=1\sim9$ , time range is $1\sim6000$
Description	Set battery discharge test mode Ramp mode time. This command is to set battery discharge test mode Ramp mode time, $n=1\sim9$ , time range is $1\sim6000$ second.
Description  Syntax	Set battery discharge test mode Ramp mode time. This command is to set battery discharge test mode Ramp mode time, n=1~9, time range is 1 ~ 6000 second.  [PRESet:] BATT:DTIME{n} {SP}{NR1}{; NL}



SURGE:SURI	Set → Query
Description	Set and read surge current mode loading current value. This command is to set and read surge current mode testing loading value XXX.XXX (A) SURGE CURRENT.
Syntax	[PRESet:]SURGE:SURI{SP}{NR2}{; NL}
Query Syntax	[PRESet:]SURGE:SURI{?}{; NL}
SURGE:NORI	Set → Query
Description	Set and read surge mode normal current test loading current value. This command is to set and read normal current testing mode loading current value XXX.XXX (A) NORMAL CURRENT.
Syntax	[PRESet:]SURGE:NORI{SP}{NR2}{; NL}
Query Syntax	[PRESet:]SURGE:NORI{?}{; NL}
SURGE:TIME	Set → Query
Description	Set and read surge mode current testing time. This command is to set and read surge mode testing time, SURGE TIME:10~1000ms
Syntax	[PRESet:]SURGE:TIME{SP}{NR2}{; NL}
Query Syntax	[PRESet:]SURGE:TIME{?}{; NL}
SURGE:STEP	Set → Query
Description	Set and read surge mode is Diminishing current is to set value. This command is to set and read surge mode Diminishing current setting value, n=1~5
Syntax	[PRESet:]SURGE:STEP{SP}{NR2}{; NL}
Query Syntax	[PRESet:]SURGE:STEP{?}{; NL}



SURGE:ON C	)FF	Set → Query
Description	Set and read surge mode command is to set and re OFF, ON:RUN SURGE, (	ead surge mode ON or
Syntax Query Syntax	[PRESet:]SURGE:ON OFF [PRESet:]SURGE:SURGE{?	• •
CPRSP		Set →
Description		E. This command is to set Fast, 4: Slow, initial value
Syntax	[PRESet:]CPRSP{n}{; NL}	
AVG		Set ————————————————————————————————————
Description	Set and read voltage value vaqlue average times. The Vmeter/Ameter/Wmeter times, MEAS AvG 1~64 s	nis command is er setting measure average
Syntax	[PRESet:]AVG{SP}{NR2}{;	NL}
Query Syntax	$[PRESet:]AVG\{?\}\{; NL\}$	



# Limit Commands

[LIMit:]CURR	lent:{HIGH LOW} or IH IL	Set → Query		
Description	This command is to set the lower limit value of threshold current. When load sink current is lower than this lower limit value or higher than the upper limit value, NG indicating light will come on to indicate "NO GOOD".			
Syntax	$[{\sf LIMit}]: {\sf CURRent}: \{{\sf HIGH LOW}\} \{{\sf SP}\} \{{\sf NR2}\ \} \{;  {\sf NL}\}$			
	[IH IL]{SP}{NR2}{; NL}			
Query Syntax	[LIMit]:CURRent:{HIGH LOW}{	?}{; NL}		
	[IH IL}{?}{; NL}			
		Set →		
[LIMit:]POW	er:{HIGH LOW} or WH WL	→ Query		
Description	This command is to set the up value of threshold power (WA (WATT) is lower than this low higher than the upper limit valight will come on to indicate	ATT). When power ver limit value or alue, NG indicating		
Syntax	$[LIMit] : POWer : \{HIGH   LOW\} \{SF   FOWer : \mathsf$	P}{NR2 }{; NL}		
	$[WH WL]{SP}{NR2}{; NL}$			
Query Syntax	$[LIMit]: POWer: \{HIGH LOW\} \{?\} \{;  NL\}$			
	[WH WL}{?}{; NL}			
		Set →		
[LIMit:]VOLta	age:{HIGH LOW} or VH VL	→ Query		
Description	This command is to set the up value of threshold voltage. Whe lower than the lower limit valupper limit value, NG indication to indicate "NO GOOD".	hen input voltage is ue or higher than the		



Syntax	[LIMit]:VOLtage:{HIGH LOW}{SP}{NR2 }{; NL} [VH VL]{SP}{NR2}{; NL}			
Query Syntax	[LIMit]:VOLtage:{HIGH LOW}{?}{; NL} [VH VL}{?}{; NL}			
SVH SVL	Set → Query			
Description	This command is to set the upper/lower limit value of short current. When short current is lower than the lower limit value or higher than the upper limit value, NG indicating light will come on to indicate "NO GOOD".			
Syntax	[LIMit:]{SVH SVL}{SP}{NR2 }{;NL}			
Query Syntax	[LIMit:]{SVH SVL}{?}{;NL}			
	(Set )→			
	Set —			
[LIMit:]ADDC				
[LIMit:]ADDC		nd +CV,		
	Set and read CC+CV or CP+CV mode of Const Voltage setting. This command is used for set a read Constant Voltage setting, when set to CC- the of load like constant current status, until EU Voltage equal setting constant voltage, into a	and +CV, JT		
	Set and read CC+CV or CP+CV mode of Const Voltage setting. This command is used for set a read Constant Voltage setting, when set to CC-the of load like constant current status, until EV Voltage equal setting constant voltage, into a constant voltage mode.  This command is used for setting and read constant Voltage setting, when set to CP+CV, to f Load like constant power status, until EUT Voltage equal setting constant voltage, into a	and +CV, JT		
Description	Set and read CC+CV or CP+CV mode of Const Voltage setting. This command is used for set a read Constant Voltage setting, when set to CC-the of load like constant current status, until EV Voltage equal setting constant voltage, into a constant voltage mode.  This command is used for setting and read constant Voltage setting, when set to CP+CV, to f Load like constant power status, until EUT Voltage equal setting constant voltage, into a constant voltage mode.	and +CV, JT		



[LIMit:]ADDC	$V:VOLtage{SP}{ON OFF} \qquad \underbrace{Set} \longrightarrow$
Description	Start and stop CC+CV or CP+CV test mode. At that time in Constant current mode or constant power mode to perform CC + CV or CP + CV mode.
Syntax	$[LIMit:] ADDCV: VOLtage \{SP\} \{ON OFF\} \{; NL\}$



# STAGE commands

Set and read the status of Load

[STATe:]LOAD	{SP} {ON 0	OFF}			_	Set ) → Qu	→ ery)
Description	Set and read the status of sink current or not. This command is used for setting the status of sink current. When setting it to ON, the load is going to sink current from appliance. When setting it to OFF, the load would not act.						
Syntax	[STATe:]LO	AD{SP}{	о ис	FF}{;	NL}		
Query Syntax	[STATe:]LO	AD{?}{; N	IL}				
Parameter	0	ON					
	1	OFF					
[STATe:]MODE	{SP}{CC 0	CR CV C	P}		_	Set ) →Qu	ery)
Description	Set and read the mode of load. Load is acting under these four modes as the following table. When reading the loading operation mode, the return value $0 \mid 1 \mid 2 \mid 3 \mid$ are meant to be $CC \mid CR \mid CV \mid CP$						
Syntax	[STATe:]MODE{SP}{CC CR CV CP}{; NL}						
Query Syntax	[STATe:]MO				, .		
Module for each series	Mode (value) PEL-5000C		CC 0 V	CR 1 V	CV 2 V	CP 3 V	



[STATe:]SHO	Rt{SP}{O	N OFF}	Set → Query			
Description	short-cir	This command is for setting the load to make a short-circuit test. While setting for the ON, the V+, V- pin of load like short-circuit status.				
Syntax	[STATe:]	[STATe:]SHORt{SP}{ON OFF}{ ; NL}				
Query Syntax	[STATe:]	[STATe:]SHORt{?}{; NL}				
[STATe:]PRES	Set{SP}{O	N OFF}	Set → Query			
Description Set the left or right digit multi-function meter display the programming load level. This command is for select the left 5 digit LCD display to show current setting or DWM.			oad level. This eft 5 digit LCD display			
Pres ON: To select the LCD display to show current setting.						
	Pres OFF: To select the LCD Display is "DWN					
Syntax	[STATe:]I	[STATe:]PRESet{SP}{ON OFF}{; NL}				
Query Syntax	[STATe:]I	PRESet{?}{; NL}				
Parameter	0	OFF				
	1	ON				
[STATe:]SEN:	Se{SP}{OI	N OFF AUTO}	Set → Query			
Description	carried land for setting for setting for and setting for and setting for an area on a setting for an area on a setting for an area on the voltage for setting for	by the VSENSE or many the load voltage by VSENSE or INPU or ON, the voltage ing for OFF, the volor. In PEL-5000C Se AUTO. So, if setting is got and read to the setting of the polytage is got and read to the setting the setting is got and read to the setting	ge to read whether is not. This command is to read whether is JT Connector. When is got from VSENSE, tage is got from INPUT ries, the optional are g for AUTO, it means from VSENSE. But if no EENSE, the voltage will			



	be inputted from INPUT Connector.
Syntax	[STATe:]SENSe{SP}{ON OFF AUTO }{; NL}
Query Syntax	[STATe:]SENSe{?}{; NL}
Query Syntax	[STATe:]SENSe{?}{; NL}

[STATe:]LEVel{SP}{HIGH LOW} or	Set —
LEV{SP}{HIGH LOW}	→ Que

Description	Set and read the LOW and HIGH of load. LEV LOW is a low level value of current on CC mode. It is a low level value of resistance on CR mode. It is a low level value of voltage on CV mode. It is a low level value of power on CP mode.		
Syntax	[STATe:]LEVel{SP}{HIGH LOW }{; NL}		
	[STATe:]LEV{SP}{HIGH LOW}{ ; NL}		
Query Syntax	[STATe:]LEVel{?}{; NL}		
	[STATe:]LEV{?}{; NL}		
Parameter	0	0 LOW/A	
	1	ні <b>с</b> н/в	
Query Syntax	low level va [STATe:]LEV [STATe:]LEV [STATe:]LEV	alue of power on CP mode. el{SP}{HIGH LOW}{; NL} {SP}{HIGH LOW}{ ; NL} el{?}{; NL} {?}{; NL}	

[STATe:] DYN	lamic {SP}{ON OFF}	Set →
Description	Set and read whether the stat static of load	tus is dynamic or
	1. DYN ON, set for a DYNA	MIC Load
	2. DYN OFF, set for a STATIO	C Load
Syntax	[STATe:]DYNamic{SP}{ON OF	F}{; NL}
Query Syntax	[STATe:]DYNamic{?}{; NL}	



[STATe:]CLR		(Set )→
Description	during the clearing the ERR. After	rror flag of PEL-5000C Series which period of working. This command is for e contents in the register of PROT and implementation, the contents of these rs will be "0".
Syntax	[STATe:]CLR	R{; NL}
[STATe:]NG?		→ Query
Description	Series. Set of Set for "0"	ere have NG flag in this PEL-5000C command NG? To show the NG status. the LCD of NG (NO GOOD) will be t "1", the LCD will be lit.
Query Syntax	[STATe:]NG	{?}{; NL}
Return Parameter	0	GO
	1	NG
[STATe:]PROTe	ect?	→(Query)
Description	set in this F PROT? Mea 5000C. "1" "8" means correspond	ere have protection flag which had been PEL-5000C series.  ans the status of protection of PEL-means OPP occurred."4" means OVP. OCP. The table below shows the ling number of protection status use CLR to clear the register of PROT status
Query Syntax	[STATe:]PRC	OTect{?}{; NL}
	Bit 7 Bit 6 Bit 5 7 6 5	5 Bit 4 Bit 3 Bit 2 Bit1 Bit 0 4 3 2 1 0  Over Power Protection (OPP) Over Voltage Protection (OVP) Over Current Protection (OCP)



Register of PROT status	BIT ID bit 0 bit 1 bit 2 bit 3	BIT VALUE  0 = Off, 1 = Triggered  0 = Off, 1 = Triggered  0 = Off, 1 = Triggered  0 = Off, 1 = Triggered	Over Temperature Protection (OTP) Over Voltage Protection (OVP)
[STATe:]CCR{A	UTO	R2}	Set →
Description	to RA	NGE II. It will sw	NGE to be forced to switch vitch the RANGE position tting for AUTO Set R2 when
Syntax	[STAT	e:]CCR{AUTO R2}	{; NL}
[STATe:]NGEAI	BLE {	ON OFF}	Set →
Description	To se	t the function of N ER ON. When set	function enable or disable. NG judgment opens when tting for POWER OFF, the ent will not be implemented.
Syntax	[STAT	e:]NGEABLE{ON	OFF}{; NL}
[STATe:]POLAF	R{POS	S NEG}	Set →
Description	pole i voltag mean	s contrary or not. ge meter shows th	he voltage meter shows the Set the display of the he pole. If it shows POS that contrary. If the pole is NEG.
Syntax	[STAT	e:]POLAR {POS N	EG}{; NL}
[STATe:]START			Set →
Description	TEST	CONFIG (TCON	ent the test, and according to IFIG), the Load will start to imeters which are required



Syntax	[STATe:]START{; NL}	
[STATe:]STOP		Set →
Description	Set for load to stop the test	
Syntax	[STATe:]STOP{; NL}	



# System Commands

Set and Read the Status of PEL-5000C Series

[SYStem:]REG	Call{SP}m{,n}	Set →
Description		
Syntax	[SYStem:]RECall{SP}m{;	NL}
Example	RECALL 2	
	Recall the status of Load in the 2nd of the memo	ding which had been saved ry
[SYStem:]STC	ORe{SP}m{,n}	Set →
Description		ing to the Memory. This the status of Loading to the ~150
Syntax	[SYStem:]STORe{SP}m{;	NL}
Example	STORE 2	
	Save the status of loading the 2nd of memory.	ng which had been saved in
[SYStem:]NA	ME?	→ Query
Description	Read the model numbe for reading the model r module is operating, th "NULL", or it will be li	e display will be lit
Query Syntax	[SYStem:]NAME{?}{; NL	}



[SYStem:]RE	MOTE Set →
Description	Command to enter the REMOTE status (only for RS232). This command is for controlling the RS23
Syntax	[SYStem:]REMOTE{; NL}
[SYStem:]LC	CAL Set →
Description Command to exit the REMOTE status (only for RS232). This command is for finishing the RS23	
Syntax	[SYStem:]LOCAL{; NL}



## Measure Commands

Measure the actual current and voltage value of Load

MEASure:CURRent?		→ Query
Description		is loading from load. Read ent meters, and the unit is
Query Syntax	$MEASure{:}CURRent\{?\}\{;   New MEASure{:} \}$	IL}
MEASure:VO	LTage?	<b>→</b> Query
Description	O	is loading from load. Read ent meters, and the unit is
Query Syntax	MEASure:VOLTage{?}{; N	IL}
MEASure:PO	Wer?	<b>→</b> (Query)
Description	<u>*</u>	s loading from load. Read rent meters, and the unit is
Query Syntax	MEASure:POWer{?}{; NL	}



# APPLICATION

This chapter details the basic operating modes along with some common applications in which the PEL-5000C series Electronic Load is used.

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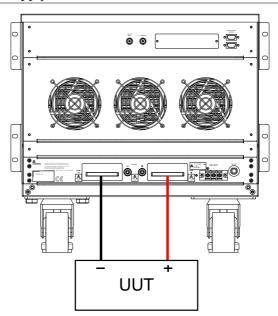
## Local sense connections

### Background

Local sensing is used in applications where the lead lengths are relatively short, or where load regulation is not critical. When connected in local sense mode the 5 digit voltage meter of the PEL-5000C Series Electronic load measures the voltage at its DC input terminals. The connecting leads between the DUT and the Electronic Load should be bundled or tie wrapped together to minimize inductance.

The diagram below illustrates a typical set up with the electronic load connected to the DC power supply.

Local voltage sense connections





## Remote sense connections

#### Background

Remote sensing compensates for the voltage drop in applications that require long lead lengths. It is useful under low voltage high current conditions. The remote voltage sense terminals (Vs+) and (Vs-) of the load are connected to (+) and (-) output of the DC Source. Be sure to observe the correct polarity or damage may occur. The power and sense cables should be bundled or tie wrapped together to minimize inductance.

The diagram below illustrates a typical set up with the electronic load connected for remote sense operation.

If V-sense is set to "ON" and the sense terminals are connected to the DUT the load will check and compensate for all voltage drops. The maximum voltage sense compensation is the same as the rating of the PEL-5006C-150-600.

#### Example

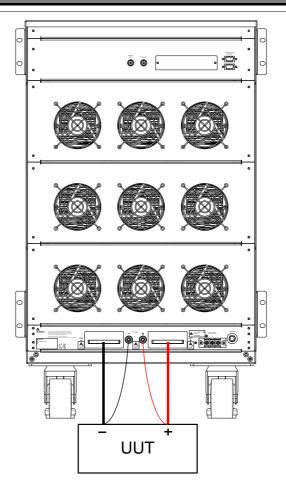
Vmax of PEL-5006C-150-600 is 150Vdc so maximum Vsense is also 150Vdc.

Vmax of PEL-5006C-600-420 is 600Vdc so maximum Vsense is also 600Vdc.

Vmax of PEL-5006C-1200-240 is 1200Vdc so maximum Vsense is also 1200Vdc.



Remote voltage sense connections





## Constant Current mode application

### Background

The Constant Current (CC) mode is ideal for testing the Load Regulation, Cross Regulation, Output Voltage and Dynamic Regulation of the power supply under test. The CC mode can also be used to test the Discharge Characteristics and the Life Cycle of cells and battery packs. In CC operation the PEL-5000C series can operate as a static load with switchable high and low current levels. It is also possible to operate the load dynamically enabling the user to adjust sink current with time.

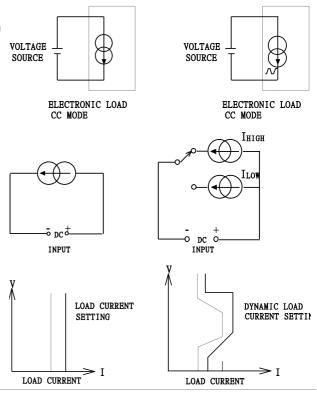
#### Static mode

Major application areas include:

- Voltage source testing
- · Power supply load regulation testing
- · Battery discharge testing



Constant current mode application



Dynamic mode

The built-in pulse generators allow the user to recreate real world loads that vary with time.

Major application areas include:

Power supply load transient response testing

Power recovery time testing

Battery Pulse load simulation

Power component testing

Two levels of current can be set and the rate of change between the 2 current levels can be adjusted in relation to time. The current rise (slew) rate and the current fall (slew) rate can be adjusted independently from each other and are further defined below.

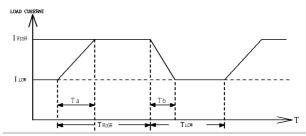


Rise slew rate = | Ilow - Ihigh | / Ta (A/us) Fall slew rate = (Ihigh - Ilow) / Tb (A/us) Rise time(Ta) = (Ilow - Ihigh) / Rise slew rate Fall time(Tb) = (Ihigh - Ilow) / Fall slew rate The time the waveform is high (Thigh) and the time the waveform is low (Tlow) can also be adjusted. The diagram below shows the 6 adjustable parameters that define the dynamic waveform.

Analogue programming input

The analogue programming input can also be used in CC mode. The analogue programming input allows a complex dynamic waveform to be set up on an external oscillator. The PEL-5000C series load will track and load according to the external signal as long as it is within its dynamic capability. The input signal can be the range of 0-10V (dc+ac). The 10V is proportional to the full current capability of the load.

Dynamic load current with independent programmed Rise/Fall slew rate



## Constant Voltage mode application

#### Background

In Constant Voltage (CV) operation the load will attempt to sink as much current as required in order to reach the set voltage value. CV operation is useful in checking the load regulation of dc current sources. The CV mode is also ideal for characterizing the current limit of dc power supplies. These application areas are explained a little more below.

# Current source testing

A common application for a dc current source is as a battery charger. Most battery chargers are designed to automatically adjust their charging current according to the battery voltage. In CV mode the electronic load will sink the current that is needed to reach the desired voltage. The CV mode is therefore ideal for checking the charge current at a particular voltage level.

If the battery charger is tested at a number of different voltage levels in CV mode a current curve can be recorded. Thus the battery charger's load regulation can be checked during development, production and batch testing.

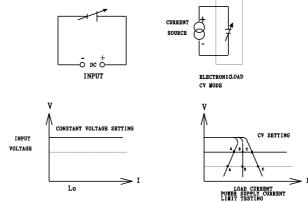
# Power supply current limit characterization

The current limit is a necessary function for power supplies. The fold back current limit curve is very common for fixed output switching power supplies. The constant current limit curve is more popular for adjustable laboratory power supplies.

It is very difficult or impossible to find the current limit curve by CC or CR mode. However it becomes simple by using CV mode. The user sets the CV voltage and Records the output current. Plotting the current measurements against the voltage Settings result in the output current limit curve of a power supply



Constant Voltage mode application

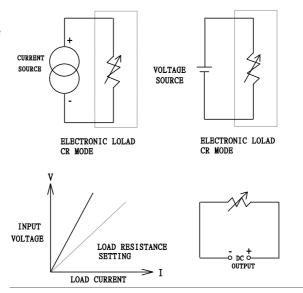


## Constant Resistance mode application

Operating in Constant Resistance mode is useful for testing both voltage and current sources. The CR mode is particularly suited for the "soft start" of power supplies. This is explained in more detail below.	
In constant current mode the demand at initial "Load ON" of the preset current value is almost instantaneous. This might cause the Device under Test (DUT) problems meeting the relatively high current demand at initial switch on.	
A 5V/50A output power supply may not be able to deliver 50A over its entire start-up range of 0-5 volts. In many cases the power supply's short circuit or over current protection circuit cause the power supply to shut down. This is because the power supply is trying to deliver the 50A at a voltage level that is too low.	
The answer to this problem is not to use CC mode but to use CR mode instead. This is because in CR mode the current and voltage ramp up together providing a 'soft start' when compared to standard CC mode.	
However please note that with the PEL-5000C Series of Electronic Loads allow an adjustable current ramp can be set. This feature is found within the dynamic settings as RISE slew rate. Even in static mode the PEL-5000C Series load will regulate its current demand at "Load ON" in line with the adjusted RISE slew rate. The FALL slew rate also in the dynamic settings allows the current ramp down to be controlled at "Load OFF".	



Constant Resistance mode Application



## Constant Power mode application

#### Background

**Battery Evaluation** 

Primary or secondary batteries are the power source for a wide range of portable electronics products, such as notebook computers, video cameras and mobile phones. To ensure long usage times and customer satisfaction the battery pack should be able to provide a constant power for the longest time possible.

It can be measured that the output voltage of a battery will drop over time (Fig a). The rate of voltage decay depends on a number of factors including duty cycle, chemistry type, battery age and ambient temperature.

So to keep the device powered for the longest possible time the battery must be able to provide a stable power output regardless of output voltage (Fig c). In order to maintain a constant power the output current will need to increase over time to compensate for the reducing voltage (Fig b).

Operating the PEL-5000C series electronic load in CP mode is ideal for testing the characteristics of a battery. This is because as the battery voltage drops the load current will automatically increase in order to keep the CP setting. By logging sink values against time the test engineer can also measure the battery's energy capacity at various discharge rates.

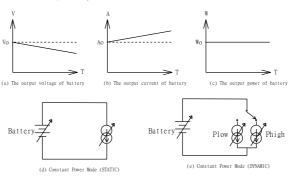
The PEL-5000C series also features an adjustable Load OFF setting. This allows a voltage level to be set so that the electronic load automatically stops sinking power upon reaching this preset voltage. This can be used to ensure the battery is not subjected to a damaging deep discharge.

Along with static operation the load can also be



operated dynamically in CP mode. The dynamic functions allow the ramp, fall and plateau times to be adjusted between 2 levels of power. This capability means that 'real world' loads can be more accurately simulated. For example the dynamic mode could be used to test the performance of a battery that is required to provide power pulses to transmit data from a radio frequency terminal.

# Constant power mode application



Note

To use CP mode to do battery discharge test when CPRSP = 0(definition is 0), the ... Too long wire may cause oscillation and stop the test. The solution as below.

- Use Vsense function Connect Vsense for voltage drop compensation
- 2. Use CPRSP = 1~4 to slower the CP mode respose speed, the CPRSP setting in the Config key.

CPRSP settings will not be stored when turned off, When the PEL-5000C power is turned on, the CPRSP gear position must be set.

## CC + CV mode of operation application

#### Background

When operating in CC + CV mode, PEL-5000C series at the same time as a Constant Current and constant voltage load, as shown in Fig below.

When operating at constant current (CC) load, PEL-5000C series electronic load to Voltage source (VM) Constant Current load (I) and keep Constant Voltage.

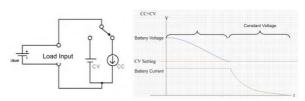
When operating at constant voltage load on, the VM is greater than V, Input current changes its input voltage is keep fixed.

When the VM voltage is less than equal to the set voltage CV, the load does not sink current.

### Operation Way:

- Load input terminals are connected to the DUT
- Change to CC mode and setting CC current setting.
- Press Limit key to setting the CV voltage and the display will show "Add.CV".
- Press START key to start up the CC+CV test, and press "STOP" key to stop CC+CV test.

CC+CV mode operation application



Remote Control CC+CV

REMOTE (Set Remote Control)
MODE CC (Setting CC mode)

CC: HIGH 20 (Setting load on current 20A) LIM: ADDCV:VOLT 50 (Setting constant Voltage is 50V)

LIM: ADDCV ON (start test CC+CV mode)



MEAS: CURR? (Read current value)
MEAS: VOLT? (Read voltage value)
LIM: ADDCV OFF (Stop test CC+CV mode)

## CP + CV mode of operation application

#### Background

Operating in CP + CV mode, PEL-5000C series at the same time as a Constant Power and constant Voltage Load, as shown in Fig below.

When Operating at Constant Power (CP) load, PEL-5000C series electronic load provides specified power, independent Constant Voltage source (VM) is output voltage.

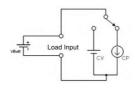
When Operating at Constant Voltage Load on, the VM is greater than V, Input power changes its input voltage is keep fixed.

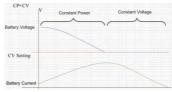
When the VM voltage is less than equal to the set voltage CV, the load does not sink current.

### Operation Way:

- Load input terminals are connected to the DUT
- Change to CP mode and setting CP power setting.
- Press Limit key to setting the CV voltage and the display will show "Add.CV".
- Press START key to start up the CP+CV test, and press "STOP "key to stop CP+CV test.

CP+CV mode operation application





Remote Control CP+CV

REMOTE (Set Remote Control)
MODE CP (Setting CP mode)
CP: HIGH 100 (Setting load on curre

CP: HIGH 100 (Setting load on current 100W) LIM: ADDCV:VOLT 50 (Setting constant Voltage is 50V)

LIM: ADDCV ON (start test CP+CV mode)
MEAS: POW? (Read power value)



MEAS: VOLT? (Read voltage value) LIM: ADDCV OFF (Stop test CP+CV mode)

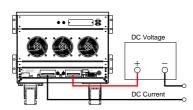
## Constant current source operating

## Background

PEL-5000C high-power electronic load can be used as a constant current source when used in series with a constant voltage source for charging the battery or other applications, as shown in Fig below.

constant current source connection





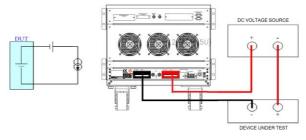


## Zero-Volt loading application

#### Background

As shown in Fig below, the electronic load can be connected in series with a DC voltage source which output voltage greater than minimum operating voltage. so that the device under test that are connected to the electronic load can be operated down to a Zero- Volt condition, the DC voltage source provides the minimum operating voltage required by the Electronic load. This application is suitable for low voltage Battery cell with high discharge current testing.

## Zero-Volt loading connection



#### Note

Minimum operating voltage varies according to different models

For model of 150V, Minimum operating voltage is 0.7V

For model of 600V, Minimum operating voltage is 10V For model of 1200V, Minimum operating voltage is 15V

## Parallel operation

#### Background

It is possible to operate load in parallel if the power and/or current capability of a single PEL-5000C series load is not sufficient.

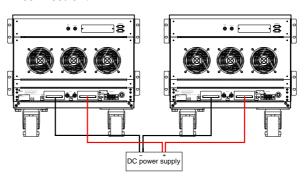
The positive and negative outputs of the power supply are connected individually to each load module as shown in the Fig below. The setting is made at each individual load module. The total load current is the sum of the load currents being taken by each load.

While in static mode the load modules can be set to operate in CC, CR or CP. When using multiple loads to sink power from a single DC Source it is not permissible to operate in dynamic mode.

#### Note

- The electronic load only may carry on the parallel operation under the fixed electric current Pattern.
- The electronic load do not use under series connection.

PEL-5000C series load parallel operation





## Power Supply OCP testing

# OCP Manual control

- 1. Press Limit key function to setting I\_Hi & I\_Lo.
- 2. Setting OCP test, press OCP key to the next step.



3. Setting start load current 0A, press OCP key to the next step.



4. Setting step load current 0.005A, press OCP key to the next step.



5. Setting stop load current 5A, press OCP key to the next step.



6. Setting OCP VTH 6.00V, press OCP key to the next step.



7. Press START/STOP test key.





8. The UUT's output voltage drop-out lower than the threshold voltage(V-th setting), and the OCP trip point is between I\_Hi and I\_Lo limitation, then middle 5 digits LCD display will shows "PASS", otherwise shows "FAIL".



(Set start load current 0.1A)

### Remote control OCP example

OCP:START 0.1

REMOTE (Set Remote) TCONFIG OCP (Set OCP test)

OCP:STEP 0.01 (Set step load current 0.01A)
OCP:STOP 2 (Set stop load current 2A)
VTH 3.0 (Set OCP VTH 3.0V)
IL 0 (Set current low limit 0A)
IH 2 (Set current high limit 2A)
NGENABLE ON (Set NG Enable ON)

START (Start OCP testing)

TESTING? (Ask Testing? 1: Testing, 0: Testing End) NG? (Ask PASS/FAIL?, 0: PASS, 1: FAIL)

OCP? (Ask OCP current value) STOP (Stop OCP testing)



## Power Supply OPP testing

# OCP Manual control

- Press Limit key function to setting W\_Hi & W Lo.
- 2. Setting OPP test, press OPP key to the next step.



3. Setting start load current 0W, press OPP key to the next step.



4. Setting step load current 0.5W, press OPP key to the next step.



5. Setting stop load current 100W, press OPP key to the next step.



6. Setting OPP VTH 6.00V, press OPP key to the next step.



7. Press START/STOP test key.





8. The UUT's output voltage drop-out lower than the threshold voltage (V-th setting), and the OPP trip point is between W\_Hi and W\_Lo limitation, then Right 5 digits LCD display will shows "PASS", otherwise shows "FAIL".



## Remote control OPP example

REMOTE (Set Remote) TCONFIG OPP (Set OPP test)

OPP:START 3 (Set start load watt 3W) (Set step load watt 1W) **OPP:STEP 1 OPP:STOP 5** (Set stop load watt 5W) VTH 3.0 (Set OPP VTH 3.0V) (Set watt low limit 0W) WL0(Set watt high limit 5W) WH5 NGENABLE ON (Set NG Enable ON) **START** (Start OPP testing)

TESTING? (Ask Testing? 1: Testing, 0: Testing End) NG? (Ask PASS/FAIL?, 0: PASS, 1: FAIL)

OPP? (Ask OPP watt value) STOP (Stop OPP testing)



## SHORT testing

OCP Manual control 1. Setting SHORT test, press Short key to the next step.



2. Press UP key, setting Short time to 10000ms, press Short key to the next Step.



3. Press down key, setting V-Hi voltage to 1.00V, press Short key to the next Step.



4. Press down key, setting V-Lo voltage to 0V, press Short key to the next step.



5. Press START/STOP test key.



 Short test finish, the UUT's drop voltage is between V\_Hi and V\_Lo limitation, then right upper 5 digits LCD display will shows "PASS"



7. The UUT's not drop voltage is between V\_Hi and V\_Lo limitation, LCD display will shows FAIL.





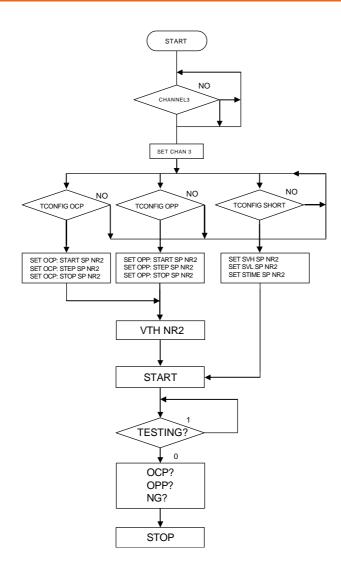
Remote control SHORT example
REMOTE (Set Remote)
TCONFIG SHORT (Set SHORT test)
STIME 1 (Set short time 1ms)
START (Start SHORT testing)

TESTING? (Ask Testing? 1: Testing, 0: Testing End)

STOP (Stop SHORT testing)



## OCP, OPP, SHORT operation flow Chart

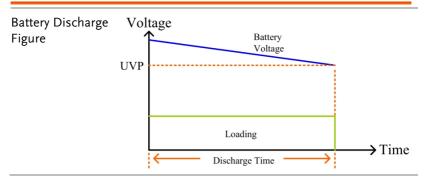


## Battery discharge test

There are 6 types battery discharge for the battery discharge application.

## Disch CC / Disch CP measure discharge capacity

User option mode CC or CP mode, firstly, Setting UVP(under voltage protect), testing LOAD ON, when battery voltage less than UVP LOAD OFF Display total discharge capacity AH/WH.



## Cycle Life test

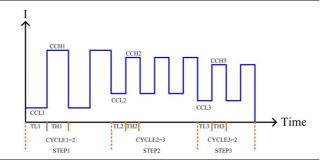
Only remote operating, please refer to the remote command list.

Cycle Life test, Battery discharge test use pulse mode, Dynamic mode use count test And Repeat function, as show Fig 5-18, load on and dynamic on until counter to 0, load on and dynamic on auto change to off, Remote will shows "OK" and XX.XXX" (V meter), Cycle setting range 1 to 2000, step setting value 1 to 3 and Repeat setting value 0 to 9999, the setting is by remote operation.

Note	Pre-setting the LOAD OFF voltage can protect the battery from discharging when the preset discharge
	time has not been reached, and stop the battery when
	the battery voltage is to low to avoid battery damage.



Cycle Life test mode Battery Discharge



#### RAMP Mode

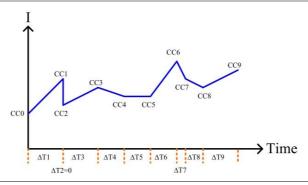
RAMP Mode, Slew rate load on and Repeat function, as Fig 5-16 Show. Setting" STEPn" n-1~9, CC0, CC1,  $\Delta$ T1, CC2,  $\Delta$ T2.....CC9,  $\Delta$ T9, Repeat, Load on mode, Increased or Decreased current values by every seconds.

 $\Delta$ CC =(CCn-(CCn-1))/Time, Time:0~6000Sec, STEP: 1~9, Repeat: 0~9999, Load on auto change to off and remoter will shows "OK" and XX.XXX"(V meter).

Note

Pre-setting the LOAD OFF voltage can protect the battery from discharging when the preset discharge time has not been reached, and stop the battery when the battery voltage is to low to avoid battery damage.

RAMP Mode Battery Discharge





## **REMOTE Command Description**

Disch CC / Disch CP : Setting BATT: CURR or BATT: POWER, Setting BATT: UVP , setting stop stop discharge time BATT: TIME, Setting stop discharge capacity BATT: AH or BATT: AH , then "BATT:TEST ON" command start testing , when batty voltage less than UVP value then LOAD OFF, on behalf of the end of the test, When it ends LOAD remote will show "OK,XXXXX", XXXXX representative total discharge capacity : AH / WH.

Example	When Disch CC	When Disch CP	
	BATT: CURR 2.34	BATT: POWER 2.34	
	BATT: UVP 12.0	BATT: UVP 12.0	
	BATT: TIME 6000	BATT: TIME 6000	
	BATT: AH 999	BATT: WH 999	
	BATT: TEST ON	BATT: TEST ON	

Set Cycle Life test, and The set sequence is CCLn/CCHn/THn/TLn/CYCLEn, Repeat, LDOFFV Parameters command input "BATT: TEST ON", Command to start the test, Test end, Remote will show "OK, XXXXX", XXXXX is end Voltage.

Example	BATT: CYCLE
	BATT: STEP 2
	BATT: CCH1 6.0
	BATT: CCL1 1.0
	BATT: TH1 2.0
	BATT: TL1 2.0
	BATT: CYCLE1 500
	BATT: CCH2 4.0
	BATT: CCL2 1.0
	BATT: TH1 1.0
	BATT: TL1 1.0
	BATT: CYCLE2 500



LDOFFV 10.5 BATT: REPEAT 1 BATT: TEST ON

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PEL-5020C-1200-800, PEL-5024C-1200-960	



## PEL-5000C Default Settings

The following default settings are the factory configuration settings for the load.

Model	PEL-5006C-150-600	PEL-5008-150-800	PEL-5010C-150-1000
Item	Initial value		
CC L+Preset	0.000 A	0.000 A	0.000 A
CC H+Preset	0.000 A	0.000 A	0.000 A
CR H+Preset	15000Ω	11250Ω	9000.0Ω
CR L+Preset	15000Ω	11250Ω	9000.0Ω
CV H+Preset	150.00 V	150.00 V	150.00 V
CV L+Preset	150.00 V	150.00 V	150.00 V
CP L+Preset	0.00 W	0.0W	0.0W
CP H+Preset	0.00 W	0.0W	0.0W

Model	PEL-5012C-150-1200	PEL-5015C-150-1500	PEL-5018C-150-1800
Item	Initial value		
CC L+Preset	0.000 A	0.000 A	0.000 A
CC H+Preset	0.000 A	0.000 A	0.000 A
CR H+Preset	7500.0Ω	6000.0Ω	5000.0Ω
CR L+Preset	7500.0Ω	6000.0Ω	5000.0Ω
CV H+Preset	150.00 V	150.00 V	150.00 V
CV L+Preset	150.00 V	150.00 V	150.00 V
CP L+Preset	0.00 W	0.0W	0.0W
CP H+Preset	0.00 W	0.0W	0.0W

Model	PEL-5020C-150-2000	PEL-5024C-150-2000	PEL-5006C-600-420
Item	Initial value		
CC L+Preset	0.000 A	0.000 A	0.000 A
CC H+Preset	0.000 A	0.000 A	0.000 A
CR H+Preset	4500.0Ω	4500.0Ω	85712Ω
CR L+Preset	4500.0Ω	4500.0Ω	85712Ω
CV H+Preset	150.00 V	150.00 V	600.00 V
CV L+Preset	150.00 V	150.00 V	600.00 V
CP L+Preset	0.00 W	0.0W	0.0W
CP H+Preset	0.00 W	0.0W	0.0W

Model	PEL-5008C-600-560	PEL-5010C-600-700	PEL-5012C-600-840
Item	Initial value		
CC L+Preset	0.000 A	0.000 A	0.000 A
CC H+Preset	0.000 A	0.000 A	0.000 A



				-
CR H+Preset	64284Ω	51427Ω	42856Ω	
CR L+Preset	64284Ω	51427Ω	42856Ω	
CV H+Preset	600.00 V	600.00 V	600.00 V	
CV L+Preset	600.00 V	600.00 V	600.00 V	
CP L+Preset	0.00 W	0.0W	0.0W	
CP H+Preset	0.00 W	0.0W	0.0W	

Model	PEL-5015C-600-1050	PEL-5018C-600-1260	PEL-5020C-600-1400
Item	Initial value		
CC L+Preset	0.000 A	0.000 A	0.000 A
CC H+Preset	0.000 A	0.000 A	0.000 A
CR H+Preset	34284Ω	28570Ω	25713Ω
CR L+Preset	34284Ω	28570Ω	25713Ω
CV H+Preset	600.00 V	600.00 V	600.00 V
CV L+Preset	600.00 V	600.00 V	600.00 V
CP L+Preset	0.00 W	0.0W	0.0W
CP H+Preset	0.00 W	0.0W	0.0W

Model	PEL-5024C-600-1680	PEL-5006C-1200-240	PEL-5008C-1200-320
Item	Initial value		
CC L+Preset	0.000 A	0.000 A	0.000 A
CC H+Preset	0.000 A	0.000 A	0.000 A
CR H+Preset	21428Ω	30000Ω	22500Ω
CR L+Preset	21428Ω	30000Ω	22500Ω
CV H+Preset	600.00 V	1200.0 V	1000.0 V
CV L+Preset	600.00 V	1200.0 V	1000.0 V
CP L+Preset	0.00 W	0.0W	0.0W
CP H+Preset	0.00 W	0.0W	0.0W

PEL-5010C-1200-400	PEL-5012C-1200-480	PEL-5015C-1200-600
Initial value		
0.000 A	0.000 A	0.000 A
0.000 A	0.000 A	0.000 A
18000Ω	15000Ω	12000Ω
18000Ω	15000Ω	12000Ω
1200.0 V	1200.0 V	1200.0 V
1200.0 V	1200.0 V	1200.0 V
0.00 W	0.0W	0.0W
0.00 W	0.0W	0.0W
	Initial value 0.000 A 0.000 A 18000Ω 18000Ω 1200.0 V 1200.0 V 0.00 W	0.000 A       0.000 A         0.000 A       0.000 A         18000Ω       15000Ω         18000Ω       15000Ω         1200.0 V       1200.0 V         1200.0 V       1200.0 V         0.00 W       0.0W

Model	PEL-5018C-1200-720	PEL-5020C-1200-800	PEL-5024C-1200-960
Item	Initial value		
CC L+Preset	0.000 A	0.000 A	0.000 A



CC H+Preset CR H+Preset CR L+Preset CV H+Preset CV L+Preset	0.000 A 10000Ω 10000Ω 1000.0 V 1000.0 V 0.00 W	0.000 A 9000Ω 9000Ω 1200.0 V 1200.0 V 0.0W	0.000 A 6000Ω 6000Ω 1200.0 V 1200.0 V 0.0W
CP H+Preset	0.00 W	0.0W	0.0W

Model	PEL-5006C-150-600	PEL-5008-150-800	PEL-5010C-150-1000	
Item	Initial value for Limit	Initial value for Limit		
V_Hi	150.00 V	150.00 V	150.00 V	
V_Lo	0.00 V	0.00 V	0.00 V	
I_Hi	600.00 A	800.00 A	1000.0 A	
I_Lo	0.00 A	0.00 A	0.00 A	
W_Hi	6000.0 W	8000.0 W	10000.0 W	
W_Lo	0.0 W	0.0 W	0.0 W	

Model	PEL-5012C-150-	1200 PEL-5015C-150-	1500 PEL-5018C-150-1800	
Item	Initial value for I	Initial value for Limit		
V_Hi	150.00 V	150.00 V	150.00 V	
V_Lo	0.00 V	0.00 V	0.00 V	
I_Hi	1200.0 A	1200.0 A	1800.0 A	
I_Lo	0.00 A	0.00 A	0.00 A	
W_Hi	12000.0 W	15000.0 W	18000.0 W	
W_Lo	0.0 W	0.0 W	0.0 W	

Model	PEL-5020C-150-2000	PEL-5024C-150-2000	PEL-5006C-600-420
Item	Initial value for Limit		
V_Hi	150.00 V	150.00 V	600.00 V
V_Lo	0.00 V	0.00 V	0.00 V
I_Hi	2000.0 A	2000.0 A	420.00 A
I_Lo	0.00 A	0.00 A	0.00 A
W_Hi	20000 W	24000 W	6000.0 W
W_Lo	0.0 W	0.0 W	0.0 W

Model	PEL-5008C-600-560	PEL-5010C-600-700	PEL-5012C-600-840	
Item	Initial value for Lim	Initial value for Limit		
V_Hi	600.00 V	600.00 V	600.00 V	
V_Lo	0.00 V	0.00 V	0.00 V	
I_Hi	560.00 A	700.00 A	840.00 A	
I_Lo	0.00 A	0.00 A	0.00 A	
W_Hi	8000.0 W	10000.0 W	12000.0 W	
W_Lo	0.0 W	0.0 W	0.0 W	



Model		PEL-5018C-600-1260	PEL-5020C-600-1400
Item	Initial value for Limit		
V_Hi	600.00 V	600.00 V	600.00 V
V_Lo	0.00 V	0.00 V	0.00 V
I_Hi	840.00 A	1260.00 A	1400.00 A
I_Lo	0.00 A	0.00 A	0.00 A
W_Hi	15000.0 W	18000.0 W	20000 W
W_Lo	0.0 W	0.0 W	0.0 W
Model	PEL-5024C-600-1680	PEL-5006C-1200-240	PEL-5008C-1200-320
Item	Initial value for Limit		
V_Hi	600.00 V	1200.0 V	1200.0 V
V_Lo	0.00 V	0.00 V	0.00 V
I_Hi	1680.00 A	240.00 A	320.00 A
I_Lo	0.00 A	0.00 A	0.00 A
W_Hi	24000 W	6000.0 W	8000.0 W
W_Lo	0.0 W	0.0 W	0.0 W
Model	PFI -5010C-1200-400	PEL-5012C-1200-480	PFI -5015C-1200-600
Item	Initial value for Limit		
V_Hi	1200.0 V	1000.0 V	1200.0 V
V_Lo	0.00 V	0.00 V	0.00 V
I_Hi	400.00 A	480.00 A	600.00 A
I_Lo	0.00 A	0.00 A	0.00 A
W_Hi	10000.0 W	12000.0 W	15000.0 W
W_Lo	0.0 W	0.0 W	0.0 W
Model	DEL 5019C 1200 720	PEL-5020C-1200-800	DEL 5024C 1200 060
Item	Initial value	FLL-3020C-1200-800	FLL-3024C-1200-300
V_Hi	1200.0 V	1200.0 V	1200.0 V
V_III V_Lo	0.00 V	0.00 V	0.00 V
v_to I_Hi	720.00 A	800.00 A	960.00 A
I_Lo	0.00 A	0.00 A	0.00 A
W_Hi	18000.0 W	20000 W	24000 W
W_Lo	0.0 W	0.0 W	0.0 W
W_LO	0.0 W	0.0 W	0.0 W
Model	PEL-5006C-150-600	PEL-5008-150-800	PEL-5010C-150-1000
Item	Initial value for DYN		
T HI	0.050 mS	0.050 mS	0.050 mS
T L0	0.050 mS	0.050 mS	0.050 mS
RISE	0.144A/uS	0.192A/uS	0.240A/uS
FALL	0.144A/uS	0.192A/uS	0.240A/uS



Model		PEL-5015C-150-1500	PEL-5018C-150-1800
Item	Initial value for DYN		
THI	0.050 mS	0.050 mS	0.050 mS
T L0	0.050 mS	0.050 mS	0.050 mS
RISE	0.288A/uS	0.360A/uS	0.432A/uS
FALL	0.288A/uS	0.360A/uS	0.432A/uS
Model	PEL-5020C-150-2000	PEL-5024C-150-2000	PEL-5006C-600-420
Item	Initial value for DYN		
T HI	0.050 mS	0.050 mS	0.050 mS
T LO	0.050 mS	0.050 mS	0.050 mS
RISE	0.480A/uS	0.480A/uS	0.288A/uS
FALL	0.480A/uS	0.480A/uS	0.288A/uS
	,	,	,
Model	PEL-5008C-600-560	PEL-5010C-600-700	PEL-5012C-600-840
Item	Initial value for DYN	1 22 3010 2 000 700	1 22 3012 2 000 010
THI	0.050 mS	0.050 mS	0.050 mS
T L0	0.050 mS	0.050 mS	0.050 mS
RISE	0.288A/uS	0.336A/uS	0.384A/uS
FALL	0.288A/uS	0.336A/uS	0.384A/uS
.,	0.200.1,00	0.550. y a.c	0.50 1/ 0.0
N4 - J - I	DEL E01EC (00 10E0	DEL F019C (00 12C0	DEL 5020C (00 1400
Model	PEL-5015C-600-1050	PEL-5018C-600-1260	PEL-5020C-600-1400
Item	Initial value for DYN		
Item T HI	Initial value for DYN 0.050 mS	0.050 mS	0.050 mS
T HI T L0	Initial value for DYN 0.050 mS 0.050 mS	0.050 mS 0.050 mS	0.050 mS 0.050 mS
T HI T LO RISE	Initial value for DYN 0.050 mS 0.050 mS 0.432A/uS	0.050 mS 0.050 mS 0.480A/uS	0.050 mS 0.050 mS 0.528A/uS
T HI T L0	Initial value for DYN 0.050 mS 0.050 mS	0.050 mS 0.050 mS	0.050 mS 0.050 mS
T HI T LO RISE FALL	Initial value for DYN 0.050 mS 0.050 mS 0.432A/uS 0.432A/uS	0.050 mS 0.050 mS 0.480A/uS	0.050 mS 0.050 mS 0.528A/uS
T HI T LO RISE	Initial value for DYN 0.050 mS 0.050 mS 0.432A/uS 0.432A/uS PEL-5024C-600-1680	0.050 mS 0.050 mS 0.480A/uS	0.050 mS 0.050 mS 0.528A/uS
Item T HI T LO RISE FALL  Model Item	Initial value for DYN 0.050 mS 0.050 mS 0.432A/uS 0.432A/uS	0.050 mS 0.050 mS 0.480A/uS 0.480A/uS	0.050 mS 0.050 mS 0.528A/uS 0.528A/uS
Item T HI T LO RISE FALL  Model Item T HI	Initial value for DYN  0.050 mS  0.050 mS  0.432A/uS  0.432A/uS  PEL-5024C-600-1680  Initial value for DYN  0.050 mS	0.050 mS 0.050 mS 0.480A/uS 0.480A/uS PEL-5006C-1200-240	0.050 mS 0.050 mS 0.528A/uS 0.528A/uS PEL-5008C-1200-320 0.050 mS
Item T HI T LO RISE FALL  Model Item	Initial value for DYN  0.050 mS  0.050 mS  0.432A/uS  0.432A/uS  PEL-5024C-600-1680  Initial value for DYN  0.050 mS  0.050 mS	0.050 mS 0.050 mS 0.480A/uS 0.480A/uS PEL-5006C-1200-240 0.050 mS 0.050 mS	0.050 mS 0.050 mS 0.528A/uS 0.528A/uS PEL-5008C-1200-320 0.050 mS 0.050 mS
Item T HI T LO RISE FALL  Model Item T HI	Initial value for DYN  0.050 mS  0.050 mS  0.432A/uS  0.432A/uS  PEL-5024C-600-1680  Initial value for DYN  0.050 mS  0.050 mS  0.576A/uS	0.050 mS 0.050 mS 0.480A/uS 0.480A/uS PEL-5006C-1200-240 0.050 mS 0.050 mS 0.192A/uS	0.050 mS 0.050 mS 0.528A/uS 0.528A/uS PEL-5008C-1200-320 0.050 mS 0.050 mS 0.192A/uS
Item T HI T L0 RISE FALL  Model Item T HI T L0	Initial value for DYN  0.050 mS  0.050 mS  0.432A/uS  0.432A/uS  PEL-5024C-600-1680  Initial value for DYN  0.050 mS  0.050 mS	0.050 mS 0.050 mS 0.480A/uS 0.480A/uS PEL-5006C-1200-240 0.050 mS 0.050 mS	0.050 mS 0.050 mS 0.528A/uS 0.528A/uS PEL-5008C-1200-320 0.050 mS 0.050 mS
Item T HI T LO RISE FALL  Model Item T HI T LO RISE	Initial value for DYN  0.050 mS  0.050 mS  0.432A/uS  0.432A/uS  PEL-5024C-600-1680  Initial value for DYN  0.050 mS  0.050 mS  0.576A/uS	0.050 mS 0.050 mS 0.480A/uS 0.480A/uS PEL-5006C-1200-240 0.050 mS 0.050 mS 0.192A/uS	0.050 mS 0.050 mS 0.528A/uS 0.528A/uS PEL-5008C-1200-320 0.050 mS 0.050 mS 0.192A/uS
Item T HI T LO RISE FALL  Model Item T HI T LO RISE	Initial value for DYN  0.050 mS  0.050 mS  0.432A/uS  0.432A/uS  PEL-5024C-600-1680  Initial value for DYN  0.050 mS  0.050 mS  0.576A/uS	0.050 mS 0.050 mS 0.480A/uS 0.480A/uS PEL-5006C-1200-240 0.050 mS 0.050 mS 0.192A/uS 0.192A/uS	0.050 mS 0.050 mS 0.528A/uS 0.528A/uS PEL-5008C-1200-320 0.050 mS 0.050 mS 0.192A/uS
Item T HI T LO RISE FALL  Model Item T HI T LO RISE FALL	Initial value for DYN  0.050 mS  0.050 mS  0.432A/uS  0.432A/uS  PEL-5024C-600-1680  Initial value for DYN  0.050 mS  0.050 mS  0.576A/uS  0.576A/uS	0.050 mS 0.050 mS 0.480A/uS 0.480A/uS PEL-5006C-1200-240 0.050 mS 0.050 mS 0.192A/uS 0.192A/uS	0.050 mS 0.050 mS 0.528A/uS 0.528A/uS PEL-5008C-1200-320 0.050 mS 0.050 mS 0.192A/uS
Item T HI T LO RISE FALL  Model Item T HI T LO RISE FALL  Model	Initial value for DYN 0.050 mS 0.050 mS 0.432A/uS 0.432A/uS  PEL-5024C-600-1680 Initial value for DYN 0.050 mS 0.050 mS 0.576A/uS 0.576A/uS  PEL-5010C-1200-400	0.050 mS 0.050 mS 0.480A/uS 0.480A/uS PEL-5006C-1200-240 0.050 mS 0.050 mS 0.192A/uS 0.192A/uS	0.050 mS 0.050 mS 0.528A/uS 0.528A/uS PEL-5008C-1200-320 0.050 mS 0.050 mS 0.192A/uS
Item T HI T LO RISE FALL  Model Item T HI T LO RISE FALL  Model Item	Initial value for DYN  0.050 mS  0.050 mS  0.432A/uS  0.432A/uS  PEL-5024C-600-1680  Initial value for DYN  0.050 mS  0.050 mS  0.576A/uS  PEL-5010C-1200-400  Initial value for DYN	0.050 mS 0.050 mS 0.480A/uS 0.480A/uS PEL-5006C-1200-240 0.050 mS 0.050 mS 0.192A/uS 0.192A/uS	0.050 mS 0.050 mS 0.528A/uS 0.528A/uS PEL-5008C-1200-320 0.050 mS 0.050 mS 0.192A/uS PEL-5015C-1200-600 0.050 mS 0.050 mS
Item T HI T LO RISE FALL  Model Item T HI T LO RISE FALL  Model Item T HI T LO RISE FALL	Initial value for DYN  0.050 mS  0.050 mS  0.432A/uS  0.432A/uS  PEL-5024C-600-1680 Initial value for DYN  0.050 mS  0.050 mS  0.576A/uS  PEL-5010C-1200-400 Initial value for DYN  0.050 mS	0.050 mS 0.050 mS 0.480A/uS 0.480A/uS PEL-5006C-1200-240 0.050 mS 0.050 mS 0.192A/uS 0.192A/uS PEL-5012C-1200-480 0.050 mS	0.050 mS 0.050 mS 0.528A/uS 0.528A/uS PEL-5008C-1200-320 0.050 mS 0.050 mS 0.192A/uS 0.192A/uS PEL-5015C-1200-600



Model		PEL-5020C-1200-800	PEL-5024C-1200-960
Item	Initial value for DYN		
T HI	0.050 mS	0.050 mS	0.050 mS
T L0	0.050 mS	0.050 mS	0.050 mS
RISE	0.320A/uS	0.352A/uS	0.384A/uS
FALL	0.320A/uS	0.352A/uS	0.384A/uS
Model	PEL-5006C-150-600	PEL-5008-150-800	PEL-5010C-150-1000
Item	Initial value for CONI	FIG	
SENSE	Auto	Auto	Auto
LD-ON	2.50 V	2.50 V	2.50 V
LD-OFF	1.000V	1.000V	1.000V
+LOAD	+LOAD	+LOAD	+LOAD
Model	PEL-5012C-150-1200	PEL-5015C-150-1500	PFL-5018C-150-1800
Item	Initial value for CONI		1 22 30 100 130 1000
SENSE	Auto	Auto	Auto
LD-ON	2.50 V	2.50 V	2.50 V
LD-OFF	1.000V	1.000V	1.000V
+LOAD	+LOAD	+LOAD	+LOAD
120/13	120/10	120/12	120715
Madal	DEL 5020C 150 2000	DEL 5034C 150 3000	DEL 5006C 600 420
Model		PEL-5024C-150-2000	PEL-5006C-600-420
ltem	Initial value for CONI	FIG	
Item SENSE	Initial value for CONI Auto	FIG Auto	Auto
Item SENSE LD-ON	Initial value for CONI Auto 2.50 V	FIG Auto 2.50 V	Auto 4.00 V
Item SENSE LD-ON LD-OFF	Initial value for CONI Auto 2.50 V 1.000V	FIG Auto 2.50 V 1.000V	Auto 4.00 V 0.50 V
Item SENSE LD-ON	Initial value for CONI Auto 2.50 V	FIG Auto 2.50 V	Auto 4.00 V
Item SENSE LD-ON LD-OFF	Initial value for CONI Auto 2.50 V 1.000V	FIG Auto 2.50 V 1.000V	Auto 4.00 V 0.50 V
Item SENSE LD-ON LD-OFF	Auto 2.50 V 1.000V +LOAD  PEL-5008C-600-560	Auto 2.50 V 1.000V +LOAD PEL-5010C-600-700	Auto 4.00 V 0.50 V
Item SENSE LD-ON LD-OFF +LOAD	Initial value for CONI Auto 2.50 V 1.000V +LOAD	Auto 2.50 V 1.000V +LOAD PEL-5010C-600-700	Auto 4.00 V 0.50 V +LOAD
Item SENSE LD-ON LD-OFF +LOAD	Auto 2.50 V 1.000V +LOAD  PEL-5008C-600-560	Auto 2.50 V 1.000V +LOAD PEL-5010C-600-700	Auto 4.00 V 0.50 V +LOAD
Item SENSE LD-ON LD-OFF +LOAD  Model Item	Initial value for CONI Auto 2.50 V 1.000V +LOAD PEL-5008C-600-560 Initial value for CONI	Auto 2.50 V 1.000V +LOAD PEL-5010C-600-700	Auto 4.00 V 0.50 V +LOAD PEL-5012C-600-840
Item SENSE LD-ON LD-OFF +LOAD  Model Item SENSE	Initial value for CONI Auto 2.50 V 1.000V +LOAD PEL-5008C-600-560 Initial value for CONI Auto	Auto 2.50 V 1.000V +LOAD PEL-5010C-600-700 FIG Auto	Auto 4.00 V 0.50 V +LOAD PEL-5012C-600-840
Item SENSE LD-ON LD-OFF +LOAD  Model Item SENSE LD-ON	Initial value for CONI Auto 2.50 V 1.000V +LOAD PEL-5008C-600-560 Initial value for CONI Auto 4.00 V	FIG Auto 2.50 V 1.000V +LOAD PEL-5010C-600-700 FIG Auto 4.00 V	Auto 4.00 V 0.50 V +LOAD PEL-5012C-600-840 Auto 4.00 V
Model Item SENSE LD-ON LD-OFF +LOAD  Model Item SENSE LD-ON LD-OFF	Initial value for CONI Auto 2.50 V 1.000V +LOAD PEL-5008C-600-560 Initial value for CONI Auto 4.00 V 0.50 V	PEL-5010C-600-700 FIG Auto 2.50 V 1.000V +LOAD  PEL-5010C-600-700 FIG Auto 4.00 V 0.50 V	Auto 4.00 V 0.50 V +LOAD PEL-5012C-600-840 Auto 4.00 V 0.50 V
Model Item SENSE LD-ON LD-OFF +LOAD  Model Item SENSE LD-ON LD-OFF	Initial value for CONI Auto 2.50 V 1.000V +LOAD PEL-5008C-600-560 Initial value for CONI Auto 4.00 V 0.50 V +LOAD	PEL-5010C-600-700 FIG Auto 2.50 V 1.000V +LOAD  PEL-5010C-600-700 FIG Auto 4.00 V 0.50 V	Auto 4.00 V 0.50 V +LOAD PEL-5012C-600-840 Auto 4.00 V 0.50 V +LOAD
Item SENSE LD-ON LD-OFF +LOAD  Model Item SENSE LD-ON LD-OFF +LOAD	Initial value for CONI Auto 2.50 V 1.000V +LOAD PEL-5008C-600-560 Initial value for CONI Auto 4.00 V 0.50 V +LOAD	FIG Auto 2.50 V 1.000V +LOAD  PEL-5010C-600-700 FIG Auto 4.00 V 0.50 V +LOAD	Auto 4.00 V 0.50 V +LOAD PEL-5012C-600-840 Auto 4.00 V 0.50 V +LOAD
Model Item SENSE LD-ON LD-OFF +LOAD  Model Item SENSE LD-ON LD-OFF +LOAD	Initial value for CONI Auto 2.50 V 1.000V +LOAD PEL-5008C-600-560 Initial value for CONI Auto 4.00 V 0.50 V +LOAD	FIG Auto 2.50 V 1.000V +LOAD  PEL-5010C-600-700 FIG Auto 4.00 V 0.50 V +LOAD	Auto 4.00 V 0.50 V +LOAD PEL-5012C-600-840 Auto 4.00 V 0.50 V +LOAD
Item SENSE LD-ON LD-OFF +LOAD  Model Item SENSE LD-ON LD-OFF +LOAD  Model Item	Initial value for CONIAuto 2.50 V 1.000V +LOAD  PEL-5008C-600-560 Initial value for CONIAuto 4.00 V 0.50 V +LOAD  PEL-5015C-600-1050 Initial value for DYN	PEL-5018C-600-1260	Auto 4.00 V 0.50 V +LOAD  PEL-5012C-600-840  Auto 4.00 V 0.50 V +LOAD  PEL-5020C-600-1400
Item SENSE LD-ON LD-OFF +LOAD  Model Item SENSE LD-ON LD-OFF +LOAD  Model Item SENSE	Initial value for CONIAuto 2.50 V 1.000V +LOAD  PEL-5008C-600-560 Initial value for CONIAuto 4.00 V 0.50 V +LOAD  PEL-5015C-600-1050 Initial value for DYN Auto	PEL-5010C-600-700 FIG Auto 2.50 V 1.000V +LOAD  PEL-5010C-600-700 FIG Auto 4.00 V 0.50 V +LOAD  PEL-5018C-600-1260  Auto	Auto 4.00 V 0.50 V +LOAD PEL-5012C-600-840 Auto 4.00 V 0.50 V +LOAD PEL-5020C-600-1400 Auto
Item SENSE LD-ON LD-OFF +LOAD  Model Item SENSE LD-ON LD-OFF +LOAD  Model Item SENSE LD-ON	Initial value for CONIAuto 2.50 V 1.000V +LOAD  PEL-5008C-600-560 Initial value for CONIAuto 4.00 V 0.50 V +LOAD  PEL-5015C-600-1050 Initial value for DYN Auto 4.00 V	PEL-5010C-600-700 FIG Auto 4.00 V +LOAD  PEL-5010C-600-700 FIG Auto 4.00 V 0.50 V +LOAD  PEL-5018C-600-1260  Auto 4.00 V	Auto 4.00 V 0.50 V +LOAD PEL-5012C-600-840 Auto 4.00 V 0.50 V +LOAD PEL-5020C-600-1400 Auto 4.00 V

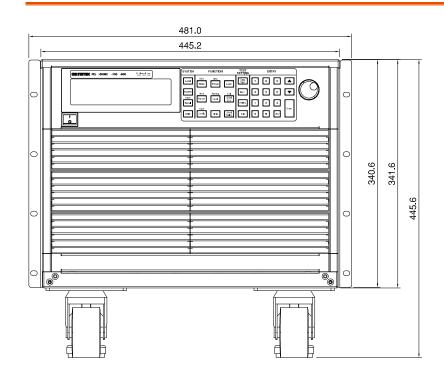


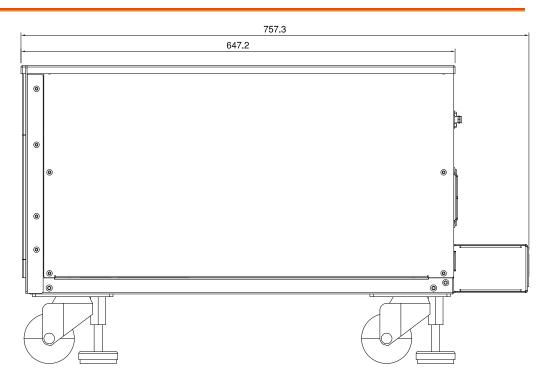
Model	PEL-5024C-600-1680	PEL-5006C-1200-240	PEL-5008C-1200-320
Item	Initial value for DYN		
SENSE	Auto	Auto	Auto
LD-ON	4.00 V	10.00 V	10.00 V
LD-OFF	0.50 V	5.00 V	5.00 V
+LOAD	+LOAD	+LOAD	+LOAD
Model	PEL-5010C-1200-400	PEL-5012C-1200-480	PEL-5015C-1200-600
Item	Initial value for DYN		
SENSE	Auto	Auto	Auto
LD-ON	10.00 V	10.00 V	10.00 V
LD-OFF	5.00 V	5.00 V	5.00 V
+LOAD	+LOAD	+LOAD	+LOAD
Model	PEL-5018C-1200-720	PEL-5020C-1200-800	PEL-5024C-1200-960
Model Item	PEL-5018C-1200-720 Initial value for DYN	PEL-5020C-1200-800	PEL-5024C-1200-960
		PEL-5020C-1200-800	PEL-5024C-1200-960
Item	Initial value for DYN		
Item SENSE	Initial value for DYN Auto	Auto	Auto
Item SENSE LD-ON	Initial value for DYN Auto 10.00 V	Auto 10.00 V	Auto 10.00 V
Item SENSE LD-ON LD-OFF	Initial value for DYN Auto 10.00 V 5.00 V	Auto 10.00 V 5.00 V	Auto 10.00 V 5.00 V
Item SENSE LD-ON LD-OFF	Initial value for DYN Auto 10.00 V 5.00 V	Auto 10.00 V 5.00 V	Auto 10.00 V 5.00 V
Item SENSE LD-ON LD-OFF +LOAD	Initial value for DYN Auto 10.00 V 5.00 V +LOAD	Auto 10.00 V 5.00 V	Auto 10.00 V 5.00 V
Item SENSE LD-ON LD-OFF +LOAD	Initial value for DYN Auto 10.00 V 5.00 V +LOAD All model	Auto 10.00 V 5.00 V	Auto 10.00 V 5.00 V
Item SENSE LD-ON LD-OFF +LOAD  Model Item	Initial value for DYN Auto 10.00 V 5.00 V +LOAD  All model Initial value	Auto 10.00 V 5.00 V	Auto 10.00 V 5.00 V
Item SENSE LD-ON LD-OFF +LOAD  Model Item SHORT	Initial value for DYN Auto 10.00 V 5.00 V +LOAD  All model Initial value Disable	Auto 10.00 V 5.00 V	Auto 10.00 V 5.00 V



# PEL-5000C Dimensions

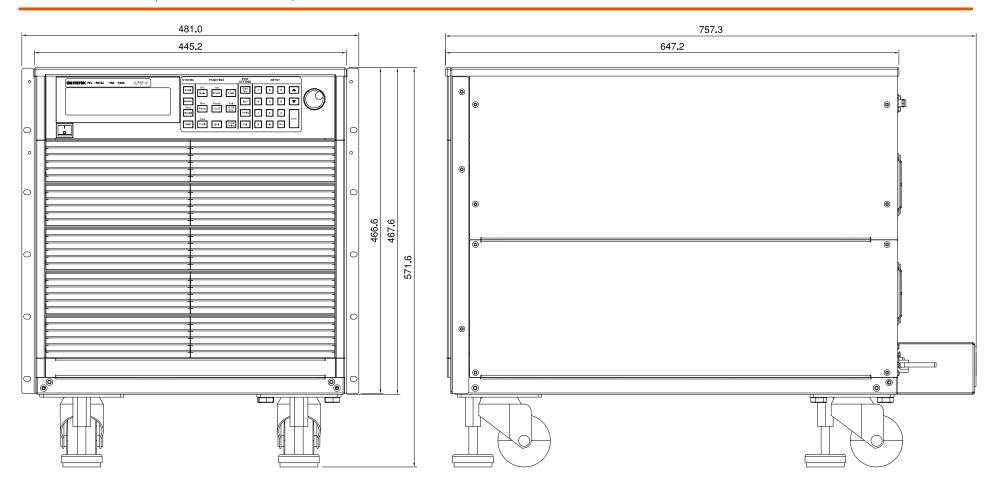
PEL-5006C-150-600, PEL-5006C-600-420, PEL-5006C-1200-240



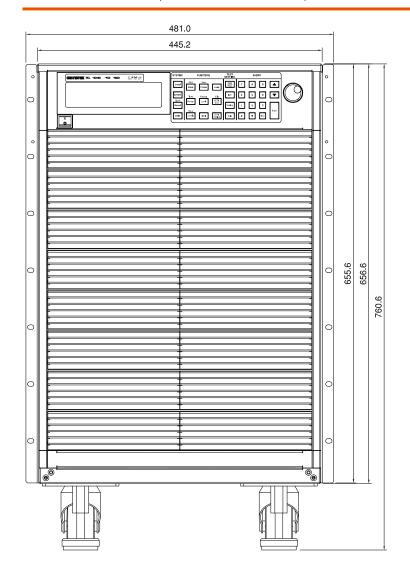


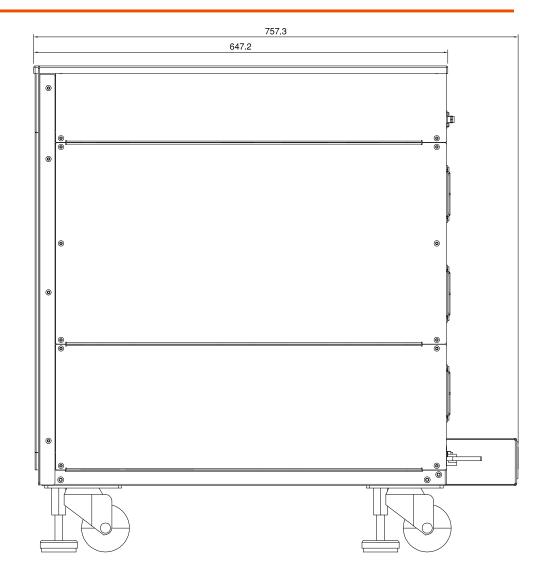


# PEL-5012C-150-1200, PEL-5012C-600-840, PEL-5012C-1200-480



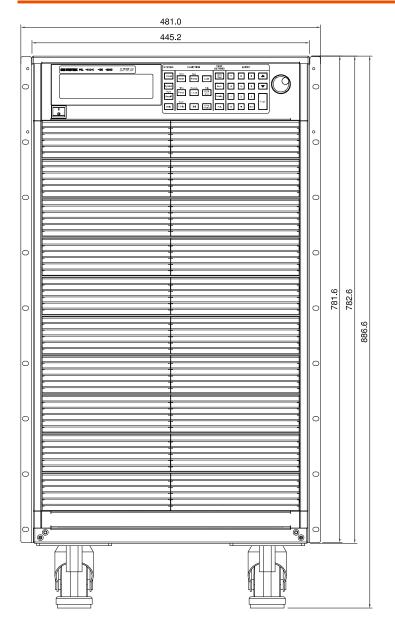
# PEL-5018C-150-1800, PEL-5018C-600-1260, PEL-5018C-1200-720

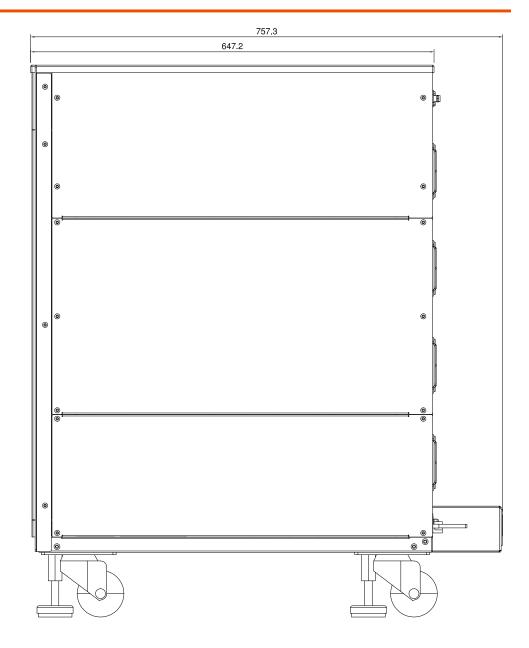




# **GWINSTEK**

# PEL-5024C-600-1680, PEL-5024C-1200-960





# PEL-5000C series Specifications

The specifications apply when the PEL-5000C is powered on for at least 30 minutes. Note that the high frequency and high voltage options are listed as separate specifications.

# PEL-5006C-150-600, PEL-5008C-150-800

Model	PEL-5006C-150-6	00	PEL-5008C-150-80	00
Power*1	6KW		8KW	
Current	0 ~ 60A	0 ~ 600A	0 ~ 80A	0 ~ 800A
Voltage	0 ~ 150V			
Min. Operating Voltage	e 0.7V@600A		0.7V@800A	
Protections				
Over Power Protection	(OPP) 105%			
Over Current Protectio	n(OCP) 104%			
Over Voltage Protectio				
Over Temp Protection	(OTP) 90°C±5°C			
Constant Current Mod	e			
Range*2	60A	600A	80A	800A
Resolution	0.96mA	9.6mA	1.28mA	12.8mA
Accuracy*3	± 0.05% of (Setting	ng + Range)		
Constant Resistance M	lode			
Range	$15000\Omega\sim0.25\Omega$	$0.25\Omega\sim0.0012\Omega$	11250Ω~ 0.1875Ω	$\Omega$ 0.1875 $\Omega$ ~ 0.0009 $\Omega$
Resolution	66.666μS	4.167μ $\Omega$	88.888μS	$3.125\mu\Omega$
Accuracy	± 0.2% of (Setting	g + Range)		
Constant Voltage Mod	e			
Range	150V			
Resolution	2.5mV			
Accuracy	± 0.05% of (Setti	ng + Range)		
Constant Power Mode				
Range	600W	6000W	800W	8000W
Resolution	9.6mW	96mW	12.8mW	128mW
Accuracy	± 0.1% of (Setting	0 ,		
Constant Voltage Mod		nt Mode		
Range	150V	600A	150V	800A
Resolution	2.5mV	9.6mA	2.5mV	12.8mA
Accuracy	± 1.0% of (Setting			
Constant Voltage Mod				
Range	150V	6000W	150V	8000W
Resolution	2.5mV	96mW	2.5mV	128mW
Accuracy	± 1.0% of (Setting	g + Range)		
Surge Test				
Surge & Normal currer			0~800A	
Surge time	10~1000ms			
Surge step	1~5			



MPPT Mode					
Algorithm	P & O				
Load mode	CV				
P&O interval	1000ms~60000ms; resolution 1000ms				
Dynamic Mode					
Timing					
Thigh & Tlow	0.010~9.999 / 99.9	9 / 999.9 / 9999m	S		
Resolution	0.001 / 0.01 / 0.1 /	1mS			
Accuracy	1μS/10μS/100μS/1	mS + 50ppm			
Slew rate	$0.0144A{\sim}~0.9A/\mu S$	0.144A ~ 9A/μS	0.0192A~ 1.2A/μS	5 0.192A ~ 12A/μS	
Resolution	0.0036A/μS	0.036Α/μS	0.0048A/μS	0.048A/μS	
Min. Rise Time	66.7μS (typical)				
Accuracy	± (5% of Setting) ±	:10μS			
Current					
Range	0 ~ 60A	60 ~ 600A	0 ~ 80A	80 ~ 800A	
Resolution	0.96mA	9.6mA	1.28mA	12.8mA	
Measurement					
Voltage Read Back					
Range (5 Digital)	0 ~ 15V	15 ~ 150V	0 ~ 15V	15 ~ 150V	
Resolution	0.25mV	2.5mV	0.25mV	2.5mV	
Accuracy	± 0.025% of (Readi	ng + Range)			
Current Read Back					
Range (5 Digital)	0 ~ 60A	60 ~ 600A	0 ~ 80A	80 ~ 800A	
Resolution	0.96mA	9.6mA	1.28mA	12.8mA	
Accuracy	± 0.05% of (Reading	ıg + Range)			
Power Read Back					
Range (5 Digital)	6000W		8000W		
Accuracy*4	± 0.06% of (Readin	ig + Range)			
General					
Typical Short	0.0012Ω		$0.0009\Omega$		
Resistance					
Maximum Short Current	600A		800A		
Load ON Voltage	0.25 ~ 62.5V				
Load OFF Voltage	0 ~ 62.5V				
Power Consumption	510VA		920VA		
Dimension(H x W x D	) 446mm x 444mn	n x 763mm	572mm x 444mm	ı x 763mm	
H x W x D (Not included wheels)	342mm x 444mn	n x 763mm	468mm x 444mm	n x 763mm	
Weight	62KG		77.5KG		
Temperature*5	0~40°C				
Safety & EMC	CE				
,					



Resolution

## PEL-5010C-150-1000, PEL-5012C-150-1200

Model PEL-5010C-150-1000 PEL-5012C-150-1200 Power\*1 12KW 10KW  $0 \sim 1000A$ 0 ~ 120A 0 ~ 1200A Current  $0 \sim 100A$ 0 ~ 150V Voltage 0.7V@1200A Min. Operating Voltage 0.7V@1000A **Protections** Over Power Protection (OPP) 105% Over Current Protection(OCP) 104% Over Voltage Protection(OVP) 105% Over Temp Protection (OTP) 90°C±5°C Constant Current Mode 100A 1000A 120A 1200A Range\*2 1.92mA 19.2mA Resolution 1.6mA 16mA Accuracy\*3 ± 0.05% of (Setting + Range) Constant Resistance Mode Range  $9000\Omega \sim 0.15\Omega$  $0.15\Omega \sim 0.0007\Omega$  $7500\Omega \sim 0.125\Omega$  $0.125\Omega \sim 0.0006\Omega$ 111.111μS 2.5μΩ 133.333μS  $2.084\mu\Omega$ Resolution Accuracy ± 0.2% of (Setting + Range) Constant Voltage Mode 150V Range Resolution 2 5mV Accuracy ± 0.05% of (Setting + Range) Constant Power Mode 10000W 1200W Range 1000W 12000W Resolution 16mW 160mW 19.2mW 192mW ± 0.1% of (Setting + Range) Accuracy Constant Voltage Mode + Constant Current Mode Range 150V 1000A 150V 1200A Resolution 3.2mA 2.5mV 19.2mA 2.5mV Accuracy ± 1.0% of (Setting + Range) Constant Voltage Mode + Constant Power Mode 150V 10000W 150V 12000W Range 160mW 2.5mV 192mW Resolution 2.5mV Accuracy ± 1.0% of (Setting + Range) Surge Test Surge & Normal current 0~1000A 0~1200A Surge time 10~1000ms 1~5 Surge step MPPT Mode Algorithm P & O Load mode CV P&O interval 1000ms~60000ms: resolution 1000ms Dynamic Mode Timing Thigh & Tlow 0.010~9.999 / 99.99 / 999.9 / 9999mS

0.001 / 0.01 / 0.1 / 1mS



Accuracy Slew rate Resolution Min. Rise Time Accuracy Current	1μS/10μS/100μS/ 0.024A~1.5A/μS 0.006A/μS 66.7μS (typical) ± (5% of Setting)	0.24A~15A/μS 0.06A/μS	0.0288A~1.8A/μS 0.0072A/μS	0.288A~18A/μS 0.072A/μS
Range	0 ~ 100A	100 ~ 1000A	0 ~ 120A	120 ~ 1200A
Resolution	1.6mA	16mA	1.92mA	19.2mA
Measurement				
Voltage Read Back				
Range (5 Digital)	0 ~ 15V	15 ~ 150V	0 ~ 15V	15 ~ 150V
Resolution	0.25mV	2.5mV	0.25mV	2.5mV
Accuracy	± 0.025% of (Rea	ding + Range)		
Current Read Back				
Range (5 Digital)	0~100A	100 ~ 1000A	0 ~ 120A	120 ~ 1200A
Resolution	1.6mA	16mA	1.92mA	19.2mA
Accuracy	± 0.05% of (Read	ing + Range)		
Power Read Back				
Range (5 Digital)	10000W	. 5 \	12000W	
Accuracy*4 General	± 0.06% of (Read	ing + Range)		
General Typical Short Resistar	0 00070		0.0006Ω	
Maximum Short	nce 0.000712		0.00002	
Current	1000A		1200A	
Load ON Voltage	0.25 ~ 62.5V			
Load OFF Voltage	0 ~ 62.5V			
Power Consumption	920VA			
Dimension(H x W x E	o) 572mm x 444m	m x 763mm		
H x W x D(Not includ wheels)	led 468mm x 444m	m x 763mm		
Weight	84.8KG		92KG	
Temperature *5	0~40°C			
Safety & EMC	CE			

# PEL-5015C-150-1500, PEL-5018C-150-1800

Model	PEL-5015C-150-1	500	PEL-5018C-150-1800			
Power*1	15KW		18KW			
Current	0 ~ 150A	0 ~ 1500A	0 ~ 180A	0 ~ 1800A		
Voltage	0 ~ 150V					
Min. Operating Voltage	e 0.7V@1500A		0.7V@1800A			
Protections						
Over Power Protection	(OPP) 105%					
Over Current Protectio	n(OCP) 104%					
Over Voltage Protectio	Over Voltage Protection(OVP) 105%					
Over Temp Protection(OTP) 90°C±5°C						
Constant Current Mode	e					
Range*2	150A	1500A	180A	1800A		
Resolution	2.4mA	24mA	2.88mA	28.8mA		



Accuracy*3	± 0.05% of (Settir	ıg + Range)		
Constant Resistance N	Mode			
Range	$6000\Omega$ ~ $0.1\Omega$	$0.1\Omega{\sim}~0.0005\Omega$	5000Ω~0.0833Ω	$0.0833\Omega{\sim}0.0004\Omega$
Resolution	166.666μS	1.667μΩ	200μS	$1.389 \mu \Omega$
Accuracy	± 0.2% of (Setting	g + Range)		
Constant Voltage Mod	de			
Range	150V			
Resolution	2.5mV			
Accuracy	± 0.05% of (Setting	ıg + Range)		
Constant Power Mode	·	<i>5</i> ,		
Range	1500W	15000W	1800W	18000W
Resolution	24mW	240mW	28.8mW	288mW
Accuracy	± 0.1% of (Setting	g + Range)		
Constant Voltage Mod	, ,			
Range	150V	1500A	150V	1800A
Resolution	2.5mV	24mA	2.5mV	28.8mA
Accuracy	± 1.0% of (Setting	+ Range)		
Constant Voltage Mod	, ,			
Range	150V	15000W	150V	18000W
Resolution	2.5mV	240mW	2.5mV	288mW
Accuracy	± 1.0% of (Setting			
Surge Test	2 11070 01 (0001111)	5		
Surge & Normal curre	ent 0~1500A		0~1800A	
Surge time	10~1000ms			
Surge step	1~5			
MPPT Mode				
Algorithm	P & O			
Load mode	CV			
P&O interval		ns ; resolution 1000	)ms	
Dynamic Mode	10001113 0000011	is, resolution root	J1113	
Timing				
Thigh & Tlow	0.010~9.999 / 99.99	9 / 999 9 / 9999mS		
Resolution	0.001 / 0.01 / 0.1 /	, ,		
Accuracy	1μS/10μS/100μS/1			
Slew rate	0.036A~2.25A/μS		0.04324 ~ 2.74/uS	0.432Δ ~ 27Δ/uS
Resolution		, ,	0.0108A/μS	0.108Α/μS
Min. Rise Time	66.7μS(typical)	ο.ουλημο	0.0100Α/μ5	ο. τουλή μο
Accuracy	± (5% of Setting) ±	105		
Current	± (370 01 3cttillg) ±	Τομο		
Range	0 ~ 150A	150 ~ 1500A	0 ~ 180A	180 ~ 1800A
Resolution	0 ~ 130A 2.4mA	24mA	0 ~ 180A 2.88mA	28.8mA
Measurement	2.4IIIA	24IIIA	2.00IIIA	20.011IA
Voltage Read Back				
Range (5 Digital)	0 ~ 15V	15 ~ 150V	0 ~ 15V	15 ~ 150V
Resolution	0.25mV	2.5mV	0.25mV	2.5mV
	± 0.025% of (Readi		U.ZJIIIV	Z.JIIIV
Accuracy Current Read Back	± 0.023/0 01 (Read)	ing + Namge)		
	0 ~ 150A	150 ~ 1500A	0 ~ 180A	180 ~ 1800A
Range (5 Digital) Resolution	0 ~ 130A 2.4mA	24mA	0 ~ 180A 2.88mA	28.8mA
VEZOINTIOLI	4.4IIIA	Z4111A	4.00IIIA	20.011IA

1800A

124KG



± 0.05% of (Reading + Range) Accuracy

Power Read Back

Range (5 Digital) 15000W 18000W

± 0.06% of (Reading + Range) Accuracy\*4

General

Typical Short Resistance 0.0005Ω  $0.0004\Omega$ 

Maximum Short Current

1500A

Load ON Voltage 0.25 ~ 62.5V Load OFF Voltage  $0 \sim 62.5 V$ 

1320VA Power Consumption Dimension(H x W x D) 761mm x 444mm x 763mm

HxWxD (Not

657mm x 444mm x 763mm

included wheels) Weight 116.5KG

0~40°C Temperature \*5 Safety & EMC CE

## PEL-5020C-150-2000, PEL-5024C-150-2000

PEL-5020C-150-2000 Model PEL-5024C-150-2000

Power\*1 20KW 24KW

 $0 \sim 200A$  $0 \sim 2000A$ 0 ~ 200A  $0 \sim 2000A$ Current

0 ~ 150V Voltage Min. Operating Voltage 0.7V@2000A

Protections

Over Power Protection (OPP) 105%

Over Current Protection (OCP) 104% Over Voltage Protection(OVP) 105%

Over Temp Protection(OTP) 90°C±5°C

Constant Current Mode

Range\*2 200A 2000A 200A 2000A Resolution 3.2mA 32mA 3.2mA 32mA

Accuracy\*3 ± 0.05% of (Setting + Range)

Constant Resistance Mode

 $4500\Omega$ ~  $0.075\Omega$   $0.075\Omega$ ~  $0.0004\Omega$   $4500\Omega$ ~  $0.075\Omega$  $0.075\Omega \sim 0.0004\Omega$ Range

Resolution 222.22µS 1.25μΩ 222.22µS 1.25μΩ

Accuracy ± 0.2% of (Setting + Range)

Constant Voltage Mode

Range 150V Resolution 2.5mV

± 0.05% of (Setting + Range) Accuracy

Constant Power Mode

Range 2000W 20000W 2400W 24000W 32mW 320mW 38.4mW 384mW Resolution

Accuracy ± 0.1% of (Setting + Range)

Constant Voltage Mode + Constant Current Mode

Range 150V 2000A 150V 2000A Resolution 2.5mV 32mA 2.5mV 32mA



Accuracy	± 1.0% of (Setti	0 0 /		
Constant Voltage Mod				
Range	150V	20000W	150V	24000W
Resolution	2.5mV	320mW	2.5mV	384mW
Accuracy	± 1.0% of (Setti	ng + Range)		
Surge Test				
Surge & Normal curre	ent 0~2000A			
Surge time	10~1000ms			
Surge step	1~5			
MPPT Mode				
Algorithm	P & O			
Load mode	CV			
P&O interval	1000ms~60000	Oms ; resolution 10	000ms	
Dynamic Mode				
Timing				
Thigh & Tlow	0.010~9.999 / 99.	.99 / 999.9 / 9999n	nS	
Resolution	0.001 / 0.01 / 0.1	/ 1mS		
Accuracy	1μS/10μS/100μS	/1mS + 50ppm		
Slew rate	$0.048A \sim 3A/\mu S$	$0.48A\sim30A/\mu S$	$0.048A\sim3A/\mu S$	$0.48A \sim 30A/\mu S$
Resolution	0.012A/μS	0.12A/μS	0.012A/μS	0.12A/μS
Min. Rise Time	66.7μS (typical)			
Accuracy	± (5% of Setting)	±10μS		
Current				
Range	0 ~ 200A	200 ~ 2000A	0 ~ 200A	200 ~ 2000A
Resolution	3.2mA	32mA	3.2mA	32mA
Measurement				
Voltage Read Back				
Range (5 Digital)	0 ~ 15V	15 ~ 150V	0 ~ 15V	15 ~ 150V
Resolution	0.25mV	2.5mV	0.25mV	2.5mV
Accuracy	± 0.025% of (Rea	ding + Range)		
Current Read Back				
Range (5 Digital)	0 ~ 200A	200 ~ 2000A	0 ~ 200A	200 ~ 2000A
Resolution	3.2mA	32mA	3.2mA	32mA
Accuracy	± 0.05% of (Read	ing + Range)		
Power Read Back				
Range (5 Digital)	20000W		24000W	
Accuracy*4	± 0.06% of (Read	ing + Range)		
General	,	· · · · · ·		
Typical Short Resistar	nce 0.0004Ω			
Maximum Short Curre	ent 2000A			
Load ON Voltage	0.25 ~ 62.5V			
Load OFF Voltage	0 ~ 62.5V			
Power Consumption	1700VA			
Dimension (H x W x D	) 884mm x 444m	nm x 763mm		
H x W x D (Not included wheels	780mm x 444m	nm x 763mm		
Weight	, 140.5KG		155KG	
Temperature *5	0~40°C			
Safety & EMC	CE			



# PEL-5006C-600-420, PEL-5008C-600-560

55000 000	3 120, 1 22 3	5555 555 5		
Model	PEL-5006C-600-42	20	PEL-5008C-600-56	50
Power*1	6KW		8KW	
Current	0 ~ 42A	0 ~420A	0 ~ 56A	0 ~ 560A
Voltage	0 ~ 600V			
Min. Operating Voltage	10V@420A		10V@560A	
Protections				
Over Power Protection	(OPP) 105%			
Over Current Protectio	n(OCP) 104%			
Over Voltage Protection	n(OVP) 105%			
Over Temp Protection(	OTP) 90°C±5°C			
Constant Current Mode	e			
Range*2	42A	420A	56A	560A
Resolution	0.672mA	6.72mA	0.896mA	8.96mA
Accuracy*3	± 0.05% of (Setting	ıg + Range)		
Constant Resistance M	ode			
Range	85712Ω~	1.42853Ω~	64284Ω~	1.0714Ω~
Karige	$1.42853\Omega$	0.02384Ω	1.0714Ω	0.01788Ω
Resolution	11.6669µS	23.84μΩ	15.5559µS	17.88μΩ
Accuracy	± 0.2% of (Setting	; + Range)		
Constant Voltage Mode	e			
Range	600V			
Resolution	10mV			
Accuracy	± 0.05% of (Setting	ıg + Range)		
Constant Power Mode				
Range	6000W	6000W	8000W	8000W
Resolution	9.6mW	96mW	12.8mW	128mW
Accuracy	± 0.2% of	± 0.1% of	± 0.2% of	± 0.1% of
·			(Setting + Range)	(Setting + Range)
Constant Voltage Mode				
Range	600V	420A	600V	560A
Resolution	10mV	6.72mA	10mV	8.96mA
Accuracy	± 1.0% of (Setting			
Constant Voltage Mode				
Range	600V	6000W	600V	8000W
Resolution	10mV	96mW	10mV	128mW
Accuracy	± 1.0% of (Setting	g + Range)		
Surge Test				
Surge & Normal currer			0~560A	
Surge time	10~1000ms			
Surge step	1~5			
MPPT Mode				
Algorithm	P & O			
Load mode	CV			
P&O interval	1000ms~60000m	ns; resolution 1000	Oms	



Daniel Med						
Dynamic Mode						
Timing	0.010.0.000.100	00 / 000 0 / 0000	~			
Thigh & Tlow	0.010~9.999 / 99.99 / 999.9 / 9999mS					
Resolution	0.001 / 0.01 / 0.1 / 1mS					
Accuracy		1μS/10μS/100μS/1mS + 50ppm				
Slew rate	• •	S 0.288A ~ 18A/μS	• •	S 0.288A ~ 18A/μS		
Resolution	0.0072A/μS	0.072A/μS	0.0072A/μS	0.072A/μS		
Min. Rise Time	66.7μS (typical)					
Accuracy	± (5% of Setting)	±10μS				
Current						
Range	0 ~ 42A	42 ~ 420A	0 ~ 56A	56 ~ 560A		
Resolution	0.672mA	6.72mA	0.896mA	8.96mA		
Measurement						
Voltage Read Back						
Range (5 Digital)	0 ~ 60V	60 ~ 600V	0 ~ 60V	60 ~ 600V		
Resolution	1mV	10mV	1mV	10mV		
Accuracy	± 0.025% of (Rea	ding + Range)				
Current Read Back						
Range (5 Digital)	0 ~ 42A	42 ~ 420A	0 ~ 56A	56 ~ 560A		
Resolution	0.672mA	6.72mA	0.896mA	8.96mA		
Accuracy	± 0.05% of (Rea	ading + Range)				
Power Read Back						
Range (5 Digital)	6000W		8000W			
Accuracy*4	± 0.06% of (Rea	ading + Range)				
General						
Typical Short	0.0239Ω		0.0179Ω			
Resistance	0.023322		0.017522			
Maximum Short	420A		560A			
Current	.2071		3007.			
Load ON Voltage	0.4 ~ 100V					
Load OFF Voltage	0 ~ 100V					
Power Consumption			920VA			
Dimension(H x W x	D) 446mm x 444m	ım x 763mm	572mm x 444mr	m x 763mm		
HxWxD	342mm x 444m	ım x 763mm	468mm x 444mr	m x 763mm		
(Not included wheel	ls)					
Weight	62KG		77.5KG			
Temperature *5	0~40°C					
Safety & EMC	CE					

# PEL-5010C-600-700, PEL-5012C-600-840

Model	PEL-5010C-600-	PEL-5010C-600-700		PEL-5012C-600-840		
Power*1	10KW		12KW			
Current	0 ~ 70A	0 ~ 700A	0 ~ 84A	0 ~ 840A		
Voltage	0 ~ 600V					
Min. Operating Voltage 10V@700A			10V@840A			
Protections						
Over Power Protection (OPP) 105%						

Over Power Protection (OPP) 105%
Over Current Protection (OCP) 104%



Core Temp Protection(OTP)         90°C±5°C           Constant Current Mode-Range**2         70A         700A         84A         840A           Range**2         ± 0.05% of (Setting + Range)         1.344mA         13.44mA           Accuracy**3         ± 0.05% of (Setting + Range)         0.714267Ω         0.714267Ω           Constant Resistance Mode-Range         \$1427.2Ω         0.014304Ω         0.714267Ω         0.01192Ω           Resolution         19.4449µS         14.304uΩ         23.3339µS         11.92uΩ           Accuracy         ± 0.2% of (Setting + Range)         1.92uΩ           Constant Voltage Mode-Range         600V         Range         1.00V           Resolution         10mV         1.000W         1200W         12000W           Range         10mV         160mW         19.2mW         192mW           Accuracy         ± 0.2% of         ± 0.1% of         ± 0.2% of         ± 0.1% of           Accuracy         ± 0.2% of         ± 0.1% of         ± 0.2% of         ± 0.1% of           Constant Voltage Mode + Constant Current Mode         Range         600V         700A         600V         840A           Range         600V         10.2mQ         10.2mQ         10.2mQ         10.2mQ </th <th colspan="5">Over Voltage Protection(OVP) 105%</th>	Over Voltage Protection(OVP) 105%				
Range*2         70A         700A         84A         840A           Resolution         1.12mA         11.2mA         13.44mA         13.44mA           Accuracy*3*** ± 0.05% of (Settling + Range)         □         □         0.714267Ω**         □           Constant Resistance Mode         □         0.85712Ω**         0.85712Ω**         0.714267Ω**         0.714267Ω**           Range         0.85712Ω**         0.14304Ω**         0.714267Ω**         0.01192Ω**           Resolution         19.4449μ\$**         14.304μΩ**         23.3339μ\$**         11.92μΩ**           Accuracy         ± 0.2% of (Settling + Range)         □	Over Temp Protectio	n(OTP) 90°C±5°C			
Resolution         1.12mA         11.2mA         1.344mA         13.44mA           Accuracy*3         ± 0.05% of (Setting + Range)         V           Constant Resistance Word           Range         \$1427.2Ω~         0.85712Ω         42856Ω~         0.714267Ω~           0.85712Ω         0.014304Ω         23.3339μS         11.92μΩ           Resolution         19.4449μS         14.304μΩ         23.3339μS         11.92μΩ           Accuracy         ± 0.2% of (Setting + Range)         V         V           Constant Voltage Mode         ± 0.05% of (Setting + Range)         V         V           Constant Power Mode         Early         ± 0.000	Constant Current Mo	de			
Accuracy	Range*2	70A	700A	84A	840A
Constant Resistance Mode           Range $51427.2\Omega$ ~ $0.85712\Omega$ $0.014304\Omega$ $0.714267\Omega$ $0.01192\Omega$ Resolution $19.4449\mu$ S $14.304u\Omega$ $23.3339\mu$ S $11.92u\Omega$ Accuracy $\pm 0.2\%$ of (Setting + Range) $1.92u\Omega$ Constant Voltage Mode         Range $600V$ Resolution $10mV$ $1000W$ $1200W$ $12000W$ Resolution $16mW$ $160mW$ $19.2mW$ $192mW$ Constant Power Mode         Range $16mW$ $160mW$ $19.2mW$ $192mW$ Resolution $16mW$ $160mW$ $19.2mW$ $192mW$ Accuracy $\pm 0.2\%$ of $\pm 0.1\%$ of $\pm 0.2\%$ of $\pm 0.2\%$ of $\pm 0.1\%$ of $\pm 0.2\%$ of $\pm 0.2\%$ of $\pm 0.1\%$ of $\pm 0.2\%$ of $\pm 0.2\%$ of $\pm 0.1\%$ of $\pm 0.2\%$ of $\pm 0.2\%$ of $\pm 0.2\%$ of $\pm 0.1\%$ of $\pm 0.2\%$ of $\pm$	Resolution	1.12mA	11.2mA	1.344mA	13.44mA
Range         51427.2Ω — 0.85712Ω — 0.014304Ω — 0.714267Ω — 0.01192Ω           Resolution         19.4449µS — 14.304µΩ — 23.3339µS — 11.92µΩ           Accuracy         ± 0.2% of (Setting + Range)           Constant Voltage Mode-Range         600V           Range         600V           Resolution         10mV           Accuracy         ± 0.05% of (Setting + Range)           Constant Power Mode         Constant Power Mode           Range         1000W         10000W         1200W         12000W           Resolution         16mW         160mW         19.2mW         192mW           Resolution         16mW         160mW         19.2mW         192mW           Accuracy         ± 0.2% of         ± 0.1% of         ± 0.2% of         ± 0.1% of           Range         600V         1700A         600V         ± 0.1% of           Range         600V         700A         600V         840A           Resolution         10mV         11.2mA         10mV         13.44mA           Accuracy         ± 1.0% of (Setting + Range)         20.000W         2000W           Resolution         10mV         160mW         10mV         192mW           Accuracy         ± 1.0% of (Setting + Range)	Accuracy*3	± 0.05% of (Setti	ng + Range)		
Range         0.85712Ω         0.014304Ω         0.714267Ω         0.01192Ω           Resolution         19.4449µS         14.304uΩ         23.3339µS         11.92uΩ           Accuracy         ± 0.2% of (Setting + Range)	Constant Resistance	Mode			
Nesolution   19.4449µS   14.304µΩ   23.3339µS   11.92µΩ	Range	51427.2Ω~	0.85712Ω~	42856Ω~	0.714267Ω~
Accuracy	Kange	0.85712Ω	$0.014304\Omega$	$0.714267\Omega$	0.01192Ω
Constant Voltage Mode   Range   600V   Resolution   10mV   Accuracy   ± 0.05% of (Setting + Range)   Constant Power Mode   Range   1000W   10000W   1200W   12000W   Resolution   16mW   160mW   19.2mW   192mW   192mW   ± 0.2% of   ± 0.1% of   ± 0.2% of   ± 0.1% of   ± 0.2% of   ± 0.1% of   Estting + Range)   (Setting + Ran	Resolution	19.4449μS	14.304uΩ	23.3339μS	11.92u $Ω$
Range       600V         Resolution       10mV         Accuracy       ± 0.05% of (Setting + Range)         Constant Power Mode         Range       1000W       10000W       1200W       12000W         Resolution       16mW       160mW       19.2mW       192mW         Accuracy       ± 0.2% of       ± 0.1% of       ± 0.2% of       ± 0.1% of         Constant Voltage Mode + Constant Current Mode       Kange       600V       700A       600V       840A         Resolution       10mV       11.2mA       10mV       13.44mA         Accuracy       ± 1.0% of (Setting + Range)       V       Constant Voltage Mode + Constant Power Mode         Range       600V       10000W       600V       12000W         Resolution       10mV       160mW       10mV       192mW         Accuracy       ± 1.0% of (Setting + Range)       V       10mV       192mW         Accuracy       ± 1.0% of (Setting + Range)       V       10mV       192mW         Accuracy       ± 1.0% of (Setting + Range)       V       10mV       192mW         Accuracy       ± 1.0% of (Setting + Range)       V       10mV       192mW         Accuracy       ± 1.0% of (Setting + Range	Accuracy	± 0.2% of (Settin	g + Range)		
Resolution   10mV   Accuracy   ± 0.05% of (Setting + Range)   Constant Power Mode	Constant Voltage Mo	de			
Accuracy	Range	600V			
Constant Power Mode   Range	Resolution	10mV			
Range         1000W         10000W         1200W         12000W           Resolution         16mW         160mW         19.2mW         192mW           Accuracy         ± 0.2% of         ± 0.1% of         ± 0.2% of         ± 0.1% of           Constant Voltage Mode + Constant Current Mode         Kesting + Range)         (Setting + Range)         (Setting + Range)         (Setting + Range)         600V         840A           Resolution         10mV         11.2mA         10mV         13.44mA         10mV         13.44mA           Accuracy         ± 1.0% of (Setting + Range)         Union         12000W         12000W         12000W         12000W         Resolution         10mV         192mW         192mW         1000W         10mV         10mV         1000W         10mV         10mV </td <td>Accuracy</td> <td>± 0.05% of (Setti</td> <td>ng + Range)</td> <td></td> <td></td>	Accuracy	± 0.05% of (Setti	ng + Range)		
Resolution   16mW   160mW   19.2mW   192mW   40.2% of	Constant Power Mod	e			
Accuracy         ± 0.2% of (Setting + Range)         ± 0.1% of (Setting + Range)         ± 0.2% of (Setting + Range)         ± 0.1% of (Setting + Range)           Constant Voltage Mode + Constant Current Mode         Range         600V         700A         600V         840A           Range         600V         700A         600V         13.44mA           Accuracy         ± 1.0% of (Setting + Range)	Range	1000W	10000W	1200W	12000W
Accuracy         (Setting + Range)           Constant Voltage Mode + Constant Current Mode         Range         600V         700A         600V         840A           Resolution         10mV         11.2mA         10mV         13.44mA           Accuracy         ± 1.0% of (Setting + Range)         Constant Voltage Mode + Constant Power Mode         Constant Voltage Mode + Constant Power Mode           Range         600V         10000W         600V         12000W           Resolution         10mV         160mW         10mV         192mW           Accuracy         ± 1.0% of (Setting + Range)         Surge Set Set Set Set Set Set Set Set Set Se	Resolution	16mW	160mW	19.2mW	192mW
Constant Voltage Mode + Constant Current Mode	Accuracy	± 0.2% of	± 0.1% of	± 0.2% of	± 0.1% of
Range       600V       700A       600V       840A         Resolution       10mV       11.2mA       10mV       13.44mA         Accuracy       ± 1.0% of (Setting + Range)       Constant Voltage Mode + Constant Power Mode         Range       600V       10000W       600V       12000W         Resolution       10mV       160mW       10mV       192mW         Accuracy       ± 1.0% of (Setting + Range)         Surge Test         Surge time       10~1000ms       0~840A         Surge step       1~5         MPPT Mode         Algorithm       P & O         Load mode       CV         P&O interval       1000ms~60000ms ; resolution 1000ms         Dynamic Mode       Timing         Thigh & Tlow       0.010~9.999 / 99.99 / 999.9 / 9999mS         Resolution       0.001 / 0.01 / 0.1 / 1mS         Accuracy       1µS/10µS/100µS/1mS + 50ppm         Slew rate       0.0336A ~ 2.1A/µS 0.336A ~ 21A/µS 0.0384A ~ 2.4A/µS 0.384A ~ 2.4A/µS 0.096A/µS         Resolution       0.0084A/µS 0.084A/µS 0.0096A/µS 0.096A/µS	Accuracy	(Setting + Range	(Setting + Range	) (Setting + Range)	(Setting + Range)
Resolution       10mV       11.2mA       10mV       13.44mA         Accuracy       ± 1.0% of (Setting + Range)       Constant Voltage Mode + Constant Power Mode         Range       600V       10000W       600V       12000W         Resolution       10mV       160mW       10mV       192mW         Accuracy       ± 1.0% of (Setting + Range)       Surge Test         Surge time       10~1000ms       Surge step       1~5         MPPT Mode       Algorithm       P & O         Load mode       CV         P&O interval       1000ms~60000ms; resolution 1000ms         Dynamic Mode       Timing         Thigh & Tlow       0.010~9.999 / 99.99 / 999.9 / 9999mS         Resolution       0.001 / 0.01 / 0.1 / 1mS         Accuracy       1µS/10µS/100µS/1mS + 50ppm         Slew rate       0.0336A ~ 2.1A/µS 0.336A ~ 21A/µS 0.096A/µS       0.096A/µS         Resolution       0.0084A/µS       0.084A/µS       0.0096A/µS	Constant Voltage Mo				
Accuracy ± 1.0% of (Setting + Range)  Constant Voltage Mode + Constant Power Mode  Range 600V 10000W 600V 12000W  Resolution 10mV 160mW 10mV 192mW  Accuracy ± 1.0% of (Setting + Range)  Surge Test  Surge & Normal current 0~700A 0~840A  Surge time 10~1000ms  Surge step 1~5  MPPT Mode  Algorithm P & O  Load mode CV  P&O interval 1000ms~60000ms; resolution 1000ms  Dynamic Mode  Timing  Thigh & Tlow 0.010~9.999 / 99.99 / 999.99 / 9999mS  Resolution 0.001 / 0.01 / 0.1 / 1mS  Accuracy 1μS/10μS/100μS/1mS + 50ppm  Slew rate 0.0336A ~ 2.1A/μS 0.336A ~ 21A/μS 0.096A/μS 0.096A/μS	Range	600V	700A	600V	840A
Constant Voltage Mode + Constant Power Mode         Range       600V       10000W       600V       12000W         Resolution       10mV       160mW       10mV       192mW         Accuracy       ± 1.0% of (Setting + Range)         Surge Test         Surge & Normal current 0~700A       0~840A         Surge time       10~1000ms         Surge step       1~5         MPPT Mode         Algorithm       P & O         Load mode       CV         P&O interval       1000ms~60000ms; resolution 1000ms         Dynamic Mode         Timing         Thigh & Tlow       0.010~9.999 / 99.99 / 999.9 / 9999mS         Resolution       0.001 / 0.01 / 0.1 / 1mS         Accuracy       1µS/10µS/100µS/1mS + 50ppm         Slew rate       0.0336A ~ 2.1A/µS 0.336A ~ 21A/µS 0.0384A ~ 2.4A/µS 0.384A ~ 2.4A/µS 0.096A/µS         Resolution       0.0084A/µS 0.084A/µS 0.0096A/µS 0.096A/µS	Resolution	10mV	11.2mA	10mV	13.44mA
Range       600V       10000W       600V       12000W         Resolution       10mV       160mW       10mV       192mW         Accuracy       ± 1.0% of (Setting + Range)         Surge Test       Surge & Normal current 0~700A       0~840A         Surge time       10~1000ms         Surge step       1~5         MPPT Mode       Algorithm       P & O         Load mode       CV         P&O interval       1000ms~60000ms; resolution 1000ms         Dynamic Mode       Timing         Thigh & Tlow       0.010~9.999 / 99.99 / 999.9 / 9999mS         Resolution       0.001 / 0.01 / 0.1 / 1mS         Accuracy       1µS/10µS/100µS/1mS + 50ppm         Slew rate       0.0336A ~ 2.1A/µS 0.336A ~ 21A/µS 0.084A/µS 0.096A/µS 0.096A/µS	Accuracy	± 1.0% of (Settin	g + Range)		
Resolution 10mV 160mW 10mV 192mW Accuracy $\pm 1.0\%$ of (Setting + Range) Surge Test Surge & Normal current 0~700A 0~840A Surge time 10~1000ms Surge step 1~5 MPPT Mode Algorithm P & O Load mode CV P&O interval 1000ms $= 10000$ s $= 1000$ s $=$	Constant Voltage Mo	de + Constant Powe	r Mode		
Accuracy $\pm 1.0\%$ of (Setting + Range) Surge Test Surge & Normal current 0~700A 0~840A Surge time 10~1000ms Surge step 1~5 MPPT Mode Algorithm P & O Load mode CV P&O interval 1000ms~60000ms; resolution 1000ms Dynamic Mode Timing Thigh & Tlow 0.010~9.999 / 99.99 / 9999mS Resolution 0.001 / 0.01 / 0.1 / 1mS Accuracy 1 $\mu$ S/10 $\mu$ S/100 $\mu$ S/100 $\mu$ S/1mS + 50ppm Slew rate 0.0336A ~ 2.1A/ $\mu$ S 0.336A ~ 21A/ $\mu$ S 0.096A/ $\mu$ S 0.096A/ $\mu$ S 0.096A/ $\mu$ S	Range	600V	10000W	600V	12000W
Surge Test  Surge & Normal current 0~700A 0~840A  Surge time 10~1000ms  Surge step 1~5  MPPT Mode  Algorithm P & O  Load mode CV  P&O interval 1000ms~60000ms; resolution 1000ms  Dynamic Mode  Timing  Thigh & Tlow 0.010~9.999 / 99.99 / 9999mS  Resolution 0.001 / 0.01 / 0.1 / 1mS  Accuracy 1μS/10μS/100μS/1mS + 50ppm  Slew rate 0.0336A ~ 2.1A/μS 0.336A ~ 21A/μS 0.096A/μS 0.096A/μS	Resolution	10mV	160mW	10mV	192mW
Surge & Normal current 0~700A 0~840A  Surge time 10~1000ms  Surge step 1~5  MPPT Mode  Algorithm P & O  Load mode CV  P&O interval 1000ms~60000ms; resolution 1000ms  Dynamic Mode  Timing  Thigh & Tlow 0.010~9.999 / 99.99 / 999.99 / 9999mS  Resolution 0.001 / 0.01 / 0.1 / 1mS  Accuracy 1μS/10μS/100μS/1mS + 50ppm  Slew rate 0.0336A ~ 2.1A/μS 0.336A ~ 21A/μS 0.0384A ~ 2.4A/μS 0.384A ~ 24A/μS  Resolution 0.0084A/μS 0.084A/μS 0.0096A/μS 0.096A/μS	Accuracy	± 1.0% of (Settin	g + Range)		
Surge time 10~1000ms Surge step 1~5  MPPT Mode  Algorithm P & O  Load mode CV  P&O interval 1000ms~60000ms; resolution 1000ms  Dynamic Mode  Timing Thigh & Tlow 0.010~9.999 / 99.99 / 9999mS  Resolution 0.001 / 0.01 / 0.1 / 1mS  Accuracy 1μS/10μS/100μS/1mS + 50ppm  Slew rate 0.0336A ~ 2.1A/μS 0.336A ~ 21A/μS 0.0384A ~ 2.4A/μS 0.384A ~ 24A/μS  Resolution 0.0084A/μS 0.084A/μS 0.0096A/μS 0.096A/μS	Surge Test				
Surge step 1~5 MPPT Mode  Algorithm P & O  Load mode CV  P&O interval 1000ms~60000ms; resolution 1000ms  Dynamic Mode  Timing Thigh & Tlow 0.010~9.999 / 99.99 / 99999 S  Resolution 0.001 / 0.01 / 0.1 / 1mS  Accuracy 1μS/10μS/100μS/1mS + 50ppm  Slew rate 0.0336A ~ 2.1A/μS 0.336A ~ 21A/μS 0.0384A ~ 2.4A/μS 0.384A ~ 24A/μS  Resolution 0.0084A/μS 0.084A/μS 0.0096A/μS 0.096A/μS	Surge & Normal curr	ent 0~700A		0~840A	
MPPT Mode Algorithm P & O Load mode CV P&O interval 1000ms-60000ms; resolution 1000ms  Dynamic Mode Timing Thigh & Tlow 0.010~9.999 / 99.99 / 9999mS  Resolution 0.001 / 0.01 / 0.1 / 1mS  Accuracy 1μS/10μS/100μS/1mS + 50ppm  Slew rate 0.0336A ~ 2.1A/μS 0.336A ~ 21A/μS 0.0384A ~ 2.4A/μS 0.384A ~ 24A/μS  Resolution 0.0084A/μS 0.084A/μS 0.0096A/μS	Surge time	10~1000ms			
$\begin{tabular}{lllllllllllllllllllllllllllllllllll$	Surge step	1~5			
$\begin{tabular}{l lllllllllllllllllllllllllllllllllll$	MPPT Mode				
P&O interval       1000ms~60000ms ; resolution 1000ms         Dynamic Mode         Timing         Thigh & Tlow       0.010~9.999 / 99.99 / 999.9 / 9999mS         Resolution       0.001 / 0.01 / 0.1 / 1mS         Accuracy       1µS/10µS/100µS/1mS + 50ppm         Slew rate       0.0336A ~ 2.1A/µS 0.336A ~ 21A/µS 0.0384A ~ 2.4A/µS 0.384A ~ 24A/µS         Resolution       0.0084A/µS 0.084A/µS 0.0096A/µS 0.096A/µS	Algorithm	P & O			
Dynamic Mode         Timing       0.010~9.999 / 99.99 / 999.99 / 9999mS         Resolution       0.001 / 0.01 / 0.1 / 1mS         Accuracy       1μS/10μS/100μS/1mS + 50ppm         Slew rate       0.0336A ~ 2.1A/μS 0.336A ~ 21A/μS 0.0384A ~ 2.4A/μS 0.384A ~ 24A/μS         Resolution       0.0084A/μS 0.084A/μS 0.0096A/μS 0.096A/μS	Load mode	CV			
Timing Thigh & Tlow $0.010-9.999 \ / \ 99.99 \ / \ 999.99 \ / \ 9999mS$ Resolution $0.001 \ / \ 0.01 \ / \ 0.1 \ / \ 1mS$ Accuracy $1\mu S \ / \ 10\mu S $	P&O interval	1000ms~60000r	ns ; resolution 100	00ms	
$ \begin{array}{llllllllllllllllllllllllllllllllllll$	Dynamic Mode				
$\begin{tabular}{lllllllllllllllllllllllllllllllllll$	Timing				
Accuracy $1\mu S/10\mu S/100\mu S/1mS + 50ppm$ Slew rate         0.0336A ~ 2.1A/μS 0.336A ~ 21A/μS         0.0384A ~ 2.4A/μS 0.384A ~ 24A/μS           Resolution         0.0084A/μS         0.084A/μS         0.0096A/μS         0.096A/μS	Thigh & Tlow	0.010~9.999 / 99.99	/ 999.9 / 9999mS		
Slew rate 0.0336A ~ 2.1A/μS 0.336A ~ 21A/μS 0.0384A ~ 2.4A/μS 0.384A ~ 24A/μS Resolution 0.0084A/μS 0.084A/μS 0.0096A/μS 0.096A/μS	Resolution	0.001 / 0.01 / 0.1 /	lmS		
Resolution 0.0084A/ $\mu$ S 0.084A/ $\mu$ S 0.0096A/ $\mu$ S 0.096A/ $\mu$ S	Accuracy	1μS/10μS/100μS/1ι	mS + 50ppm		
Resolution 0.0084A/ $\mu$ S 0.084A/ $\mu$ S 0.0096A/ $\mu$ S 0.096A/ $\mu$ S	Slew rate			0.0384A ~ 2.4A/μS	0.384A ~ 24A/μS
Accuracy $\pm$ (5% of Setting) $\pm$ 10 $\mu$ S	Resolution	0.0084Α/μS	).084A/μS	0.0096A/μS	0.096A/μS
		,,	, . Ι0μS	, .	
Current	•		•		
Range 0 ~ 70A 70 ~ 700A 0 ~ 84A 84 ~ 840A	Range	0 ~ 70A	70 ~ 700A	0 ~ 84A	84 ~ 840A
Resolution 1.12mA 11.2mA 1.334mA 13.34mA	Resolution	1.12mA	11.2mA	1.334mA	13.34mA



Measurement				
Voltage Read Back				
•	0 ~ 60V	60 ~ 600V	0 ~ 60V	60 ~ 600V
	1mV	10mV	1mV	10mV
	± 0.025% of (Read		11114	TOTTIV
Current Read Back	± 0.023/0 01 (Near	unig + Kange)		
	0 ~ 70A	70 ~ 700A	0 ~ 84A	84 ~ 840A
Resolution	1.12mA	11.2mA	1.334mA	13.34mA
	± 0.05% of (Read		1.5541117	13.54111/4
Power Read Back	± 0.0370 01 (11caa	ing i Runge)		
Range (5 Digital)	10000W		12000W	
Accuracy *4	± 0.06% of (Read	ing + Range)	12000 W	
General	_ 0.00,0 o. (a.a.	66-/		
Typical Short				
Resistance	0.0143Ω		0.00120Ω	
Maximum Short				
Current	700A		840A	
Load ON Voltage	0.4 ~ 100V			
Load OFF Voltage	0 ~ 100V			
Power Consumption	920VA			
Dimension (H x W x D)	) 572mm x 444m	m x 763mm		
H x W x D (Not	. 460 444	763		
included wheels)	468mm x 444m	m x /63mm		
Weight	84.8KG		92KG	
Temperature *5	0~40°C			
Safety & EMC	CE			

# PEL-5015C-600-1050, PEL-5018C-600-1260

Model	PEL-5015C-600-1	1050	PEL-5018C-600-1260		
Power*1	15KW		18KW		
Current	0 ~ 105A	0 ~ 1050A	0 ~ 126A	0 ~ 1260A	
Voltage	0 ~ 600V				
Min. Operating Voltag	ge 10V@1050A		10V@1260A		
Protections					
Over Power Protection	1(OPP) 105%				
Over Current Protection	on(OCP) 104%				
Over Voltage Protection	on(OVP) 105%				
Over Temp Protection	(OTP) 90°C±5°C	•			
Constant Current Mod	le				
Range*2	105A	1050A	126A	1260A	
Resolution	1.68mA	16.8mA	2.016mA	20.16mA	
Accuracy*3	± 0.05% of (Sett	ing + Range)			
Constant Resistance Mode					
D	34284.8 ~	0.571413~	28570.67Ω~	$0.476178\Omega \sim$	
Range	$0.571413\Omega$	$0.009536\Omega$	$0.476178\Omega$	$0.007947\Omega$	
Resolution	29.1674μS	$9.536\mu\Omega$	35.0009μS	$7.947\mu\Omega$	
Accuracy	± 0.2% of (Setting	g + Range)			



Constant Voltage Me	ode			
Range	600V			
Resolution	10mV			
Accuracy	± 0.05% of (Set	ting + Range)		
Constant Power Mod	de			
Range	1500W	15000W	1800W	18000W
Resolution	24mW	240mW	28.8mW	288mW
	± 0.2% of	± 0.1% of	± 0.2% of	± 0.1% of
Accuracy	(Setting + Rang	e) (Setting + Range	e) (Setting + Range)	(Setting + Range)
Constant Voltage Me			, (	, , , , , , , , , , , , , , , , , , , ,
Range	600V	1050A	600V	1260A
Resolution	10mV	16.8mA	10mV	20.16mA
Accuracy	± 1.0% of (Setti	ng + Range)		
Constant Voltage Me	ode + Constant Pow	ver Mode		
Range	600V	15000W	600V	18000W
Resolution	10mV	240mW	10mV	288mW
Accuracy	± 1.0% of (Setti	ng + Range)		
Surge Test	,	0 0,		
Surge & Normal cur	rent 0~1050A		0~1260A	
Surge time	10~1000ms			
Surge step	1~5			
MPPT Mode				
Algorithm	P & O			
Load mode	CV			
P&O interval	1000ms~60000	Oms ; resolution 10	00ms	
Dynamic Mode		,		
Timing				
Thigh & Tlow	0.010~9.999 / 99.9	9 / 999.9 / 9999mS		
Resolution	0.001 / 0.01 / 0.1 /			
Accuracy	1μS/10μS/100μS/			
Slew rate	0.0432A ~ 2.7A/µS		0.048A ~ 3A/µS	0.48A ~ 30A/µS
Resolution	0.0108A/µS	0.108A/µS	0.012A/µS	0.12A/μS
Accuracy	± (5% of Setting) ±	, .	0.0.27.7 p.0	υ <u>-</u> , , μο
Current	± (370 01 3cttill6) =	11043		
Range	0 ~ 105A	105 ~ 1050A	0 ~ 126A	126 ~ 1260A
Resolution	1.68mA	16.8mA	2.016mA	20.16mA
Measurement	1.0011174	10.011174	2.01011174	20.10111/4
Voltage Read Back				
Range (5 Digital)	0 ~ 60V	60 ~ 600V	0 ~ 60V	60 ~ 600V
Resolution	1mV	10mV	1mV	10mV
Accuracy	± 0.025% of (Read		11114	TOTTIV
Current Read Back	± 0.02370 OI (Nead	ing + Kange)		
Range (5 Digital)	0 ~ 105A	105 ~ 1050A	0 ~ 126A	126 ~ 1260A
,	1.68mA	16.8mA	2.016mA	20.16mA
Resolution			2.010IIIA	20.1011IA
Accuracy				
Power Post Past	± 0.05% of (Reading	ig + Kalige)		
Power Read Back	,	ig + Kalige)	18000//	
Power Read Back Range (5 Digital) Accuracy *4	± 0.05% of (Reading 15000W) ± 0.06% of (Reading 15000W)	0 0,	18000W	



General Typical Short  $0.0096\Omega$  $0.0080\Omega$ Resistance Maximum Short 1050A 1260A Current 0.4 ~ 100V Load ON Voltage Load OFF Voltage 0 ~ 100V Power Consumption 1320VA Dimension(H x W x D) 761mm x 444mm x 763mm HxWxD (Not 657mm x 444mm x 763mm included wheels) Weight 116.5KG 124KG

Temperature\*5 0~40°C Safety & EMC

# PEL-5020C-600-1400, PEL-5024C-600-1680

CE

Model	PEL-5020C-600-14	400	PEL-5024C-600-16	580
Power*1	20KW		24KW	
Current	0 ~ 140A	0 ~ 1400A	0 ~ 168A	0 ~ 1680A
Voltage	0 ~ 600V			
Min. Operating Voltag	e 10V@1400A		10V@1680A	
Protections				
Over Power Protection	` '			
Over Current Protection	, ,			
Over Voltage Protection	` '			
Over Temp Protection	` '			
Constant Current Mod	-			
Range*2	140A	1400A	168A	1680A
Resolution	2.24mA	22.4mA	2.688mA	26.88mA
Accuracy*3	± 0.05% of (Settir	ng + Range)		
Constant Resistance M		_		_
Range	25713.6Ω~	0.42856Ω~	21428 ~	0.357133Ω~
_	0.42856Ω	0.007152Ω	0.357133Ω	0.00596Ω
Resolution	38.8899μS	7.152μΩ	46.6679μS	5.96μΩ
Accuracy	± 0.2% of (Setting	g + Range)		
Constant Voltage Mod				
Range	600V			
Resolution	10mV			
Accuracy	± 0.05% of (Settir	ng + Range)		
Constant Power Mode				
Range	2000W	20000W	2400W	24000W
Resolution	32mW	320mW	38.4mW	384mW
Accuracy	± 0.2% of	± 0.1% of	± 0.2% of	± 0.1% of
·			(Setting + Range)	(Setting + Range)
Constant Voltage Mod			6001	7.0004
Range	600V	1400A	600V	1680A
Resolution	10mV	22.4mA	10mV	26.88mA
Accuracy	± 1.0% of (Setting	g + Kange)		



Constant Voltage Mo	ode + Constant Po	wer Mode		
Range	600V	20000W	600V	24000W
Resolution	10mV	320mW	10mV	384mW
Accuracy	± 1.0% of (Sett	ing + Range)		
Surge Test	,	0 0,		
Surge & Normal cur	rent 0~1400A		0~1680A	
Surge time	10~1000ms			
Surge step	1~5			
MPPT Mode				
Algorithm	P & O			
Load mode	CV			
P&O interval	1000ms~6000	0ms; resolution 10	00ms	
Dynamic Mode				
Timing				
Thigh & Tlow	0.010~9.999 / 99.9	99 / 999.9 / 9999mS	5	
Resolution	0.001 / 0.01 / 0.1			
Accuracy	1μS/10μS/100μS/	1mS + 50ppm		
Slew rate	0.0528A ~ 3.3A/μS	S 0.528A ~ 33A/μS	0.0576A ~ 3.6A/μS	5 0.576A ~ 36A/μS
Resolution	0.0132A/μS	0.132A/μS	0.0144A/μS	0.144A/μS
Accuracy	± (5% of Setting)	±10µS		
Current				
Range	0 ~ 140A	140 ~ 1400A	0 ~ 168A	168 ~ 1680A
Resolution	2.24mA	22.4mA	2.688mA	26.88mA
Measurement				
Voltage Read Back				
Range (5 Digital)	0 ~ 60V	60 ~ 600V	0 ~ 60V	60 ~ 600V
Resolution	1mV	10mV	1mV	10mV
Accuracy	± 0.025% of (Read	ling + Range)		
Current Read Back				
Range (5 Digital)	0 ~ 140A	140 ~ 1400A	0 ~ 168A	168 ~ 1680A
Resolution	2.24mA	22.4mA	2.688mA	26.88mA
Accuracy	± 0.05% of (Read	ding + Range)		
Power Read Back				
Range (5 Digital)	20000W		24000W	
Accuracy*4	± 0.06% of (Read	ding + Range)		
General				
Typical Short	0.0072Ω		0.0060Ω	
Resistance	0.007212		0.000012	
Maximum Short	1400A		1680A	
Current			1000/1	
Load ON Voltage	0.4 ~ 100V			
Load OFF Voltage	0 ~ 100V			
Power Consumption				
Dimension(H x W x	D) 884mm x 444m	m x 763mm		
H x W x D (Not included wheels)	780mm x 444m	m x 763mm		
Weight	140.5KG		155KG	
Temperature*5	0~40°C			
Safety & EMC	CE			



# PEL-5006C-1200-240, PEL-5008C-1200-320

1 LL-3000C-1	200-240, 1 L	L 3000C 120	30 320	
Model	PEL-5006C-120	0-240	PEL-5008C-1200-	320
Power *1	6KW		8KW	
Current	0 ~ 24A	0 ~240A	0 ~ 32A	0 ~ 320A
Voltage	0 ~ 1200V			
Min. Operating Volt	tage 15V@240A		15V@320A	
Protections				
Over Power Protect	ion(OPP) 105%			
Over Current Protec	ction(OCP) 104%			
Over Voltage Protec	ction(OVP) 105%			
Over Temp Protecti	on(OTP) 90°C±5°	C.		
Constant Current M	lode			
Range *2	24A	240A	32A	320A
Resolution	0.384mA	3.84mA	0.512mA	5.12mA
Accuracy *3	± 0.05% of (Sett	ing + Range)		
Constant Resistance	e Mode			
Range	$30K\Omega \sim 5\Omega$	$5\Omega$ ~ $0.0625\Omega$	$22.5\text{K}\Omega~\sim3.75\Omega$	$3.75\Omega{\sim}~0.0469\Omega$
Resolution	3.333μS	$83.334\mu\Omega$	4.444μS	62.5μΩ
Accuracy	± 0.2% of (Setting	ng + Range)		
Constant Voltage M	lode			
Range	1200V			
Resolution	20mV			
Accuracy	± 0.05% of (Sett	ing + Range)		
Constant Power Mo	ode			
Range	600W	6000W	800W	8000W
Resolution	9.6mW	96mW	12.8mW	128mW
Accuracy	± 0.1% of (Set	tting + Range)		
Constant Voltage M	Iode + Constant Cu	rrent Mode		
Range	1200V	240A	1200V	320A
Resolution	20mV	3.84mA	20mV	5.12mA
Accuracy	± 1.0% of (Set	tting + Range)		
Constant Voltage M	lode + Constant Po	wer Mode		
Range	1200V	6000W	1200V	8000W
Resolution	20mV	96mW	20mV	128mW
Accuracy	± 1.0% of (Set	tting + Range)		
Surge Test				
Surge & Normal cu	rrent 0~240A		0~320A	
Surge time	10~1000ms			
Surge step	1~5			
MPPT Mode				
Algorithm	P & O			
Load mode	CV			
P&O interval	1000ms~6000	0ms ; resolution 10	000ms	
Dynamic Mode				
Timing				
Thigh & Tlow	0.010~9.999 / 99	.99 / 999.9 / 9999n	nS	
Resolution	0.001 / 0.01 / 0.1	/ 1mS		



Accuracy Slew rate Resolution Accuracy	$1\mu$ S/10μS/100μS 0.0192A ~ 1.2A/μ 0.0048A/μS ± (5% of Setting)	ιS 0.192A ~ 12A/μS 0.048A/μS	0.0192A ~ 1.2A <sub>/</sub> 0.0048A/μS	/μS 0.192A ~ 12A/μS 0.048A/μS	
Current					
Range	0 ~ 24A	24 ~ 240A	0 ~ 32A	32 ~ 320A	
Resolution	0.384mA	3.84mA	0.512mA	5.12mA	
Measurement					
Voltage Read Back					
Range (5 Digital)	0 ~ 120V	120 ~ 1200V	0 ~ 120V	120 ~ 1200V	
Resolution	2mV	20mV	2mV	20mV	
Accuracy	± 0.025% of (R	eading + Range)			
Current Read Back					
Range (5 Digital)	0 ~ 24A	24 ~ 240A	0 ~ 32A	32 ~ 320A	
Resolution	0.384mA	3.84mA	0.512mA	5.12mA	
Accuracy	± 0.05% of (Re	± 0.05% of (Reading + Range)			
Power Read Back					
Range (5 Digital)	6000W		8000W		
Accuracy*4	± 0.06% of (Re	ading + Range)			
General					
Typical Short Resistance	0.0625Ω		$0.0469\Omega$		
Maximum Short Current	240A		320A		
Load ON Voltage	1 ~ 250V				
Load OFF Voltage	0 ~ 250V				
Power Consumptio	n 510VA		920VA		
Dimension(H x W >	(D) 446mm x 44	4mm x 763mm	572 mm x 444	mm x 763mm	
H x W x D (Not included wheels)	342mm x 44	4mm x 763mm	468mm x 444ı	mm x 763mm	
Weight	62KG		77.5KG		
Temperature*5	0~40°C				
Safety & EMC	CE				

# PEL-5010C-1200-400, PEL-5012C-1200-480

Model	PEL-5010C-1200	PEL-5010C-1200-400		PEL-5012C-1200-480	
Power*1	10KW		12KW		
Current	0 ~ 40A	0 ~ 400A	0 ~ 48A	0 ~ 480A	
Voltage	0 ~ 1200V				
Min. Operating Voltage 15V@400A			15V@480A		
Protections					
Over Power Protection	Over Power Protection(OPP) 105%				
Over Current Protect	ion(OCP) 104%				
Over Voltage Protect	ion(OVP) 105%				
Over Temp Protectio	n(OTP) 90°C±5°0	2			
Constant Current Mode					
Range*2	40A	400A	48A	480A	
Resolution	0.64mA	6.4mA	0.768mA	7.68mA	



Accuracy*3	± 0.05% of (Se	tting + Range)		
Constant Resistanc	,	<i>5 6-1</i>		
Range	18ΚΩ∼ 3Ω	$3\Omega \sim 0.0375\Omega$	15ΚΩ ~ 2.5Ω	2.5Ω~ 0.0313Ω
Resolution	5.5555μS	50μΩ	6.6666µS	41.667μΩ
Accuracy	± 0.2% of (Sett	•	•	•
Constant Voltage M	,	8 8-7		
Range	1200V		1200V	
Resolution	20mV		20mV	
Accuracy	± 0.05% of (S	etting + Range)		
Constant Power Mo	`	0 0,		
Range	1000W	10000W	1200W	12000W
Resolution	16mW	160mW	19.2mW	192mW
Accuracy	± 0.1% of (Se	tting + Range)		
Constant Voltage N	1ode + Constant C	urrent Mode		
Range	1200V	400A	1200V	480A
Resolution	20mV	6.4mA	20mV	7.68mA
Accuracy	± 1.0% of (Se	tting + Range)		
Constant Voltage M	10de + Constant P	ower Mode		
Range	1200V	10000W	1200V	12000W
Resolution	20mV	160mW	20mV	192mW
Accuracy	± 1.0% of (Se	tting + Range)		
Surge Test				
Surge & Normal cu	rrent 0~400A		0~480A	
Surge time	10~1000ms			
Surge step	1~5			
MPPT Mode				
Algorithm	P & O			
Load mode	CV			
P&O interval	1000ms~600	000ms ; resolution 10	000ms	
Dynamic Mode				
Timing				
Thigh & Tlow	0.010~9.999 / 99	.99 / 999.9 / 9999m	S	
Resolution	0.001 / 0.01 / 0.	I / 1mS		
Accuracy	1μS/10μS/100μS	S/1mS + 50ppm		
Slew rate	0.0224A ~ 1.4A/ <sub>1</sub>	uS 0.224A ~ 14A/μS	0.0256A ~ 1.6A/µ	ιS 0.256A ~ 16A/μS
Resolution	0.0056A/μS	0.056A/μS	0.0064A/μS	0.064A/μS
Accuracy	± (5% of Setting	) ±10µS		
Current				
Range	0 ~ 40A	40 ~ 400A	0 ~ 48A	48 ~ 480A
Resolution	0.64mA	6.4mA	0.768mA	7.68mA
Measurement				
Voltage Read Back				
Range (5 Digital)	0 ~ 120V	120 ~ 1200V	0 ~ 120V	120 ~ 1200V
Resolution	2mV	20mV	2mV	20mV
Accuracy	± 0.025% of (R	eading + Range)		
Current Read Back				
Range (5 Digital)	0 ~ 40A	40 ~ 400A	0 ~ 48A	48 ~ 480A
Resolution	0.64mA	6.4mA	0.768mA	7.68mA
Accuracy	± 0.05% of (Re	ading + Range)		



Power Read Back 10000W 12000W Range (5 Digital) Accuracy\*4 ± 0.06% of (Reading + Range) General Typical Short  $0.0375\Omega$ 0.03130 Resistance Maximum Short 400A 480A Current Load ON Voltage 1 ~ 250V Load OFF Voltage  $0 \sim 250V$ 920VA Power Consumption Dimension(H x W x D) 572mm x 444mm x 763mm HxWxD (Not 468mm x 444mm x 763mm included wheels) Weight 84.8KG 92KG 0~40°C Temperature\*5 Safety & EMC CE

## PEL-5015C-1200-600, PEL-5018C-1200-720

Model PEL-5015C-1200-600 PEL-5018C-1200-720 Power\*1 15KW 18KW Current  $0 \sim 600A$ 0 ~ 720A  $0 \sim 60A$  $0 \sim 72A$  $0 \sim 1200V$ Voltage Min. Operating Voltage 15V@600A 15V@720A Protections Over Power Protection (OPP) 105% Over Current Protection (OCP) 104% Over Voltage Protection (OVP) 105% Over Temp Protection(OTP) 90°C±5°C Constant Current Mode 600A Range\*2 60A 72A 720A Resolution 0.96mA 9.6mA 1.152mA 11.52mA Accuracy\*3  $\pm$  0.05% of (Setting + Range) Constant Resistance Mode 10ΚΩ~ 1.666Ω  $12K\Omega \sim 2\Omega$  $2\Omega\sim0.0250\Omega$  $1.666\Omega \sim 0.0209\Omega$ Range Resolution 8.3333uS  $33.334 \mu\Omega$ 10μS  $27.77\mu\Omega$ Accuracy ± 0.2% of (Setting + Range) Constant Voltage Mode Range 1200V Resolution 20mV ± 0.05% of (Setting + Range) Accuracy Constant Power Mode Range 1500W 15000W 1800W 18000W 24mW 240mW 28.8mW 288mW Resolution Accuracy ± 0.1% of (Setting + Range) Constant Voltage Mode + Constant Current Mode Range 1200V 600A 1200V 720A Resolution 20mV 9.6mA 20mV 3.2mA



Accuracy	+ 1.0% of (Se	etting + Range)		
Constant Voltage M	,	<u> </u>		
Range	1200V	15000W	1200V	18000W
Resolution	20mV	240mW	20mV	288mW
Accuracy		etting + Range)	201117	2001111
Surge Test	11.070 01 (36	ttilig + Kalige)		
Surge & Normal cu	rrant 0 600A		0~720A	
Surge time	10~1000ms	_	0~720A	
U	1~5	5		
Surge step MPPT Mode	د~ا			
	P & O			
Algorithm Load mode	CV			
		00		
P&O interval	1000ms~6000	00ms ; resolution 1000	ms	
Dynamic Mode				
Timing	0.010.0000.0	00.00.1000.0.10000	-	
Thigh & Tlow		99.99 / 999.9 / 9999ms	5	
Resolution	0.001 / 0.01 / 0	•		
Accuracy		μS/1mS + 50ppm		
Slew rate		λ/μS 0.288Α ~ 18Α/μS	0.032A ~ 2A/μS	0.32A ~ 20A/μS
Resolution	0.0072A/μS	0.072A/μS	0.008A/μS	0.08Α/μS
Accuracy	± (5% of Settir	ng) ±10µS		
Current				
Range	0 ~ 60A	60 ~ 600A	0 ~ 72A	72 ~ 720A
Resolution	0.96mA	9.6mA	1.152mA	11.52mA
Measurement				
Voltage Read Back				
Range (5 Digital)	0 ~ 120V	120 ~ 1200V	0 ~ 120V	120 ~ 1200V
Resolution	2mV	20mV	2mV	20mV
Accuracy	± 0.025% of (Re	eading + Range)		
Current Read Back				
Range (5 Digital)	0 ~ 60A	60 ~ 600A	0 ~ 72A	72 ~ 720A
Resolution	0.96mA	9.6mA	1.152mA	11.52mA
Accuracy	$\pm 0.05\%$ of (R	leading + Range)		
Power Read Back				
Range (5 Digital)	15000W		18000W	
Accuracy*4	± 0.06% of (R	teading + Range)		
General				
Typical Short	0.00500		0.00000	
Resistance	0.0250Ω		0.0209Ω	
Maximum Short	6004		7004	
Current	600A		720A	
Load ON Voltage	1 ~ 250V			
Load OFF Voltage	0 ~ 250V			
Power Consumptio				
Dimension(H x W >		44mm x 763mm		
H x W x D (Not	•	44mm x 763mm		
included wheels)		/ 03		
Weight	116.5KG		124KG	
Temperature*5	0~40°C			



Safety & EMC

PEL-5020C-1200-800, PEL-5024C-1200-960

CE

 Model
 PEL-5020C-1200-800
 PEL-5024C-1200-960

 Power\*1
 20KW
 24KW

Current  $0 \sim 80A$   $0 \sim 800A$   $0 \sim 96A$   $0 \sim 960A$ 

Voltage  $0 \sim 1200V$ 

Min. Operating Voltage 15V@800A 15V@960A

Protections

Over Power Protection (OPP) 105%
Over Current Protection (OCP) 104%
Over Voltage Protection (OVP) 105%
Over Temp Protection (OTP) 90°C±5°C

Constant Current Mode

Range\*2 80A 800A 96A 960A Resolution 1.28mA 12.8mA 1.536mA 15.36mA

Accuracy\*3  $\pm 0.05\%$  of (Setting + Range)

Constant Resistance Mode

 Range
  $9KΩ \sim 1.5Ω$   $1.5Ω \sim 0.0187Ω$   $7.5KΩ \sim 1.25Ω$   $1.25Ω \sim 0.0156Ω$  

 Resolution
 11.111μS 25μΩ 13.333μS 20.834μΩ

Accuracy  $\pm 0.2\%$  of (Setting + Range)

Constant Voltage Mode

 Range
 1200V
 1200V

 Resolution
 20mV
 20mV

Accuracy  $\pm 0.05\%$  of (Setting + Range)

Constant Power Mode

 Range
 2000W
 2000W
 2400W
 2400W

 Resolution
 32mW
 320mW
 38.4mW
 384mW

 Accuracy
 ± 0.1% of (Setting + Range)

Constant Voltage Mode + Constant Current Mode

 Range
 1200V
 800A
 1200V
 960A

 Resolution
 20mV
 3.84mA
 20mV
 15.36mA

Accuracy  $\pm 1.0\%$  of (Setting + Range)

 Constant Voltage Mode + Constant Power Mode

 Range
 1200V
 20000W
 1200V
 24000W

 Resolution
 20mV
 320mW
 20mV
 384mW

Accuracy  $\pm 1.0\%$  of (Setting + Range)

Surge Test

Surge & Normal current 0~800A 0~960A

Surge time  $10\sim1000$ ms Surge step  $1\sim5$ 

MPPT Mode

Algorithm P & O Load mode CV

P&O interval 1000ms~60000ms; resolution 1000ms

Dynamic Mode

**Timing** 

Thigh & Tlow 0.010~9.999 / 99.99 / 999.9 / 9999mS



Accuracy Slew rate	0.001 / 0.01 / 0.1 / 1mS 1μS/10μS/100μS/1mS + 50ppm 0.0352A ~ 2.2A/μS 0.352A ~ 22A/μS 0.0384A ~ 2.4A/μS 0.384A ~ 24A/μS				
	/ ·	0.088A/μS	0.0096A/μS	0.096A/μS	
Accuracy Current	± (5% of Setting) ±	: (5% of Setting) ±10µS			
	0 ~ 80A	80 ~ 800A	0 ~ 96A	96 ~ 960A	
Range Resolution	0 ~ 80A 1.28mA	80 ~ 800A 12.8mA	0 ~ 96A 1.536mA	15.36mA	
Measurement	1.28ffIA	12.8ITIA	Alliocc.1	13.30mA	
Voltage Read Back					
Range (5 Digital)	0 ~ 120V	120 ~ 1200V	0 ~ 120V	120 ~ 1200V	
Resolution	0 ~ 120 V 2mV	20mV	0 ~ 120 V 2mV	20mV	
Accuracy	± 0.025% of (Readi		ZIIIV	201114	
Current Read Back	± 0.02570 01 (Nead)	ing i Kange)			
Range (5 Digital)	0 ~ 80A	80 ~ 800A	0 ~ 96A	96 ~ 960A	
Resolution	1.28mA	12.8mA	1.536mA	15.36mA	
Accuracy	± 0.05% of (Reading				
Power Read Back	(	.6			
Range (5 Digital)	20000W		24000W		
Accuracy*4	± 0.06% of (Readin	ıg + Range)			
General	,	0 0,			
Typical Short Resistan	ce 0.0188Ω		0.0157Ω		
Maximum Short	800A		0604		
Current	800A		960A		
Load ON Voltage	1 ~ 250V				
Load OFF Voltage	0 ~ 250V				
Power Consumption	1700VA	1700VA			
Dimension (H x W x D	) 884mm x 444mn	n x 763mm			
H x W x D (Not	780mm x 444mn	762			
included wheels)	/80mm x 444mm	1 x /b3ffiffi			
Weight	140.5KG		155KG		
Temperature*5	0~40°C				
Safety & EMC	CE				

<sup>\*1</sup> The power rating specifications at ambient temperature = 25 °C

 $<sup>\</sup>ensuremath{^{*2}}$  The range is automatically or forcing to range II only in CC mode

<sup>\*3</sup> If the operating current is below range 0.1%, the accuracy specification is 0.1% F.S.

<sup>\*4</sup> Power F.S. = Vrange F.S. x Irange F.S.

<sup>\*5</sup> Operating temperature range is 0~40°C, All specifications apply for 25°C±5°C, Except as noted



# Certificate Of Compliance

We

#### GOOD WILL INSTRUMENT CO., LTD.

declare that the CE marking mentioned product

satisfies all the technical relations application to the product within the scope of council:

Directive: EMC; LVD; WEEE; RoHS

The product is in conformity with the following standards or other normative documents:

normative documents.				
⊚ EMC				
EN 61326-1	Electrical equipment for measurement, control and laboratory use — EMC requirements			
Conducted & Radiated EN 55011 / EN 5503		Electrical Fast Transients EN 61000-4-4		
Current Harmonics EN 61000-3-2 / EN 6	51000-3-12	Surge Immunity EN 61000-4-5		
Voltage Fluctuations EN 61000-3-3 / EN 61000-3-11		Conducted Susceptibility EN 61000-4-6		
Electrostatic Discharg EN 61000-4-2	e	Power Frequency Magnetic Field EN 61000-4-8		
Radiated Immunity EN 61000-4-3		Voltage Dip/ Interruption EN 61000-4-11 / EN 61000-4-34		
© Safety				
EN 61010-1 :		Safety requirements for electrical equipment for measurement, control, and laboratory use - Part 1: General requirements		

#### GOODWILL INSTRUMENT CO., LTD.

No. 7-1, Jhongsing Road, Tucheng District, New Taipei City 236, Taiwan

Tel: +886-2-2268-0389 Fax: +886-2-2268-0639

GOODWILL INSTRUMENT (SUZHOU) CO., LTD.

No. 521, Zhujiang Road, Snd, Suzhou Jiangsu 215011, China Tel: <u>+86-512-6661-7177</u> Fax: <u>+86-512-6661-7277</u>

GOODWILL INSTRUMENT EURO B.V.

De Run 5427A, 5504DG Veldhoven, The Netherlands
Tel: +31-(0)40-2557790
Fax: +31-(0)40-2541194
Empile color@gwy.instele

Email: sales@gw-instek.eu

# **GPIB** programming Example

```
C Example Program
/* Link this program with appropriate *cib*.obj. */
/* This application program is written in TURBO C 2.0 for the IBM
PC-AT compatible. The National Instruments Cooperation (NIC)
Model PC-2A board provides the interface between the PC-AT and
a PRODIGIT MPAL ELECTRONIC LOAD. The appropriate
*cib*.obj file is required in each program to properly link the NIC
board to C LANGUAGE, and include the <decl.h.> HEADER FILE
to C LANGUAGE. */
#include <stdio.h>
#include <dos.h>
#include <math.h>
#include "decl.h"
                       /* NI GPIB CARD HEADER FILE */
main()
 char ouster[20],rdbuf[15],spec[10];
 int i,ch,load;
/* Assign unique identifier to the device "dev5" and store in
variable load. check for error. ibfind error = negative value
returned. */
 if((load = ibfind("dev5")) < 0) /* Device variable name is load
*/
                               /* GPIB address is 5 */
    printf("\r*** INTERFACE ERROR! ***\a\n");
    printf("\rnError routine to notify that ibfind failed.\n");
    printf("\r\nCheck software configuration.\n");
    exit(1);
/* Clear the device */
 if((ibclr(load)) & ERR);
```



```
printf("INTERFACE ERROR!\a");
    exit (1);
 clrscr();
/* Clear load error register */
   outstr=chan[0];
   ibwrt(load,outstr,6);
   ibwrt(load, "CLR", 3);
   }
 ibwrt(load,"NAME?",5);
                                          /* Get the PEL-5000C
series load specification */
                                          /* Clear rdbuf string
 strset(rdbuf, '\0');
buffer */
 strset(spec, '\ 0');
                                          /* Clear spec string buffer
 ibrd(load,spec,20);
 if (spec[3] == '9')
   printf("\n PEL-5000C series specification error !");
/* Set the channel 1, preset off, current sink 1.0 amps and load on
commands to the load. */
 ibwrt(load, "chan 1; pres off; curr:low 0.0; curr:high 1.0; load on ",43);
 ibwrt(load, "meas:curr?", 10);
/* Get the load actially sink current from the load */
 ibrd(load,rdbuf,20);
/* go to local. */
 ibloc(load);
}
```

# BASICA Example Program

LOAD DECL.BAS using BASICA MERGE command.

100 REM You must merge this code with DECL.BAS



105 REM

110 REM Assign a unique identifier to the device "dev5" and store it in variable load%.

**125 REM** 

130 udname\$ = "dev5"

140 CALL ibfind (udname\$,load%)

145 REM

150 REM Check for error on ibfind call

155 REM

160 IF load% < 0 THEN GOTO 2000

165 REM

170 REM Clear the device

175 REM

180 CALL ibclr (load%)

185 REM

190 REM Get the PEL-5012C-600-840 load specification

195 REM

200 wrt\$ = "NAME?" : CALL ibwrt(load%,wrt\$)

rd = space (20) : CALL ibrd (load%,rd\$)

215 REM

220 REM Set the preset off, current sink 1.0 amps and load on commands to the load.

**225 REM** 

230 wrt\$ = "pres off;curr:low 0.0;curr:high 1.0;load on"

240 CALL ibwrt(load%,wrt\$)

**245 REM** 

250 REM Get the load actially sink current from the load

255 REM

260 wrt\$ = "meas:curr?" : CALL ibwrt(load%,wrt\$)

rd = space (20) : CALL ibrd(load%, rd)

275 REM



280 REM Go to local

285 REM

290 CALL ibloc(load%)

2000 REM Error routine to notify that ibfind failed.

2010 REM Check software configuration.

2020 PRINT "ibfind error!": STOP

# PEL-5000C series USB Instruction

## Background

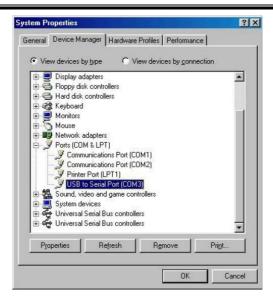
1. Install the USB DRIVER select USB\SETUP\PL-2303 Driver Installer.exe

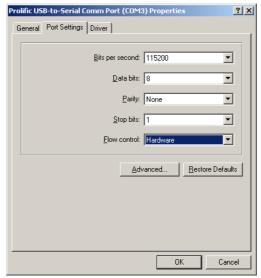




 After the installation, connect the PEL-5000C series and PC with USB. Then select the item USB to Serial Port (COM3), set the BAUD-RATE and Flow control to 115200bps and Hardware to control PEL-5000C series with COM3.







# PEL-5000C series Auto, Sequence function provide EDIT, ENTER, EXIT, TEST and STORE 5 keys operation

#### Edit mode

- 1. Set mode, Range, current level ··· Load Setting an, Load ON.
- Press STORE key to store the load setting in memory STATE
- 3. Repeat 1~2, for the sequence load setting.
- 4. Press Shift + SEQ. key of PEL-5000C Series front panel.
- 5. Press up/down key to select Edit Mode.
- 6. Press 1~9 number key program number.
- Press STATE up/down key to select memory state.
- 8. Press ENTER to next step.
- 9. Repeat 6~8 to edit Step of sequence
- 10. Press SAVE to confirm the step
- 11. LCD shows "rept" to setting repeat count.
- Press up/down key to set repeat count of sequence loop.
- 13. Press ENTER to confirm the sequence edit.

#### Test mode

- 1. Press Shift + SEQ. key of PEL-5000C series front panel.
- 3. Press up/down key to select Test Mode.
- 4. Press 1~9 number to select sequence number
- 5. Press ENTER to execution the sequence
- 6. The LCD shows "PASS" or "FAIL" after testing.

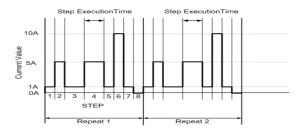


#### **AUTO SEQUENCE:**

AUTO SEQUENCE SET COMMAND	NOTE	RETURN
FILE {SP} {n}{ ;   NL}	n=1~9	1~9
STEP {SP} {n} { ;   NL}	n=1~16	1~16
TOTSTEP {SP} {n}{;   NL}	Total step n=1~16	1~16
SB {SP} {m} { ;   NL}	m=1~150 m:STATE	
TIME {SP} {NR2} {;   NL}	100~9999(ms)	100~9999(ms)
SAVE {;   NL}	Save "File n" data	
REPEAT {SP} {n} {;   NL}	n=0~9999	0~9999
RUN {SP} {F} {n} {;   NL}	N=1~9	AUTO REPLY "PASS" or "FAIL:XX" (XX=NG STEP)

Example Sequence In this example, we will create a program based on following Figure.

The program repeats steps 1 to 8 two times. After repeating the sequence two times, the load is turned off and the sequence ends.



Sequence Number	Step Number	Current Value	Execution Time(T1+T2)
3	1	1A	200mS
3	2	5A	200mS
3	3	1A	400mS



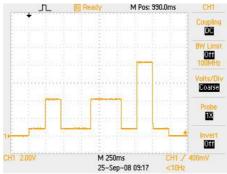
3	4	5A	400mS
3	5	1A	200mS
3	6	10A	200mS
3	7	1A	200mS
3	8	0A	200mS

## Example Sequence

- Setting the Load current level and store to state 1~8
- Set the operation mode Press the mode key to CC mode.
- 3. Set the range Press RANGE key to force range 2
- 4. Press Load ON
- 5. Set the current value as step 1~8 and store to memory state 1~8
- 6. Press EDIT key of PEL-5000C series mainframe
- 7. Press up/down key to select Edit Mode
- 8. Press sequence number 3 to edit the sequence.
- 9. Press up/down key to memory state 1
- 10. Press ENTER key to confirm the sequence memory
- 11. Press up/down key to setting execution time
- 12. Press ENTER key to confirm the sequence step
- 13. Repeat 8~12 to setting step 1~8
- 14. Press SAVE key to confirm step 1~8
- 15. Press up/down key to 1 to repeat one times.
- 16. Press ENTER to confirm the repeat count.



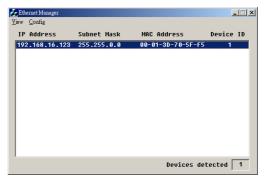




## PEL-5000C series LAN Instruction

## Background

- 1. Connecting AC power and the network line to the PEL-5000C series mainframe, connect the other Side of the network line to the HUB.
- Run the ETM.EXE which bellows the path of the LAN on the CDROM drive, it will show as fig below. If not, please press F5 to search again, or check the first step was succeed or not.



3. It will be shown the installation which has been searched on the screen , click it and select the Set IP Address bellows Config:



- 4. Set a useful IP Address and Subnet Mask.
- It will be shown the Setup Device as the following figure if all steps was corrected to be run.





- 6. Insert the numbers as the following : IP Address: as recommended according to your network
- A. Subnet Mask: as recommended according to your network
- B. Gateway Address: as recommended according to your network
- C. Network link speed: Auto
- D. DHCP client: Enable
- E. Socket port of HTTP setup: 80
- F. Socket port of serial I/O: 4001, TCP Server
- G. Socket port of digital I/O: 5001, TCP Server
- H. Destination IP address / socket port (TCP client and UDP) Connection: Auto
- TCP socket inactive timeout(minutes): Set the network disconnection after N minutes, set 0 minutes will work forever.
- J. Serial I/O settings (baud rate, parity, data, bits, stop bits): 115200, N, 8, 1
- K. Interface of serial I/O: RS 232 (RTS/CTS)



L. Packet mode of serial input: Disable

M. Device ID: 5

N. Report device ID when connected: Auto

O. Setup password: Not required